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Model Checking – Exercise sheet 5

Exercise 5.1

Consider the following NBA with the acceptance set $F = \{s_1, s_6\}$. Apply the nested depth-first search approach to verify that $L(A) \neq \phi$.



Exercise 5.2

Consider the Promela model below which addresses the mutual exclusion problem by using a semaphore s. When s is false, a process may enter its critical section and set s to true. The semaphore is reset to false when the process leaves its critical section.

```
bool s;
1
\mathbf{2}
               active [2] proctype m() {
3
                           idle:
4
                           skip;
5
                           wait:
6
                           atomic { (!s) \rightarrow s = true; }
\overline{7}
                           cs:
8
                           s = false;
9
                           goto idle;
10
               }
11
```

We consider the following properties:

- a) Both processes cannot enter the critical section at the same time.
- b) Whenever a process waits, it will eventually enter the critical section.

Follow step-by-step the outline given below to model check the properties:

- (i) Construct a state transition system from the model.
- (ii) Write down an atomic proposition AP and an LTL formula ϕ for each properties.
- (iii) Construct a Büchi automaton $\mathcal{B}_{\neg\phi}$ for the negation of the formula ϕ .
- (iv) Construct from the transition system the Kripke structure \mathcal{K} and the Büchi automaton $\mathcal{B}_{\mathcal{K}}$ over AP.
- (v) Construct the intersection Büchi automaton \mathcal{B} for $\mathcal{B}_{\mathcal{K}}$ and $\mathcal{B}_{\neg\phi}$.
- (vi) Run the emptiness algorithm in the lecture to check whether $\mathcal{L}(\mathcal{B}) = \emptyset$:
 - If $\mathcal{L}(\mathcal{B}) = \emptyset$, the property holds, i.e. $\mathcal{K} \models \phi$.
 - If L(B) ≠ Ø, the property does not hold, i.e. K ⊭ φ.
 In this case, find a counterexample run that violates the property. How to obtain a counterexample in general?
- (vii) Use Spin to confirm your results.

First do step (i), and then steps (ii)-(vii) separately for each property (a) and (b). Write down all intermediary results.

Solution 5.1

Let's assume that the algorithm selects the next state from top-to-bottom and left-to-right. It first finds the SCC $\{s_2, s_3\}$ which does not have any accepting state. Then it goes to state s_4 and later finds the SCC $\{s_4, s_5, s_6\}$ when it reaches s_6 . Since s_6 is an accepting state, the algorithm terminates and reports that the language of the NBA is non-empty.

Solution 5.2

(i) $\mathcal{T} = (S, \rightarrow, r)$, where $S = \{i_0, w_0, cs_0\} \times \{i_1, w_1, cs_1\} \times \{t, f\}$ for modeling three locations in **m** and two possible values of **s**.



- (ii) $\phi_a = \neg \mathbf{F}(cs_0 \wedge cs_1)$, where $AP_a = \{cs_0, cs_1\}$ and $\phi_b = \mathbf{G}(w_0 \rightarrow \mathbf{F}cs_0)$, where $AP_b = \{w_0, cs_0\}$
- (iii) $\neg \phi_a = \mathbf{F}(cs_1 \wedge cs_2)$. So, $\mathcal{B}_{\neg \phi_a}$ can be constructed as follows:



 $\neg \phi_b = \mathbf{F}(w_0 \wedge \mathbf{G} \neg cs_0)$. So, $\mathcal{B}_{\neg \phi_b}$ can be constructed as follows:



(iv) Let rename the states to $S = \{s_0, \ldots, s_7\}.$



$$\mathcal{K}_{a} = (S, \to, r, AP_{a}, \nu_{a}), \text{ where } \nu_{a}(s) = \begin{cases} \{cs_{0}\}, & \text{if } s \in \{s_{3}, s_{6}\} \\ \{cs_{1}\}, & \text{if } s \in \{s_{5}, s_{7}\} \\ \emptyset, & \text{otherwise} \end{cases}$$
$$\mathcal{K}_{b} = (S, \to, r, AP_{b}, \nu_{b}), \text{ where } \nu_{b}(s) = \begin{cases} \{w_{0}\}, & \text{if } s \in \{s_{1}, s_{4}, s_{7}\} \\ \{cs_{0}\}, & \text{if } s \in \{s_{3}, s_{6}\} \\ \emptyset, & \text{otherwise} \end{cases}$$

The Büchi automaton $\mathcal{B}_{\mathcal{K}_a} = (2^{AP_a}, S, r, \Delta_{K_a}, S)$, where $\Delta_{K_a} = \{(s, \nu_a(s), t) \mid s \to t\}$:



The Büchi automaton $\mathcal{B}_{\mathcal{K}_b} = (2^{AP_b}, S, r, \Delta_{K_b}, S)$, where $\Delta_{K_b} = \{(s, \nu_b(s), t) \mid s \to t\}$:



(v) $\mathcal{B}_a = (2^{AP_a}, S \times \{q_0, q_1\}, (s_0, q_0), \Delta_a, S \times \{q_1\})$



$$\mathcal{B}_b = (2^{AP_b}, S \times \{q_0, q_1\}, (s_0, q_0), \Delta_b, S \times \{q_1\})$$



(vi) For \mathcal{B}_a , the algorithm terminates without reporting a counterexample. By the time the algorithm terminates, it finds out that every state forms an SCC, but without an accepting state.

For \mathcal{B}_b , assuming that the algorithm always searches the automaton above top-tobottom and left-to-right, then it first finds the SCC $\{(s_0, q_0), (s_1, q_0), (s_3, q_0)\}$ when it reaches (s_3, q_0) . Later, it finds the SCC $\{(s_6, q_0), (s_2, q_0), (s_4, q_0)\}$ when it reaches (s_4, q_0) . Finally, it reaches (s_4, q_1) and finds out that its successor (s_7, q_1) is still active. Since (s_4, q_1) is an accepting state, the algorithm stops. Notice that the last SCC it discovers is $\{(s_7, q_1), (s_1, q_1), (s_4, q_1)\}$ with (s_7, q_1) as the root.

The counterexample run in \mathcal{B}_b found by the algorithm is

 $(s_0, q_0), (s_1, q_0), (s_3, q_0), (s_6, q_0), (s_2, q_0), (s_4, q_0), ((s_7, q_1), (s_1, q_1), (s_4, q_1))^{\omega}$

The corresponding path in \mathcal{K}_b can be obtained by projecting the run on the first component. The counterexample valuation sequence is as follows:

$$\{\}\{w_0\}\{cs_0\}\{cs_0\}\{\}\{w_0\}\{w_0\}\{w_0\}\{w_0\}\}^{\omega}$$

(vii) Check the formulas: <>(m[0]@cs && m[1]@cs) and [](m@wait -> (<> m@cs))