Exercise 7.1
Consider the transition system $TS$ depicted below. Show that the ample set conditions $(C0)-(C3)$ do not allow for any state reduction, although there is a smaller subsystem $\hat{TS}$ that is stutter equivalent to $TS$.

Exercise 7.2
Consider the following Promela model

```promela
byte g;

active proctype m() {
    byte x;
    m0: x ++;
    m1: x ++;
    m2: g = x;
}

active proctype n() {
    byte y;
    n0: y ++;
    n1: y ++;
    n2: atomic { (g > 0) -> g = g - y };
}

active proctype p() {
    p0: atomic { (g > 0) -> g -- };
}
```

and the following properties:

a) The value of $g$ will eventually become one.
b) The process n cannot finish before the process m reaches m1.

For each property, define a labeled Kripke structure with actions extracted from program statements. Determine the independence relation and the invisibility set, and construct a reduced Kripke structure using the ample sets method.

**Exercise 7.3**
Which of the following equivalences for $CTL^*$ are correct? Provide a proof or a counterexample.

(a) $AXAG \phi \equiv AXG \phi$

(b) $EXEG \phi \equiv EXG \phi$

(c) $A(\phi \land \psi) \equiv A\phi \land A\psi$

(d) $E(\phi \land \psi) \equiv E\phi \land E\psi$
Solution 7.1
Dependent set: \( \{ (\alpha, \gamma_0), (\gamma_0, \alpha), (\beta, \delta_0), (\delta_0, \alpha), (\gamma_0, \delta_0), (\delta_0, \gamma_0), (\beta, \gamma), (\gamma, \beta), (\alpha, \delta), (\delta, \alpha) \} \)

Invisible set: \( \{ \alpha, \beta, \gamma_0, \delta_0 \} \)

We shall show that it's not possible to reduce any actions for the initial state, similar arguments can be given for the other states.

Since all actions are invisible, condition (C2) does not impose any restrictions. But since \( \gamma_0 \) and \( \delta_0 \) are independent, (C1) says that either both of them would be the \textit{red()} set or neither of them. Similarly, either both \( \alpha \) and \( \gamma_0 \) would be in the \textit{red()} set or neither of them. This combined with \( C0 \) conditions gives us that all three of them would have to be included in the \textit{red()} set.

Smaller subsystem that is stutter equivalent to the TS:

![Diagram](https://example.com/diagram.png)

Solution 7.2
We define actions \( a_0, a_1, a_2, b_0, b_1, b_2, \) and \( c_0 \) for statements in \( m, n, \) and \( p, \) respectively. Each state in the Kripke structure is a tuple of program locations and a valuation of \( g. \) Notice that it is not necessary to explicitly models valuations of \( x \) and \( y \) as they are implicitly defined by program locations of \( m \) and \( n. \)

For each property, we construct a labeled Kripke structure \( K = (S, A, \to, r, AP, \nu), \) where and \( S, A, \to, \) and \( r \) are as follows:
The independence relation $I = (A \times A \setminus Id) \setminus \{(b_2, c_0), (c_0, b_2)\}$.

Next, we consider each property individually.

a) The corresponding LTL formula is $F(g == 1)$, where $AP_a = \{g == 1\}$. So, $\nu_a(s) = \{g == 1\}$ iff the valuation of $g$ in the state $s$ is 1, and as a result, $U = A \setminus \{b_2, c_0\}$. A possible reduced Kripke structure is as follows:
b) The corresponding LTL formula is \( m_1 \mathbf{R} \neg n_3 \), where \( AP_b = \{ m_1, n_3 \} \) (resp. \( \{ n_3 \} \)) iff the \( s \) contains \( m_1 \) (resp. \( \{ n_3 \} \)). As a result, \( U = A \setminus \{ a_0, a_1, b_2 \} \). A possible reduced Kripke structure is as follows:

![Kripke Structure Diagram]

Solution 7.3

Note that the solutions discussed during the tutorial for this exercise are wrong.

(a) Yes, if a tree \( T \) satisfies \( \mathbf{AXAG} \phi \) then, every path in the tree is of the form \( \pi = a_1, a_2, a_3 \ldots \) where everything from \( a_2 \) onwards satisfies \( \phi \) which is equivalent to saying that \( \pi \) also satisfies the formula \( \mathbf{XG} \phi \). Now, since all paths satisfies \( \mathbf{XG} \phi \), then \( T \) satisfies \( \mathbf{AXG} \phi \).

(b) Yes, if a tree \( T \) satisfies \( \mathbf{EXEG} \phi \) then there exists a path in the tree \( a_1, a_2, a_3 \ldots \) such that starting from \( a_2 \) there exist another path, let’s say \( a_2, a'_3, a'_4 \ldots \) on which \( \phi \) is true everywhere. This means that the path \( a_1, a_2, a'_3, a'_4 \ldots \) satisfies the formula \( \mathbf{XG} \phi \) which means that \( T \) satisfies \( \mathbf{EXG} \phi \).

(c) Yes, since \( \phi \) and \( \psi \) both are true in all paths of a tree satisfying the formula, this means that \( \phi \) is true in all paths of the tree and \( \psi \) is also true in all paths of the tree.
(d) No, consider this tree which satisfies $\text{EX}p \land \text{EX}q$ but does not satisfy $\text{E}(Xp \land Xq)$: