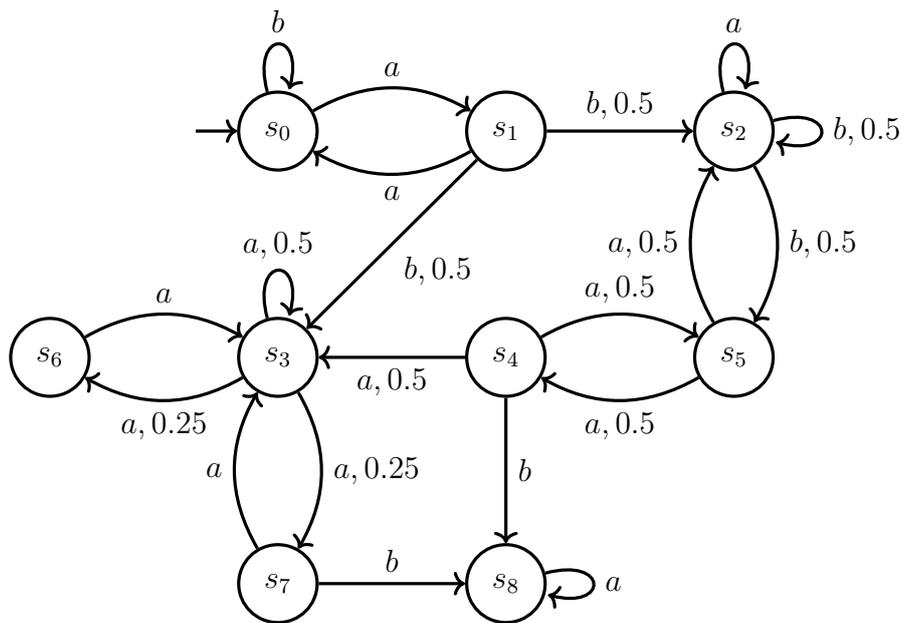


## Quantitative Verification – Exercise sheet 11

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### Exercise 11.1

Compute the MECs (both states and actions) of the following MDP.



### Exercise 11.2

On Figure 1, compute  $R_{=?}[C \leq 4]$  and check whether  $R_{\geq 1}[C \leq 2]$  holds. Also, compute  $R_{=?}[I = 4]$ .

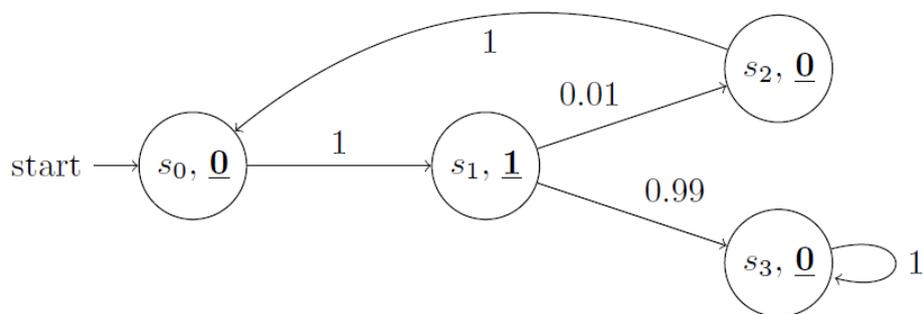


Figure 1: State rewards are bold-faced and underlined.

**Exercise 11.3**

The *instantaneous reward* of a path at time  $t$  associates with a path, the reward in the state of that path when exactly  $t$  time units have elapsed. In general, *instantaneous reward* refers to the expected reward of a model at a particular instant in time. See lecture slides for more details. Are memoryless schedulers sufficient to obtain optimal instantaneous rewards? If yes, give a proof sketch. If no, give a counterexample.

**Exercise 11.4**

We have seen expected step-bounded reward and expected long-run average reward. How can you rephrase (bounded) reachability as an instance of these problems?

### Solution 11.1

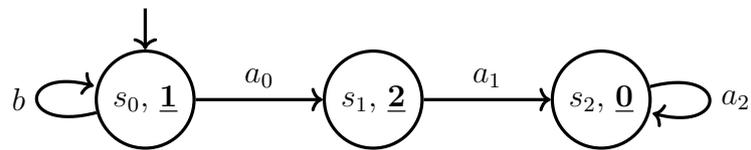
MECs:

- $(\{s_0, s_1\}, \{(s_0, a), (s_0, b), (s_1, a)\})$
- $(\{s_2\}, \{(s_2, a)\})$
- $(\{s_3, s_6, s_7\}, \{(s_3, a), (s_6, a), (s_7, a)\})$
- $(\{s_8\}, \{(s_8, a)\})$

### Solution 11.2

$R=1$  for  $C \leq 4$ , and  $R_{\geq 1}[C \leq 2]$  holds because  $R=1$  for  $C \leq 2$ .  $R=0.01$  for  $I = 4$ .

### Solution 11.3



MDP which shows that memoryless schedulers do not exist for instantaneous rewards. (e.g. take  $b$  twice and  $a_0$  to maximize instantaneous reward in 3 steps)

### Solution 11.4

- Bounded reachability: Make target states absorbing, i.e. remove all outgoing transitions and add a self-loop, set their reward to 1 and all other rewards to 0.
- Unbounded reachability: Cannot be phrased easily as bounded reward problem. For unbounded, apply the above idea.