

Learning Curves in Gaussian Process Regression

April 17, 2024

Introduction to GP

- Bayesian Linear Regression: Model $y|X, w \sim \mathcal{N}(Xw, \sigma_n^2 I_n)$ and prior $w \sim \mathcal{N}(0, \Sigma_p)$. Here $X \in \mathbb{R}^{p \times n}$ is the data matrix.

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- Posterior becomes

$$p(w|y, X) \propto p(y|X, w)p(w) = \mathcal{N}(\sigma_n^{-2} A^{-1} Xy, A^{-1})$$

where $A = \sigma_n^{-2} X X^T + \Sigma_p^{-1} \in \mathbb{R}^{p \times p}$.

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- Predictive distribution at new x ...

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$$p(f(x)|x, X, y) = \mathcal{N}(\sigma_n^{-2} x^T A^{-1} Xy, x^T A^{-1} x)$$

- Can directly be kernelized with Φ replacing X .

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- A bit more mathematically sound: We define $f \sim GP(\mu, k)$ as a Gaussian process on \mathbb{R}^d if for all datasets $X = \{x_1, \dots, x_n\}$, we get

$$f(X) \sim \mathcal{N}(\mu(x_i), k(x_i, x_j))$$

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- Given data X with observations y , and a new x , we have

$$f(x)|X, y, x \sim \mathcal{N}(\bar{f}(x), \sigma^2(f(x)))$$

where

$$\bar{f}(x) = k(x, X) (K + \sigma_n^2 I_n)^{-1} y$$

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- It's kernel regression with uncertainty estimation.

Generalization Error for GP

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$$E^{gen}(X) = \int k_0(x, x) dp(x) - 2 \text{Trace} \left(K_{1, \sigma_1^2}^{-1} \int k_0(X, x) k_1(x, X) dp(x) \right) + \\ \text{Trace} \left(K_{1, \sigma_1^2}^{-1} K_{0, \sigma_0^2} K_{1, \sigma_1^2}^{-1} \int k_1(X, x) k_0(x, X) dp(x) \right)$$

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- In the well-specified case

$$E^{gen}(X) = \int k_0(x, x) dp(x) - \text{Trace} \left(K_{0, \sigma_0^2}^{-1} \int k_0(X, x) k_0(x, X) dp(x) \right)$$

Generalization Error for GP

- Mercer's Theorem: $k(x, x') = \sum_i \lambda_i \phi_i(x) \phi_i(x')$. This gives

$$E^{gen}(X) = \text{Trace} \left(\left(\Lambda + \sigma^{-2} \Phi \Phi^T \right)^{-1} \right)$$

here ϕ_i are L^2 orthonormal, i.e. $\int \phi_i(x) \phi_j(x) d\rho(x) = \delta_{ij}$ for all i, j .

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- Using $\mathbb{E}[\Phi \Phi^T] = nI$ we get the simple approximation

$$E^{gen} \approx \text{Trace} \left(\left(\Lambda + \sigma^{-2} nI \right)^{-1} \right) = \sum_i \frac{\lambda_i \sigma^2}{\sigma^2 + n\lambda_i}$$

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- This is a lower bound on E^{gen} .

Sollich's 1st Approximation

- Let's see how new data affects $G(n) := (\Lambda + \sigma^{-2}\Phi\Phi^T)^{-1}$. We have

$$G(n+1) := (\Lambda + \sigma^{-2}\Phi\Phi^T + \sigma^{-2}\phi\phi^T)^{-1} = (G^{-1}(n) + \sigma^{-2}\phi\phi^T)^{-1}$$

Woodbury's formula for rank 1 updates of matrix inverses gives...

$$G(n+1) - G(n) = -\frac{G(n)\phi\phi^T G(n)}{\sigma^2 + \phi^T G(n)\phi}$$

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- We now average over the new point ϕ (note $\mathbb{E}[\phi\phi^T] = I$) and treat n as continuous. We then average this **informally** over X by (i) taking expectations over numerator and denominator separately and (ii) assuming $\mathbb{E}[G(n)^2] = \mathbb{E}[G(n)]^2 =: \bar{G}(n)^2$

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- Finally, with n' satisfying $n' + \log \text{Trace}(I + n'\sigma^{-2}\Lambda) = n$, we have

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- Note that $n' < n$, so this is indeed a larger bound than the naive approximation from before.