

How good is your embedded design, if at all?



Holger Hermanns

dependable systems and software

Saarland University

Saarbrücken, Germany



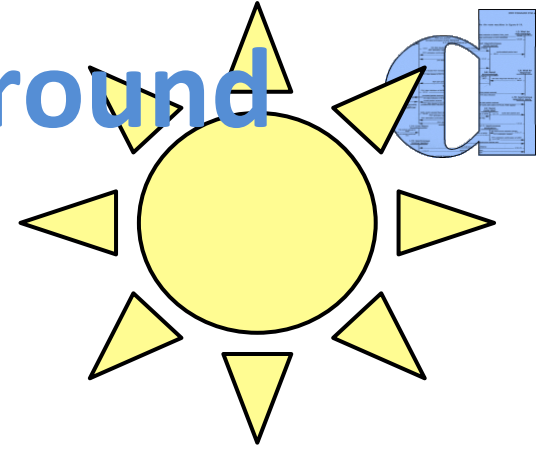


The German Energy Turn-Around

Renewables are on the rise!

⇒ In Germany ... and elsewhere

⇒ On residential rooftops.

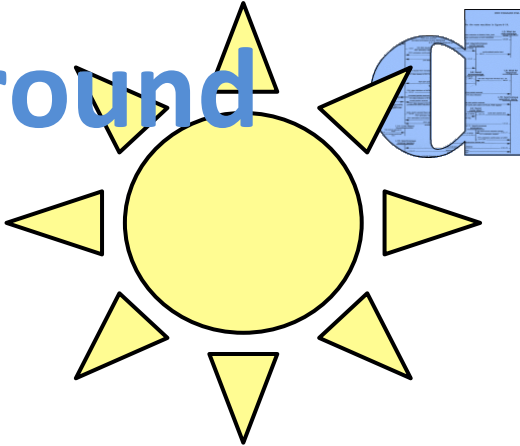


1999: 0.07 GW

2009: 10.6 GW

2019: 49.0 GW

The German Energy Turn-Around



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- ⇒ In Germany ... and elsewhere
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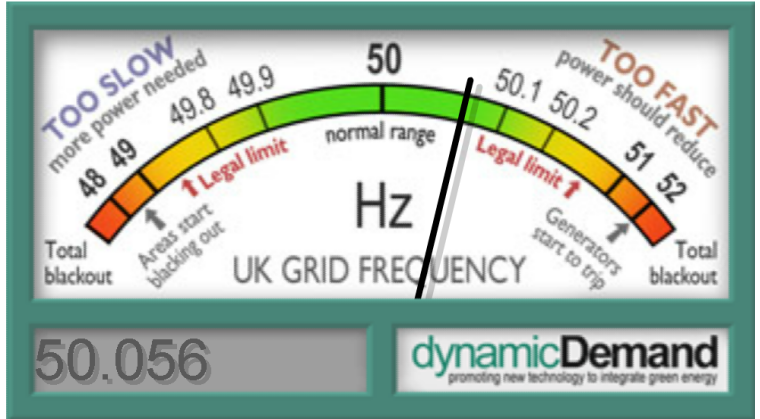
1999: 0.07 GW

2009: 10.6 GW

2019: 49.0 GW

That is so great!

Is it?



European Grid:
15 GW ≈ 1 Hz

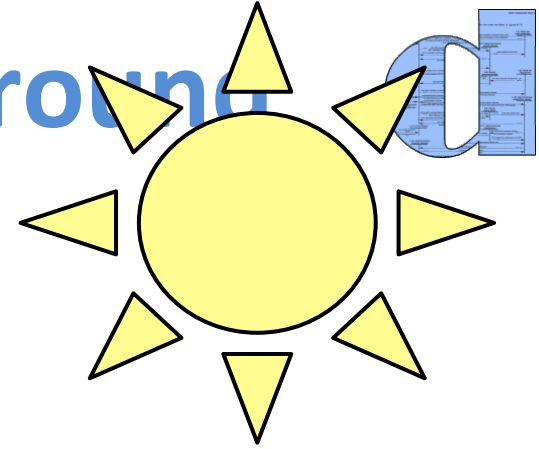
Target:
[49.8, 50.2] Hz

The German Energy Turn-Around

Renewables are on the rise!

⇒ In Germany ... and elsewhere

⇒ On residential rooftops.



They jointly influence the stability of the European grid.

Current state of control:

EN 50438:2007, in force since 2007:

Switch off when frequency > 50.2 Hz

"on-off"
controller

VDE-AR-N 4105, required today:

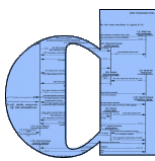
Output linear function of frequency in $[50.2, 51.5]$ Hz

Emergency switchoff above 51.5 Hz

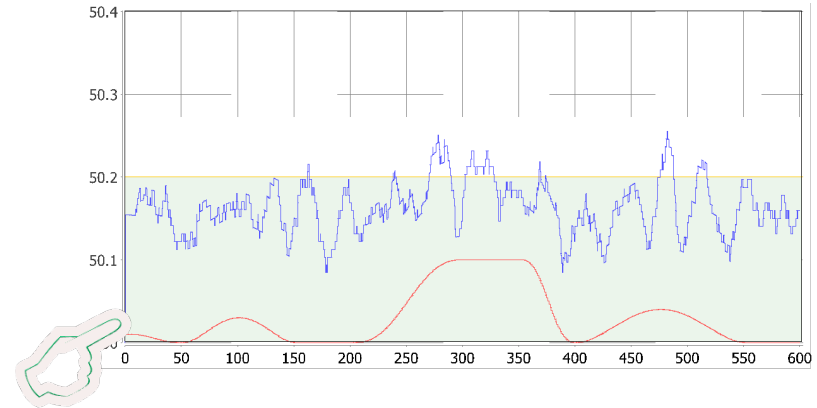
Switch on again when < 50.05 Hz for 1 minute

"linear"
controller

The Distributed Turn-Around



Each controller is a gambler.



Let a die decide whether you must leave the grid.

Size of dice depends on grid frequency.

... as in 802.11e

(linearly)

Let another die decide when you can resume.

Size of dice depends on length of overload.

... as in Ethernet

(exponentially)

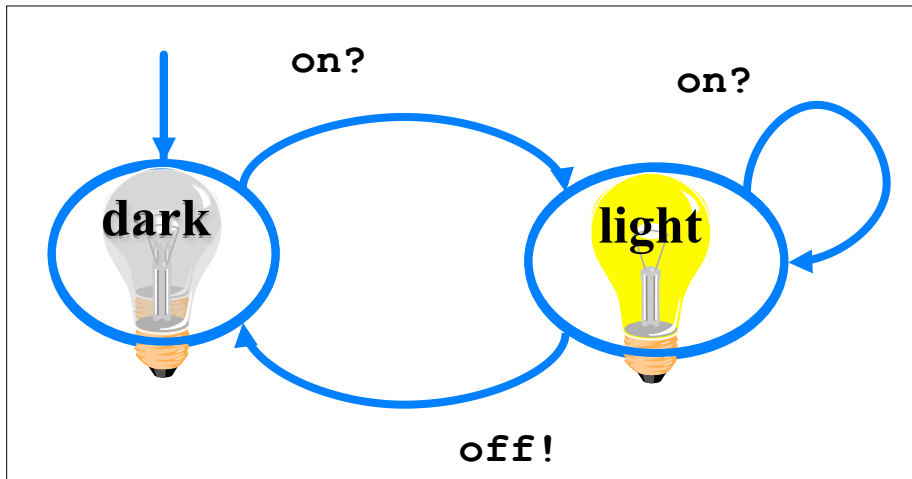
Quantitative Models

All models
are wrong,
but some
are useful

George E. P. Box

Useful Quantitative Models

🏠 finite automata

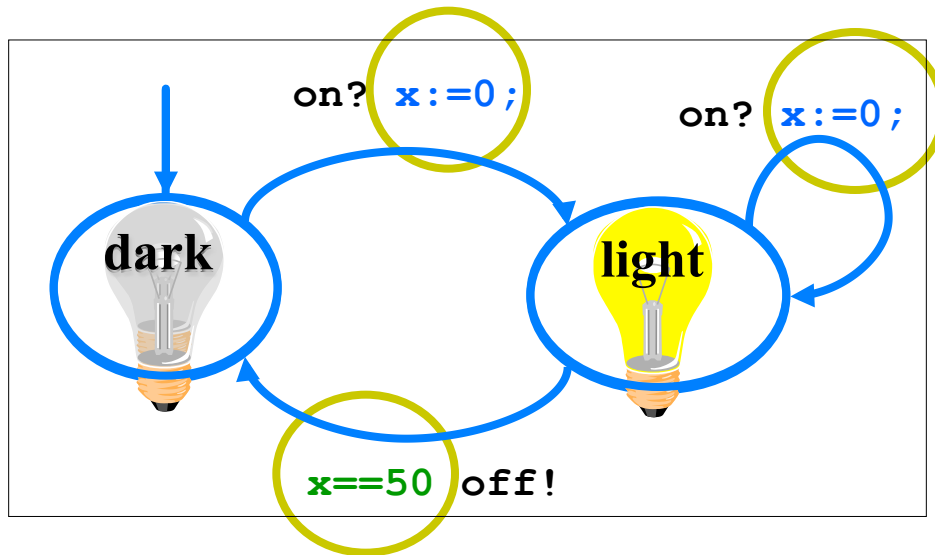


Useful Quantitative Models

finite automata

with clocks

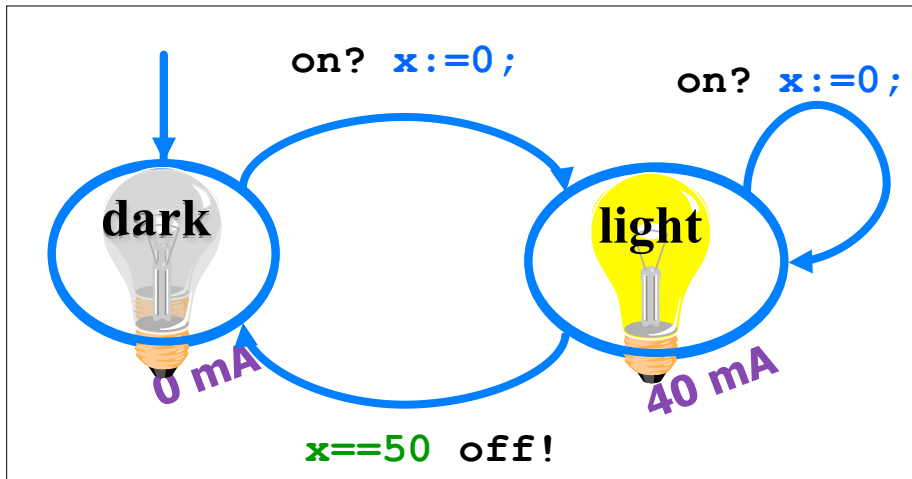
all running at the same speed



Timed Automata

Useful Quantitative Models

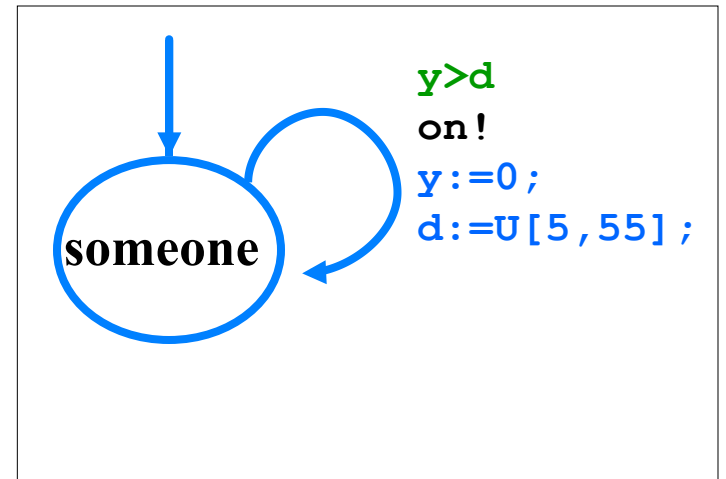
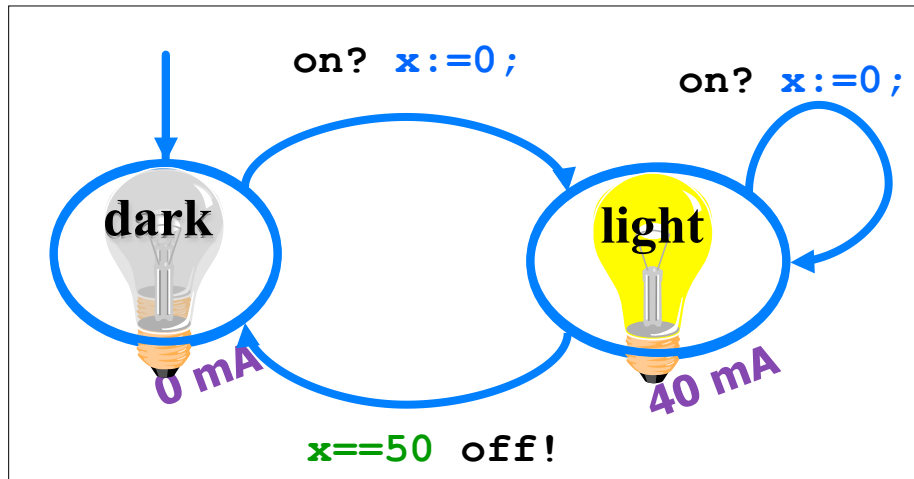
- finite automata
- with clocks
- and with costs *incurred as time advances*



Priced Timed Automata

Useful Quantitative Models

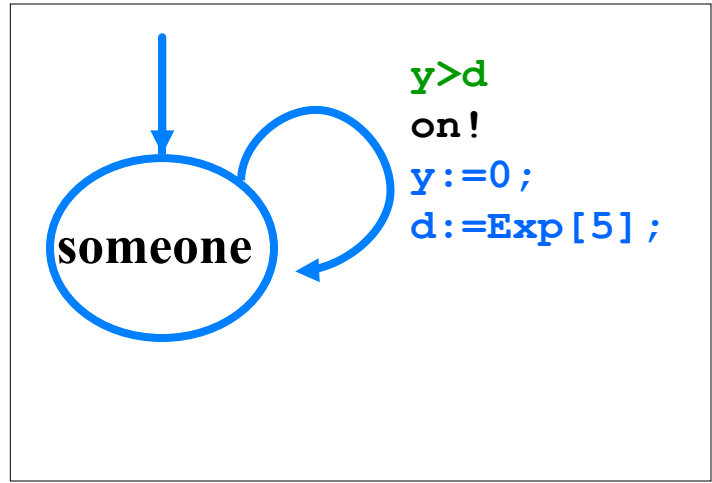
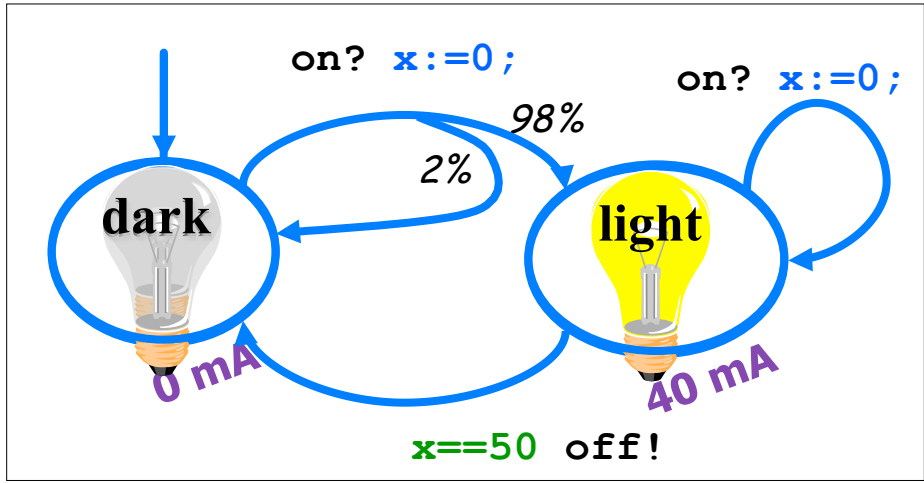
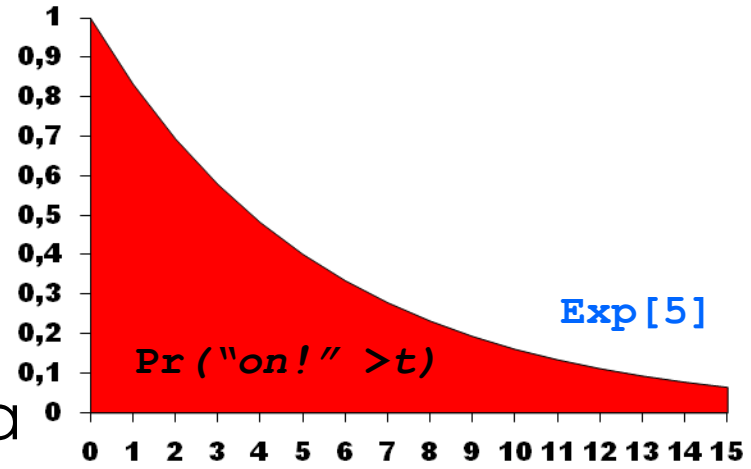
- finite automata
- with clocks
- and with costs
- modular: composition of automata



Automata Networks

Useful Quantitative Models

- finite automata
- with clocks
- and with costs
- modular: composition of automata

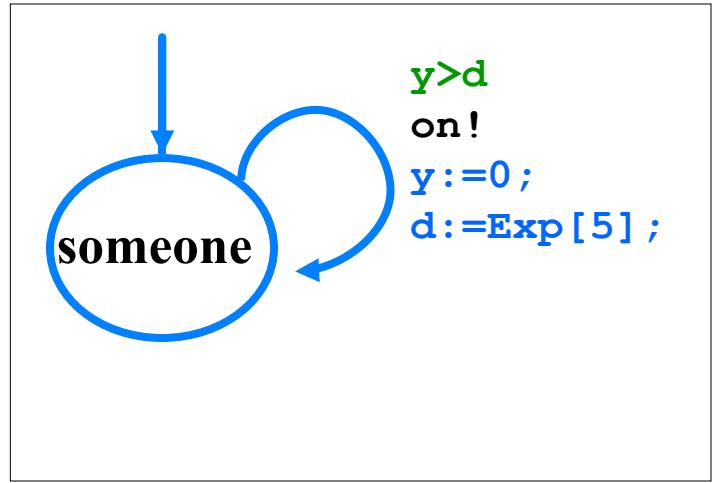
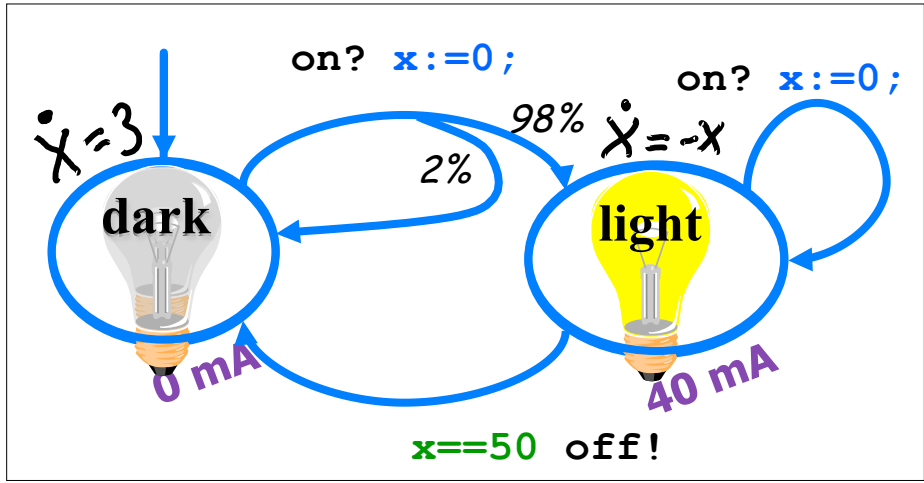
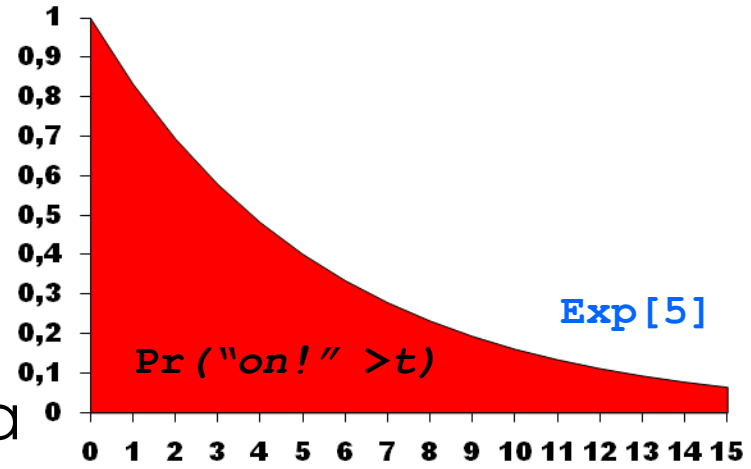


- with probability distributions

Stochastic Timed Automata

Useful Quantitative Models

- finite automata
- with clocks
- and with costs
- modular: composition of automata

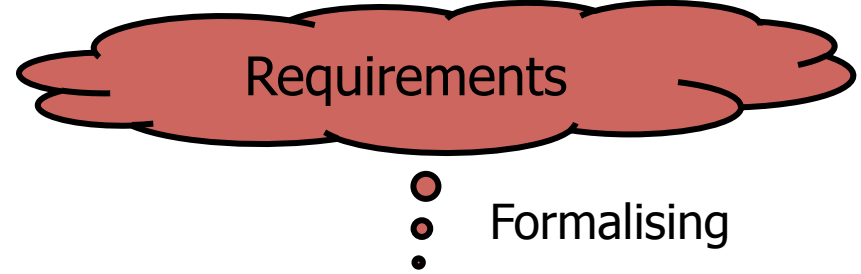
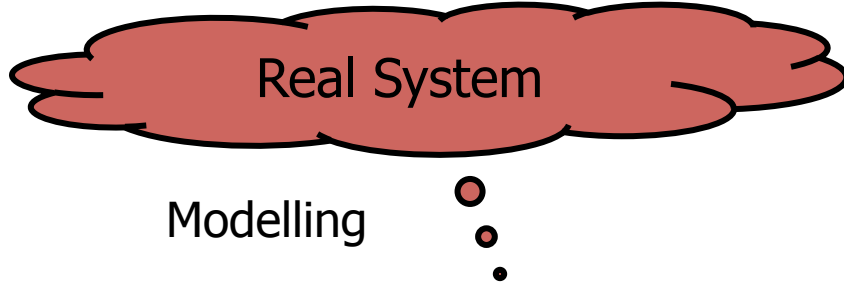


- with probability distributions
- and continuous dynamics

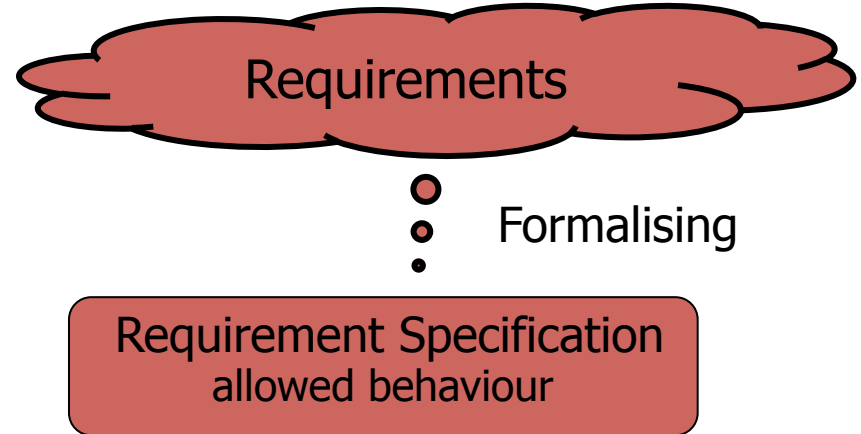
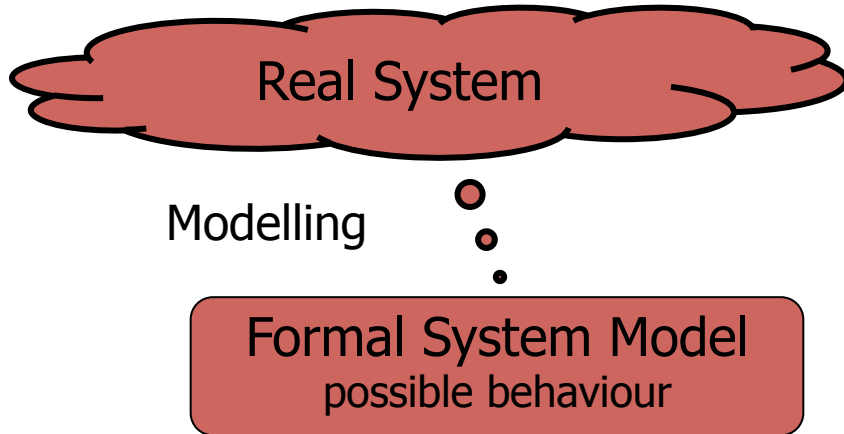
Stochastic Hybrid Automata

Model Checking

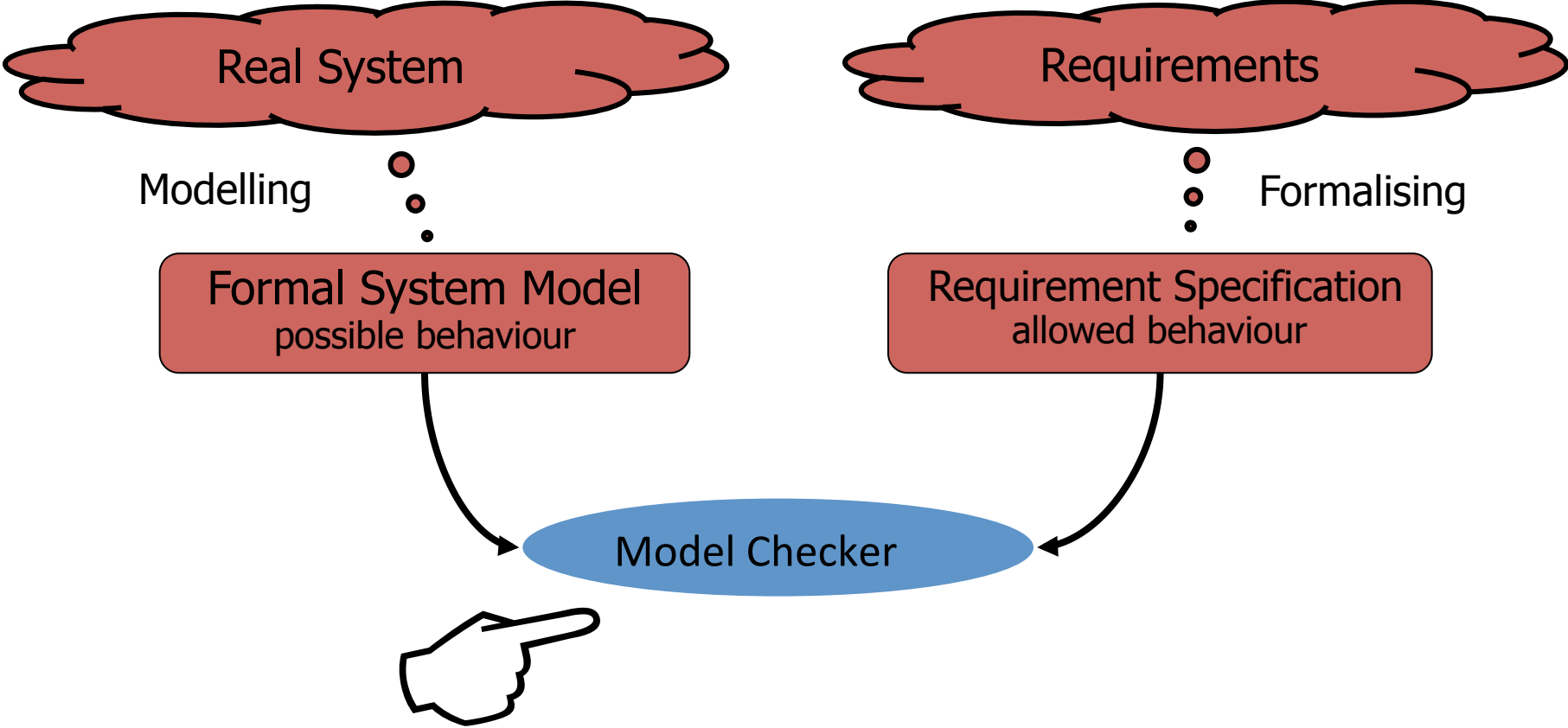
Model Checking



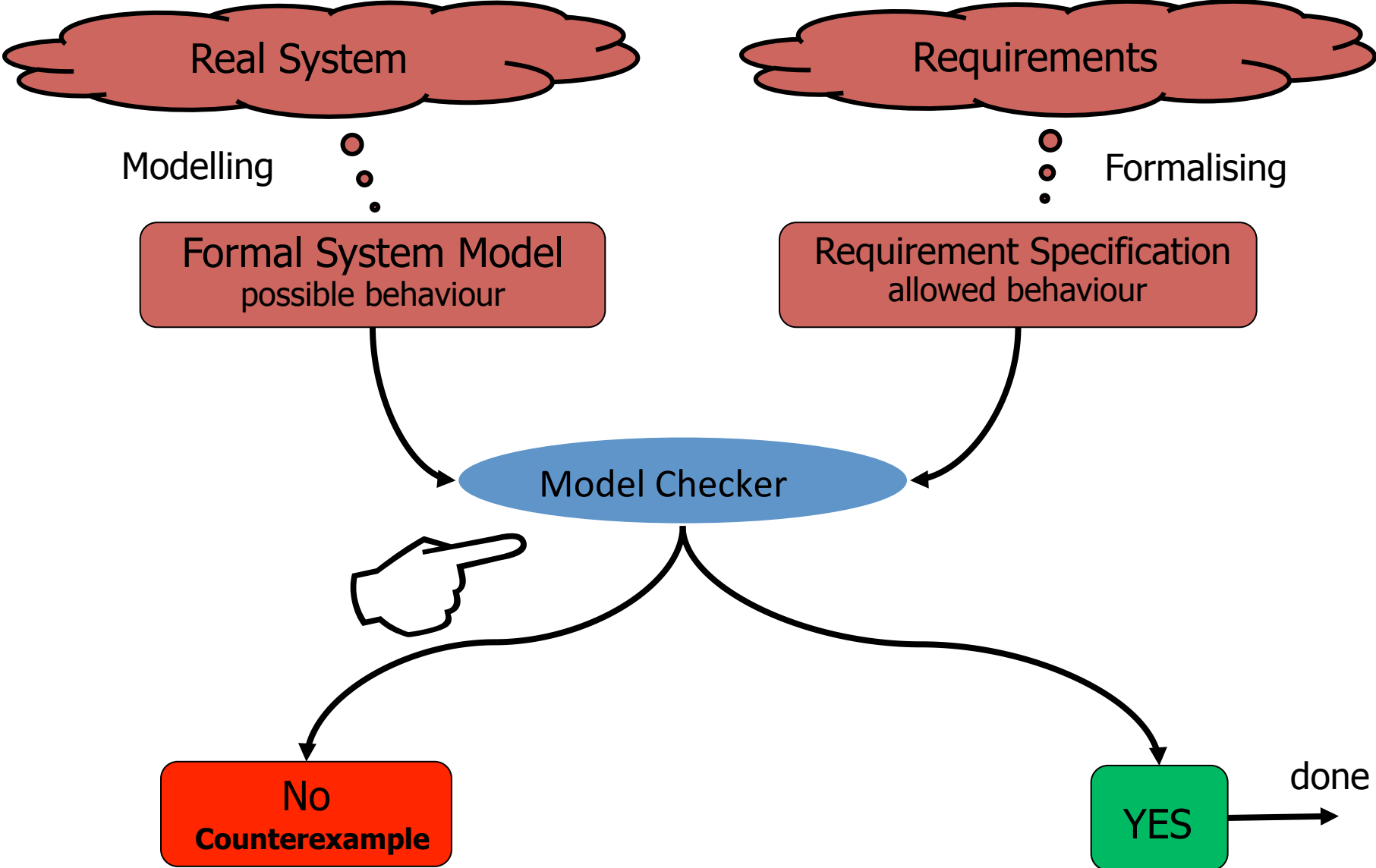
Model Checking



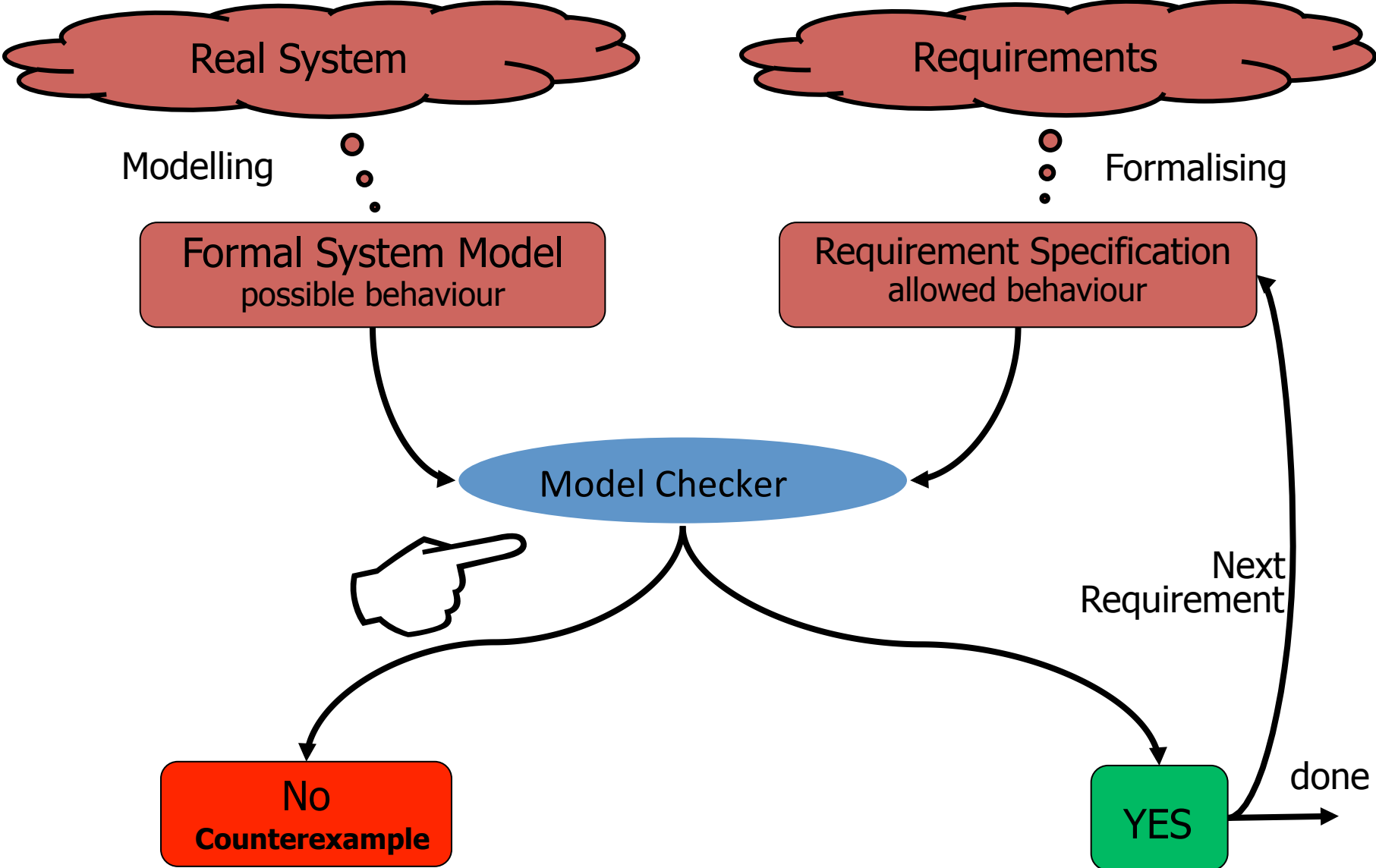
Model Checking



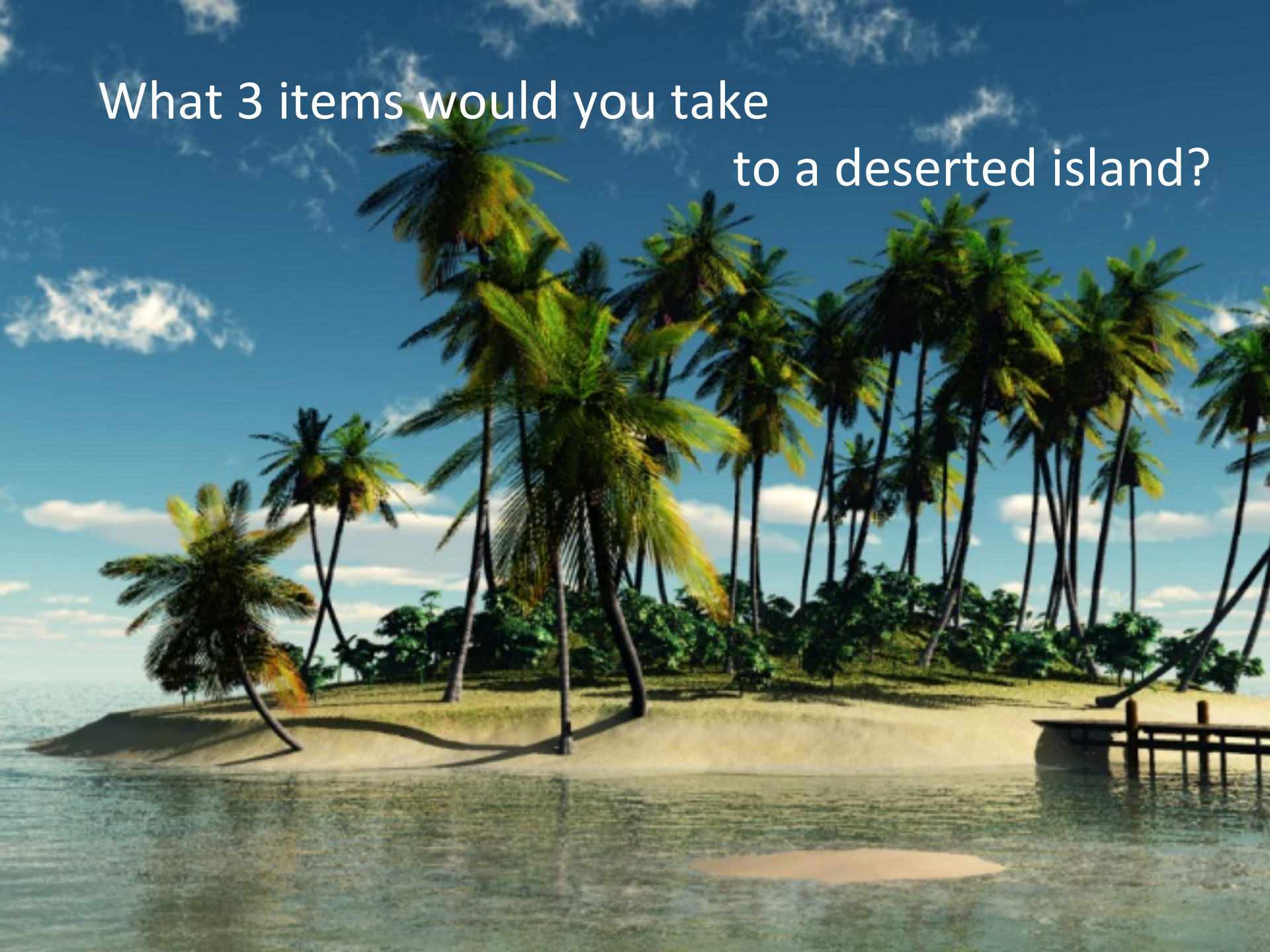
Model Checking



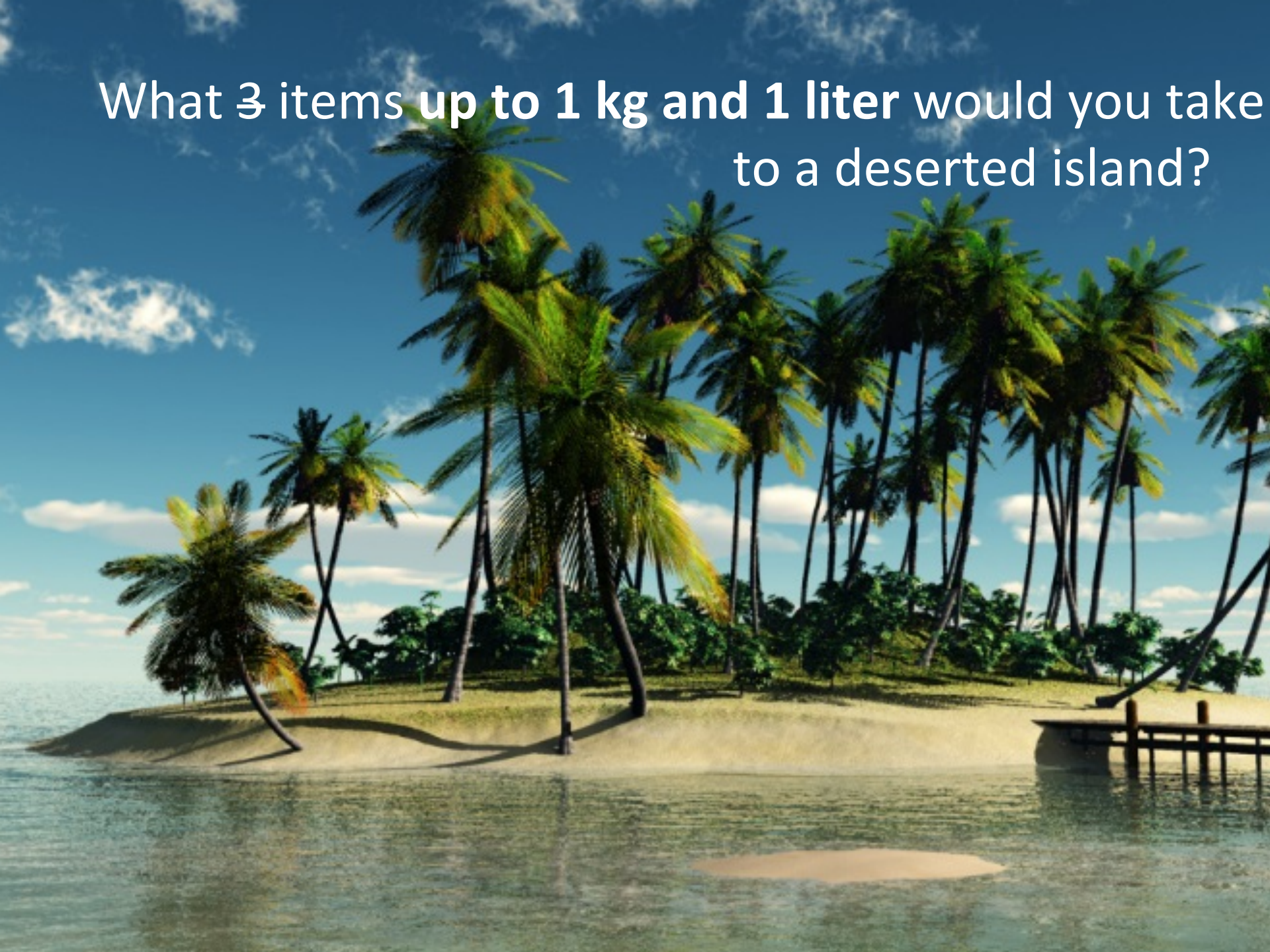
Model Checking



What 3 items would you take
to a deserted island?



What 3 items **up to 1 kg and 1 liter** would you take to a deserted island?



What 3 items **up to 1 kg and 1 liter** would you take to a deserted island?



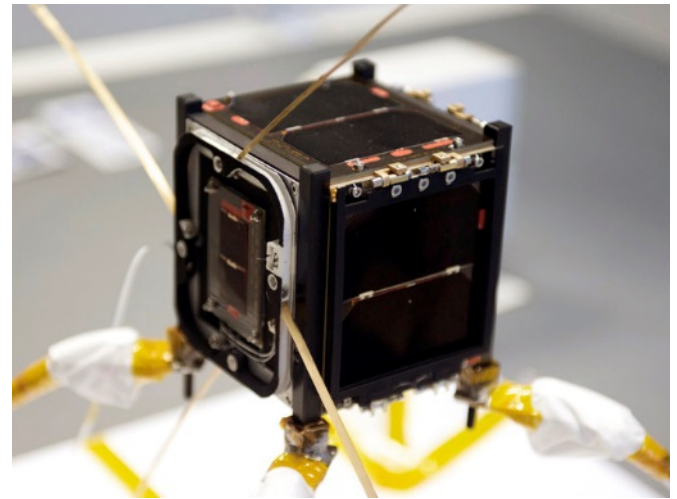
ESA 'Fly Your Satellite!' program

What 3 items **up to 1 kg and 1 liter** would you take **into space?**

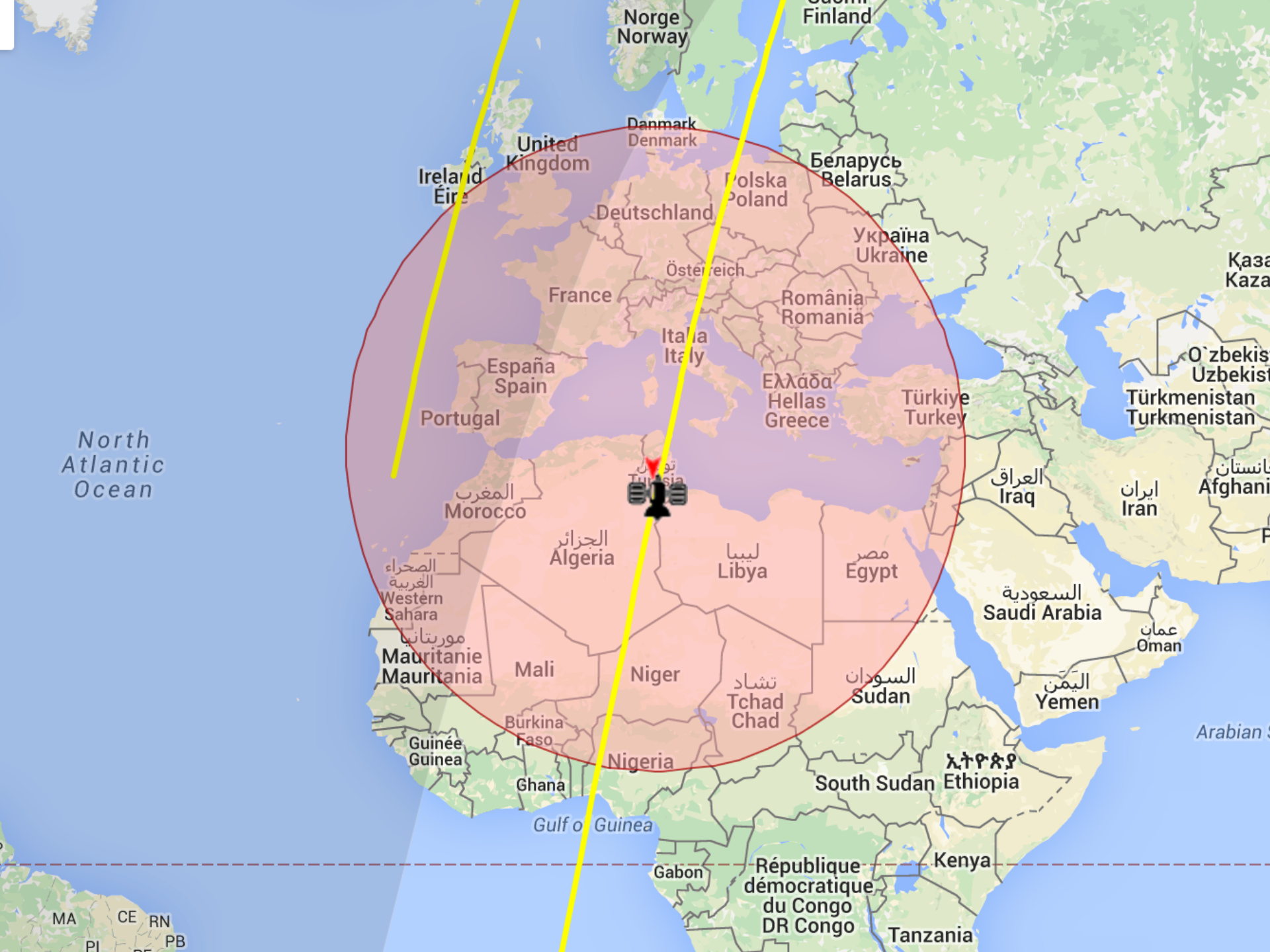
Cube Satellites, educational / scientific use

Limits: Up to 1 kg & 1 liter

Mission time: up to 4 years



European Space Agency



Norge
Norway

Finland

Danmark
Denmark

United Kingdom
Ireland
Éire

Polska
Poland

Беларусь
Belarus

Deutschland

Україна
Ukraine

France

Österreich

România
Romania

Italia
Italy

España
Spain

Ελλάδα
Hellas
Greece

Türkiye
Turkey

Portugal

North Atlantic Ocean

المغرب
Morocco

الجزائر
Algeria

ليبيا
Libya

مصر
Egypt

العراق
Iraq

ایران
Iran

O'zbekis
Uzbekis

Türkmenistan
Turkmenistan

افغانستان
Afghanistan

الصحراء الغربية
Western Sahara

موريتانيا
Mauritania

Mali

Niger

تشاد
Tchad
Chad

السودان
Sudan

السعودية
Saudi Arabia

عمان
Oman

اليمن
Yemen

Arabian S

Guinée
Guinea

Burkina Faso

Nigeria

Gulf of Guinea

South Sudan
Ethiopia

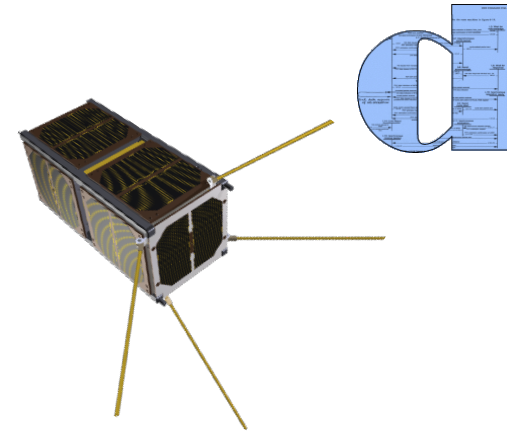
MA CE RN
PI DE PB

Gabon
République démocratique
du Congo
DR Congo

Kenya

Tanzania

GOMSPACE GOMX-1

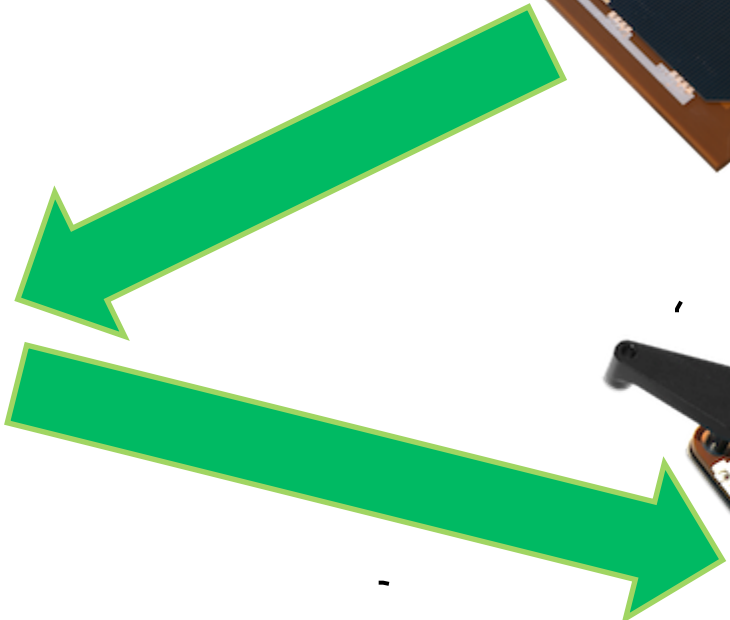
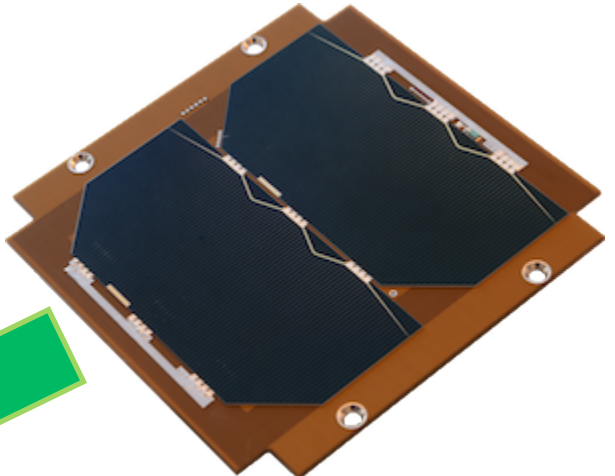
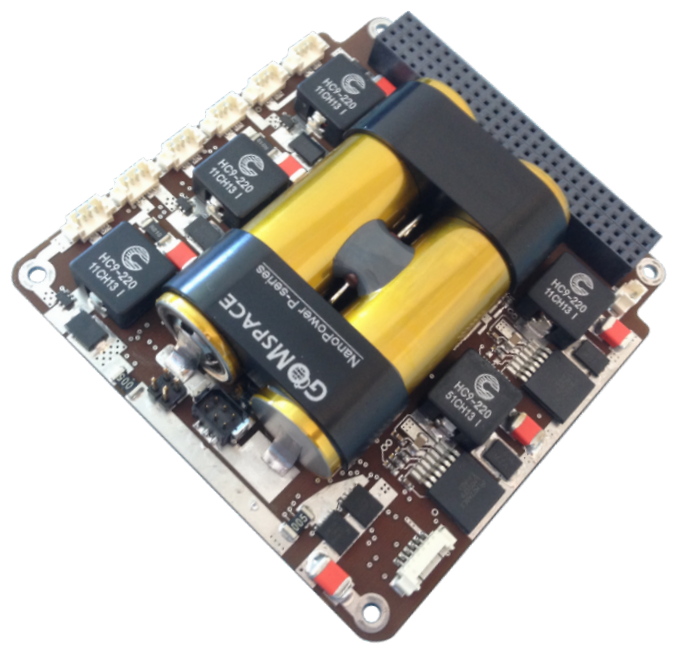
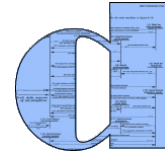


- 2U CubeSat (2 liter)
- Launched in November 2013
- Payloads:
 - software defined receiver for aircraft signals
 - color camera for earth observation
- Telemetry transmitted on amateur radio frequency
- Massive amounts of data collected
 - battery voltage, temperature, solar infeed, ...

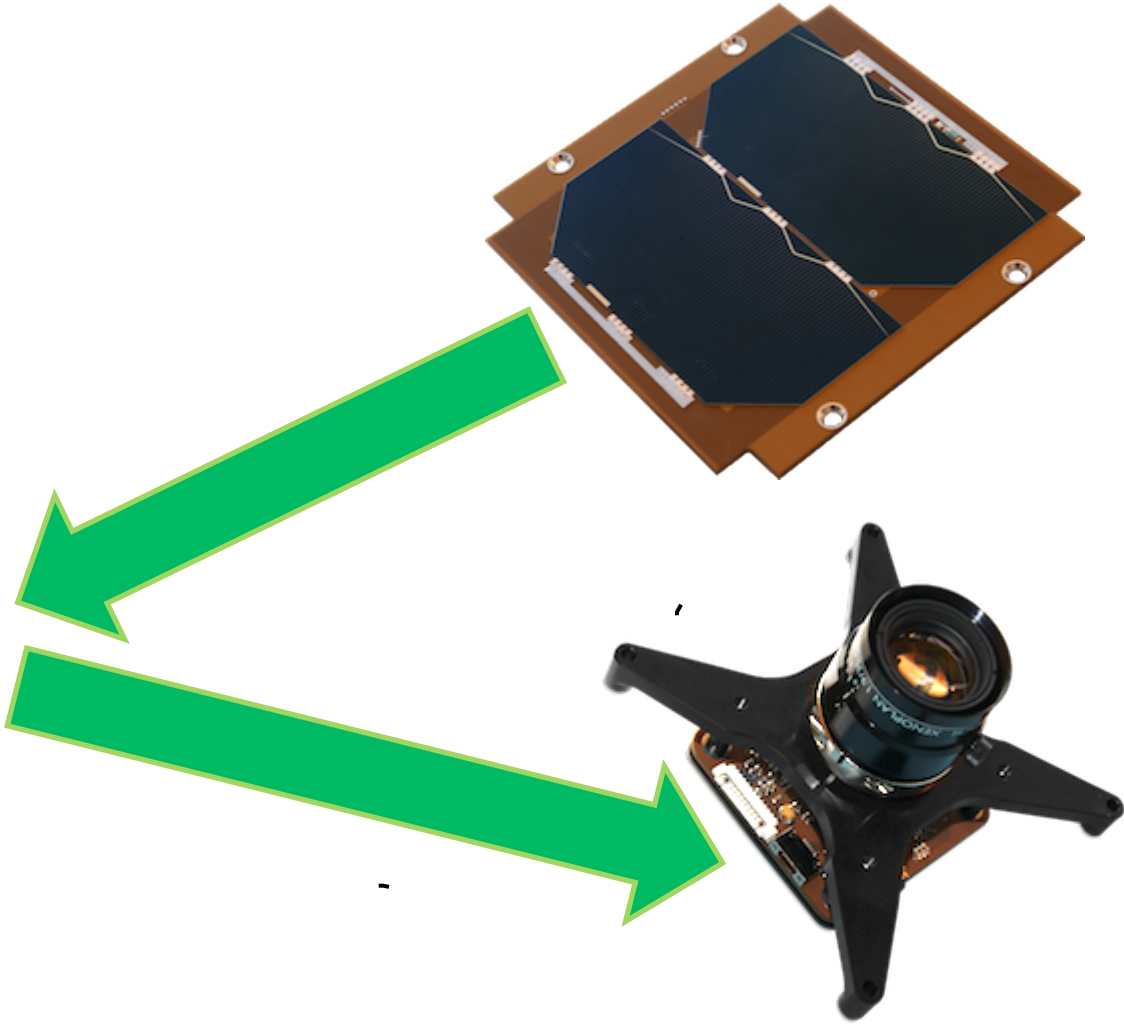
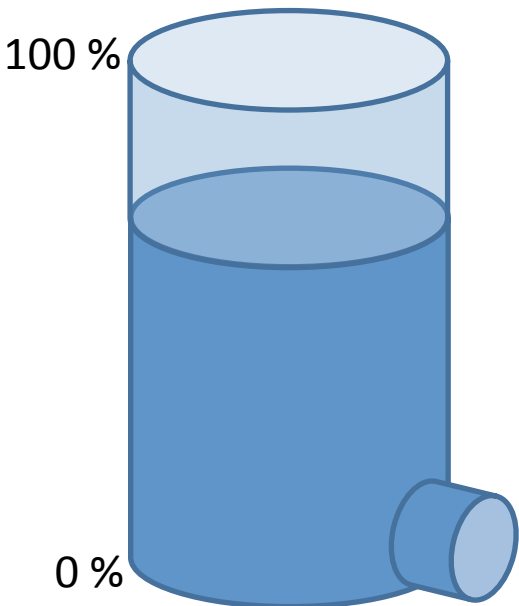
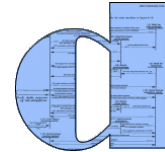
Runs our calibration experiments.

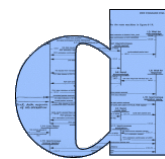


Battery Kinetics

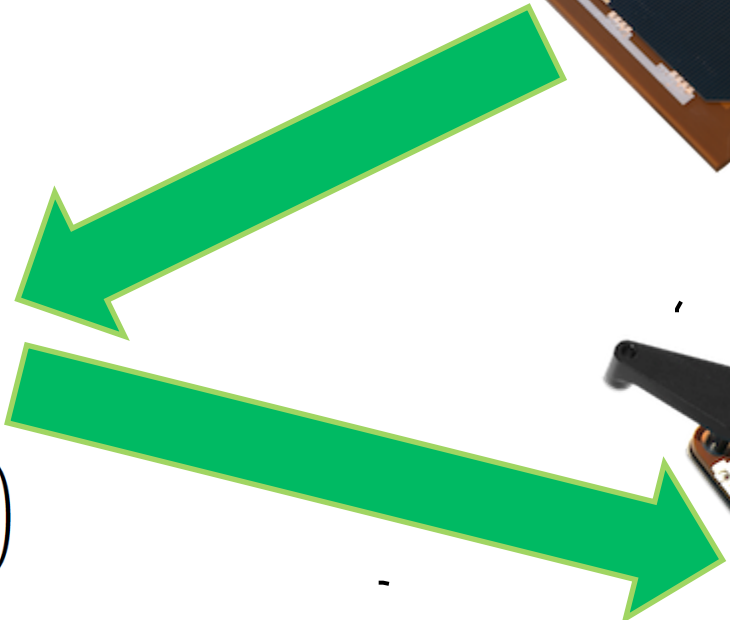
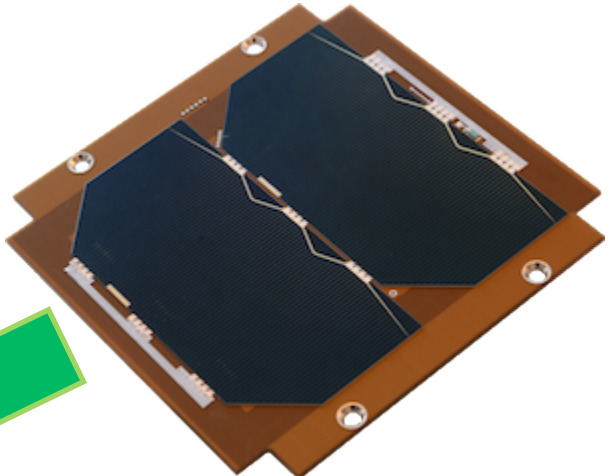
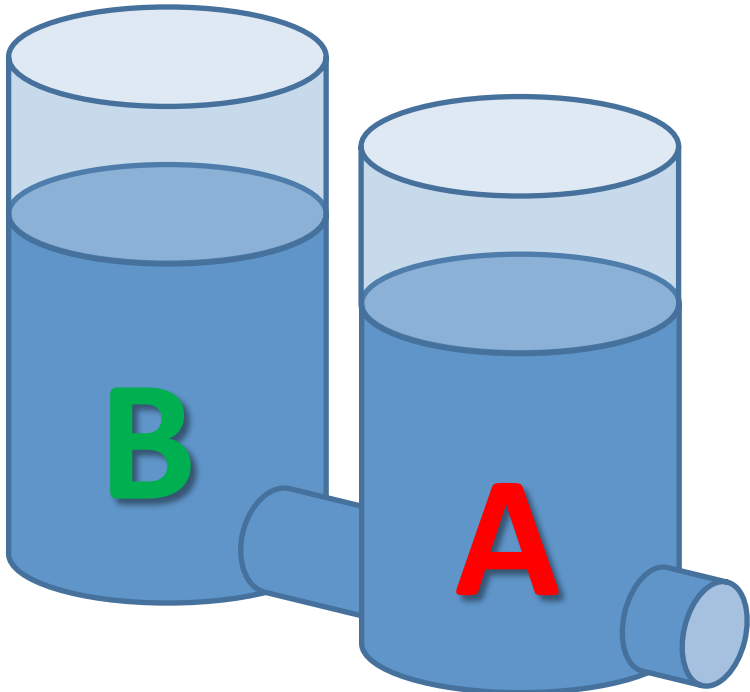


Battery Kinetics



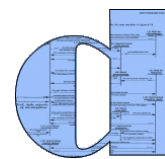


Battery Kinetics

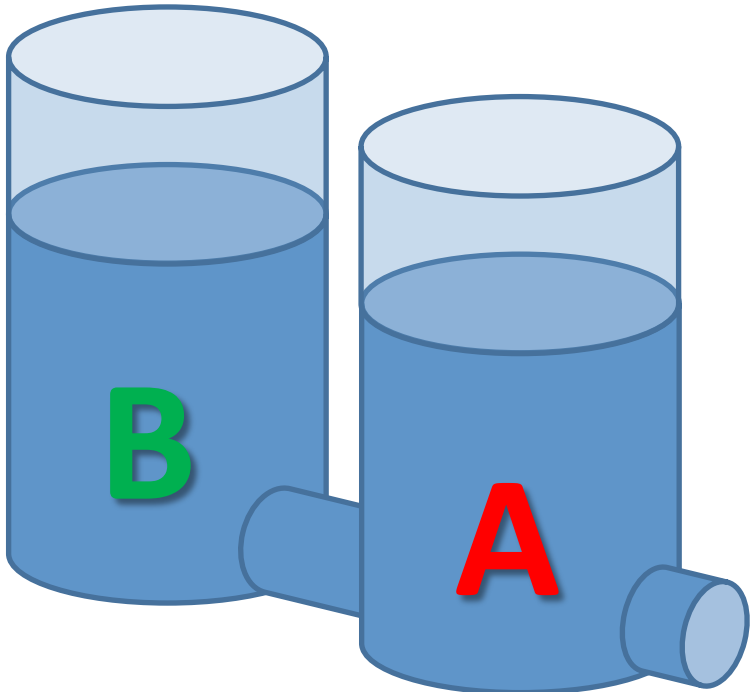


$$\dot{a}(t) = -I + p \left(\frac{b(t)}{1-c} - \frac{a(t)}{c} \right)$$
$$\dot{b}(t) = p \left(\frac{a(t)}{c} - \frac{b(t)}{1-c} \right)$$

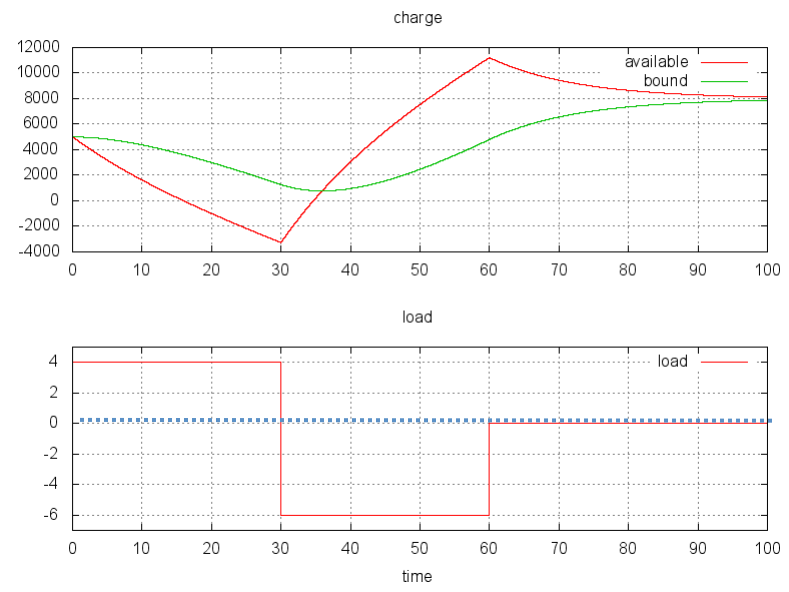
“Kinetic Battery Model”, or KiBaM



Battery Kinetics

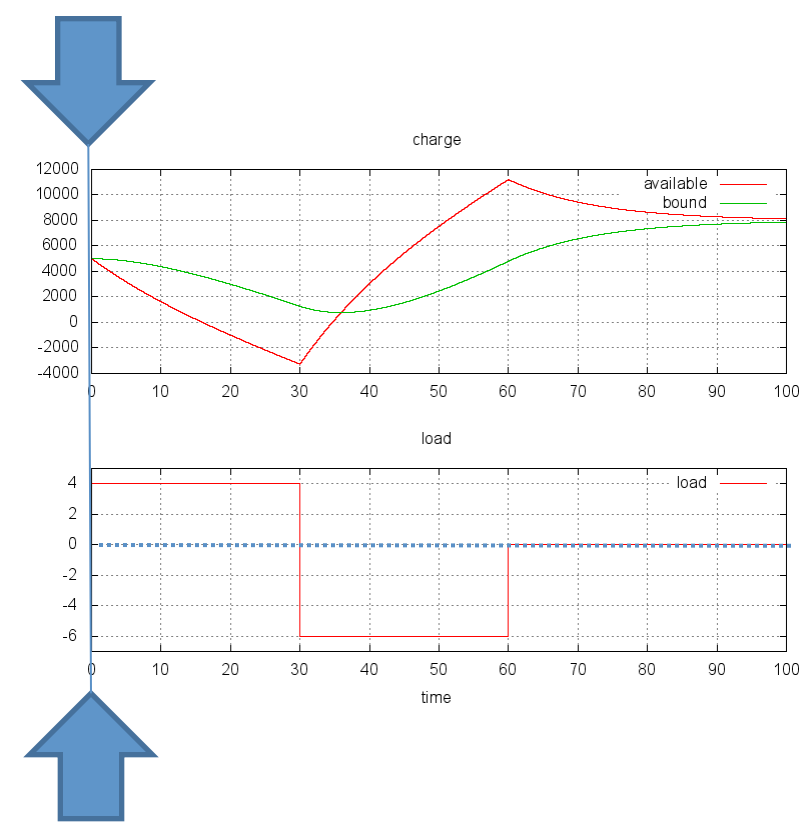
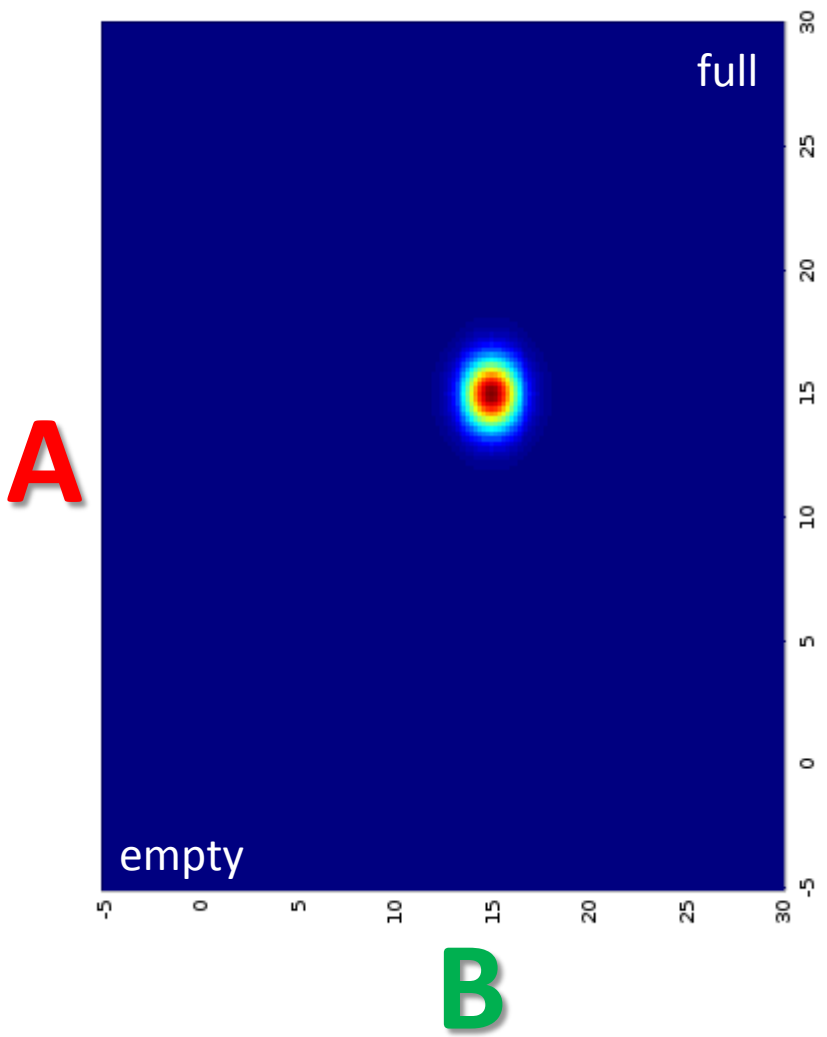
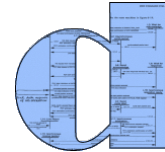


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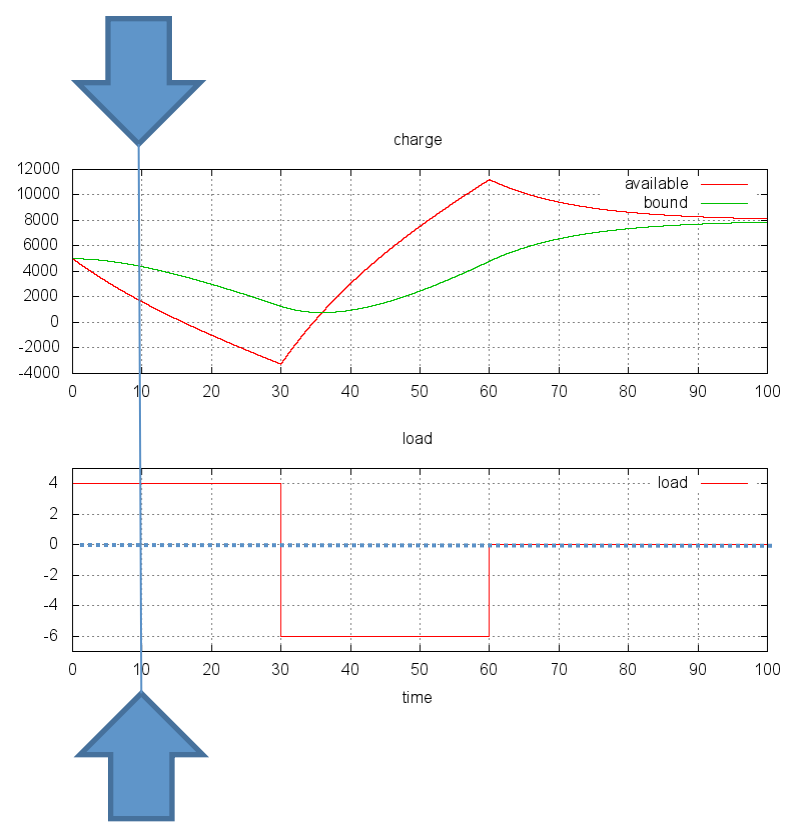
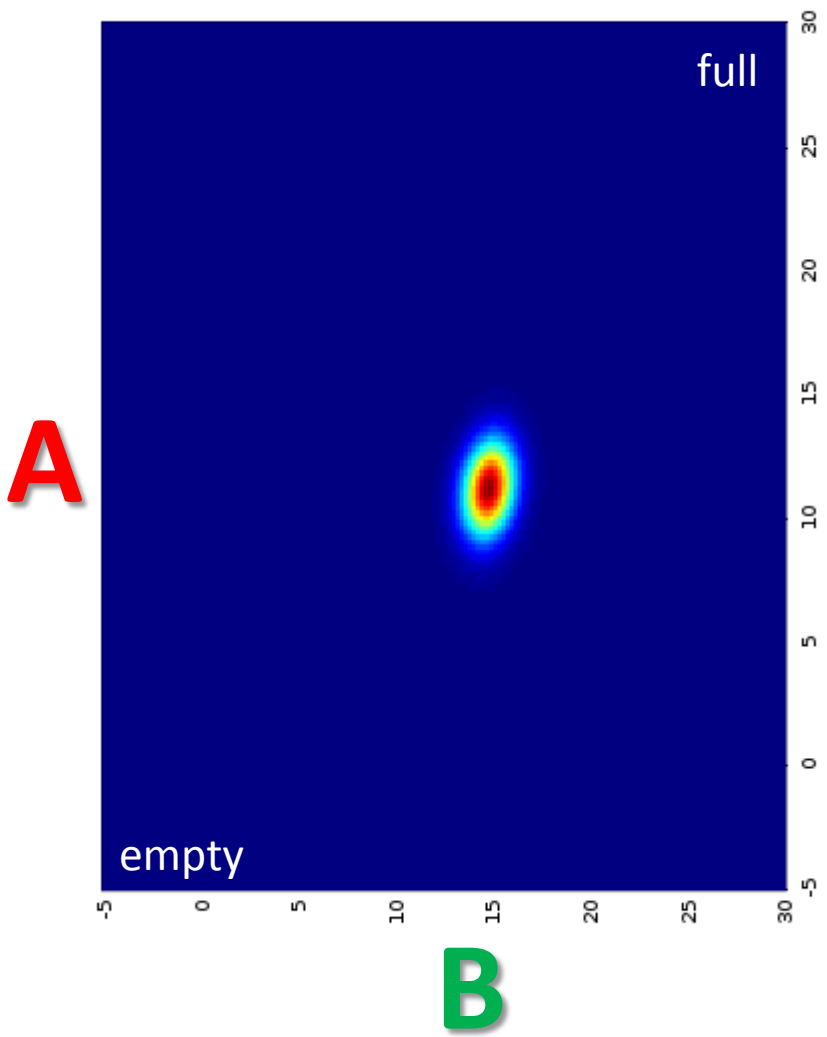
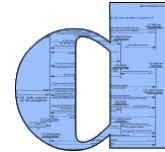
“Kinetic Battery Model”, or KiBaM

Battery Kinetics



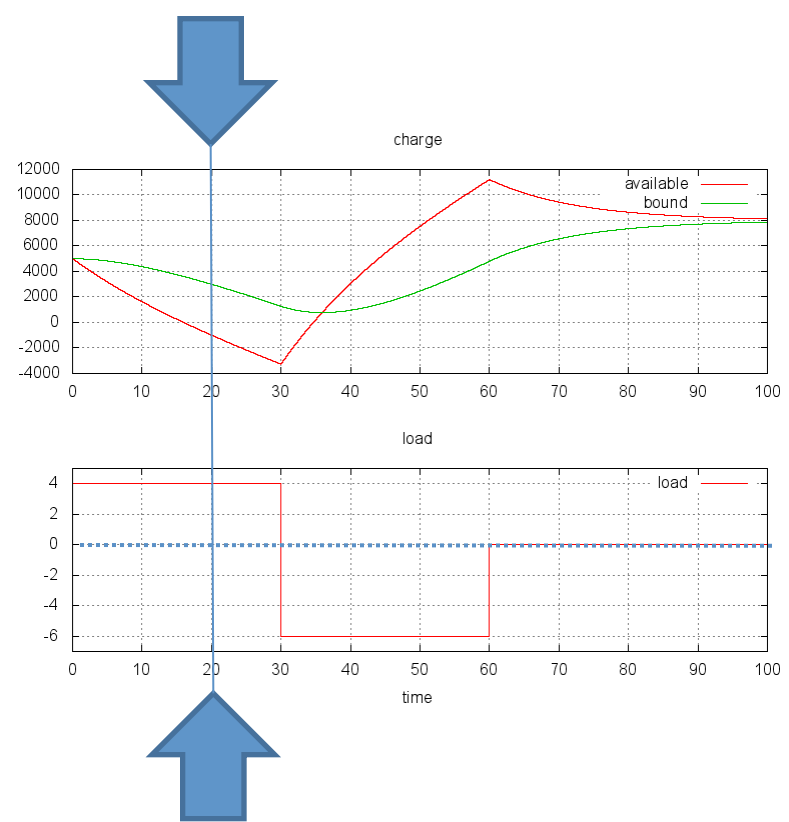
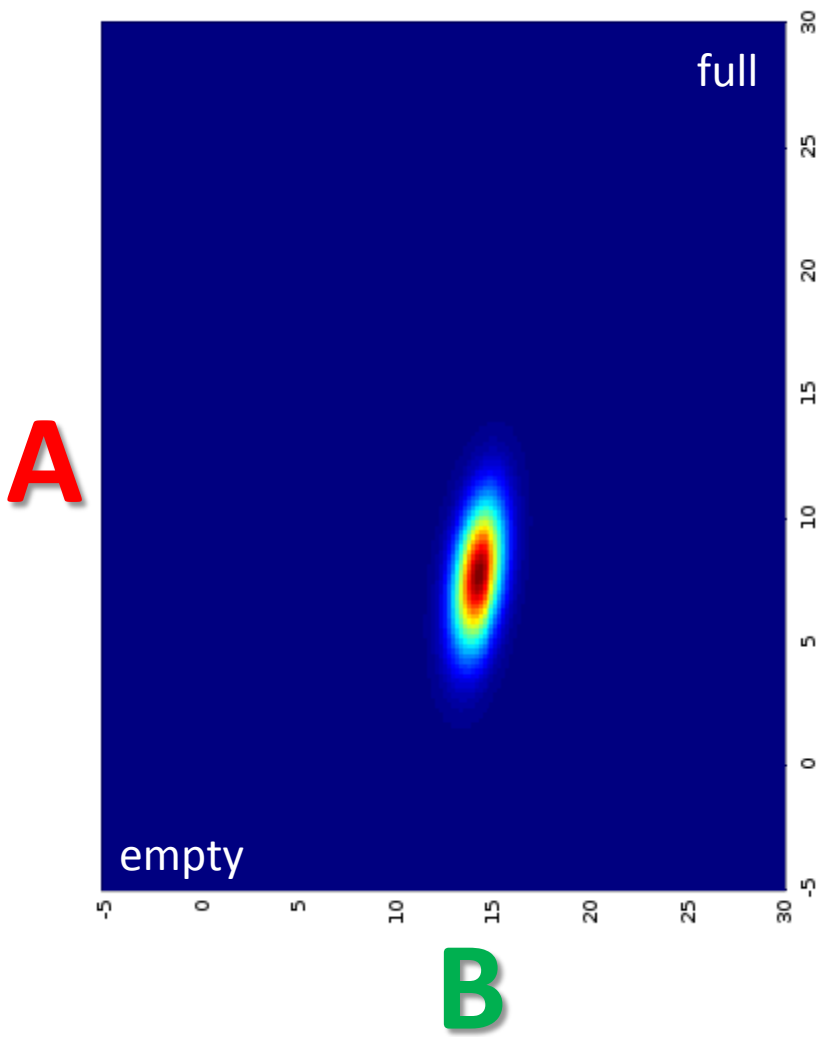
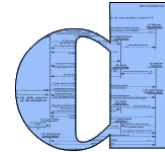
“Stochastic” KiBaM

Battery Kinetics



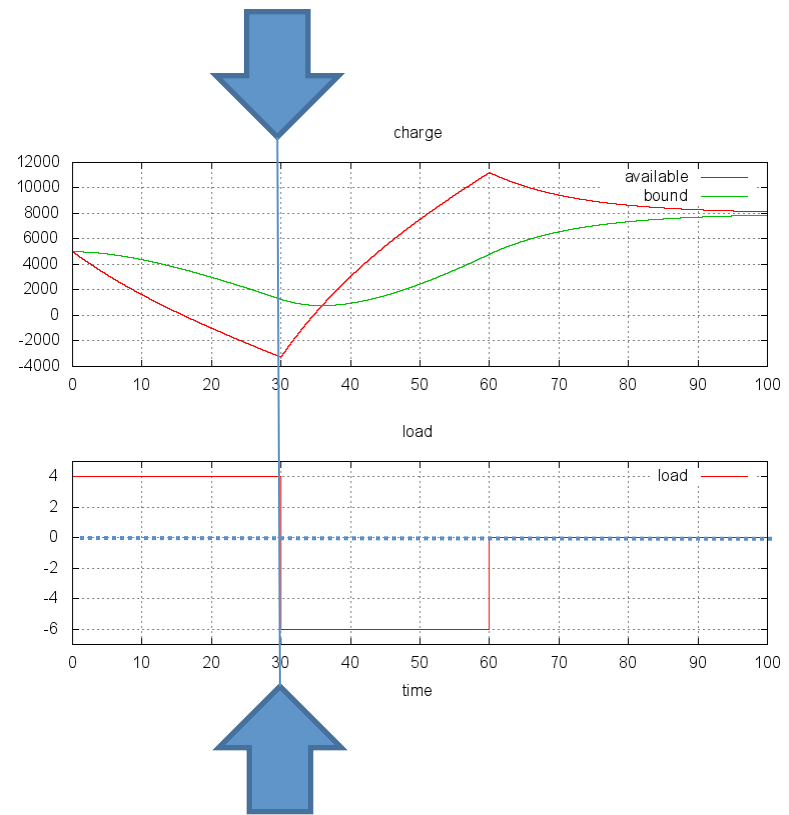
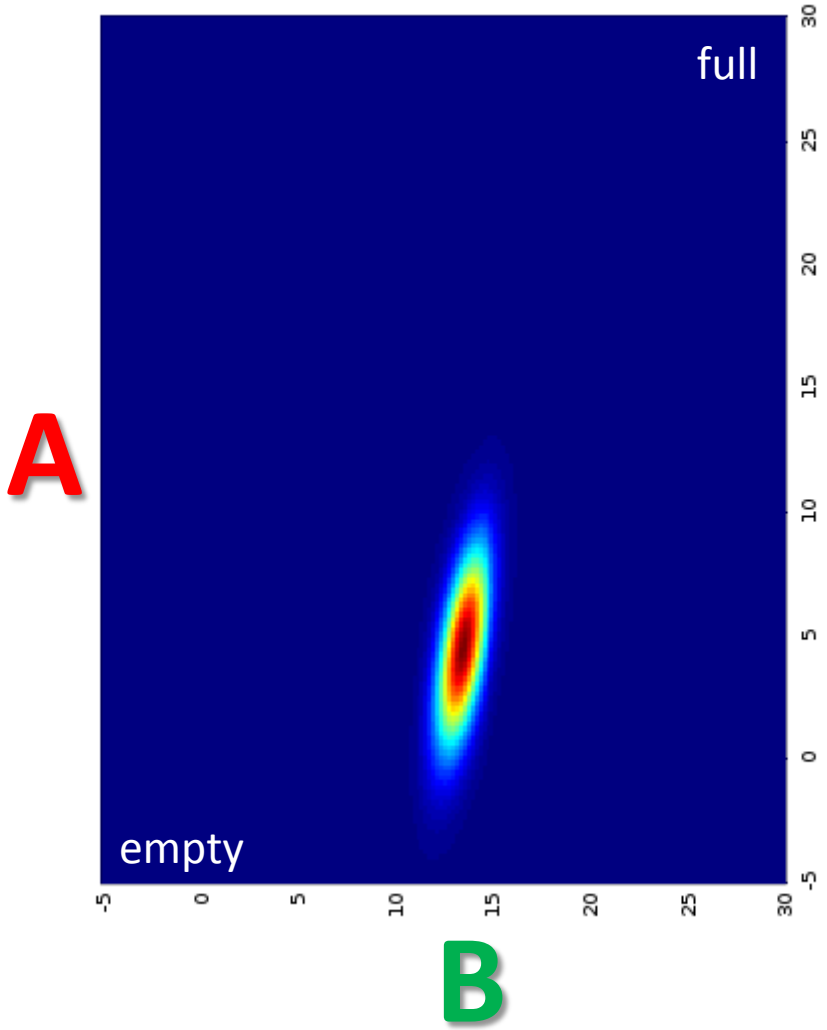
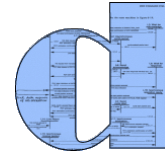
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Battery Kinetics



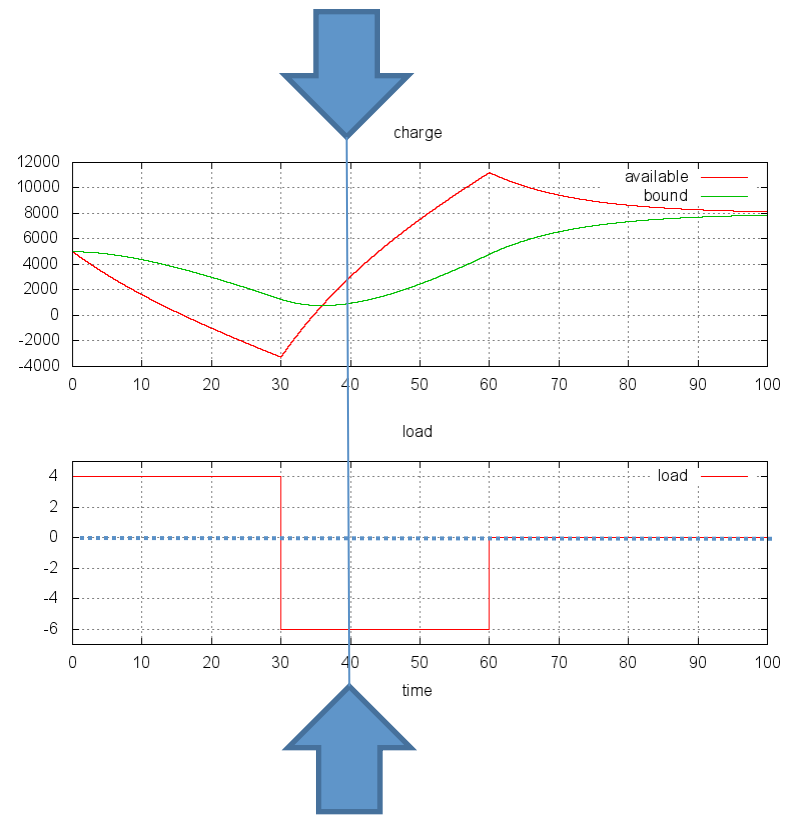
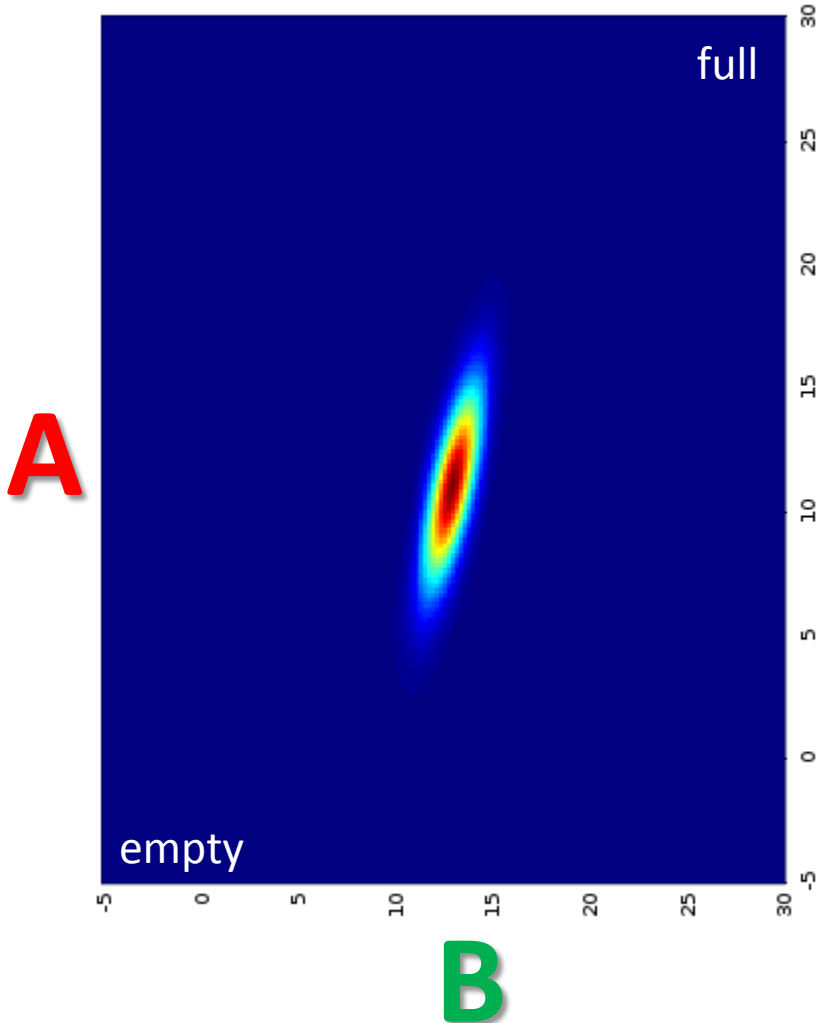
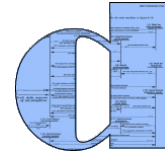
“Stochastic” KiBaM

Battery Kinetics



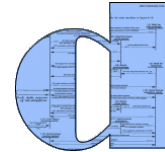
“Stochastic” KiBaM

Battery Kinetics

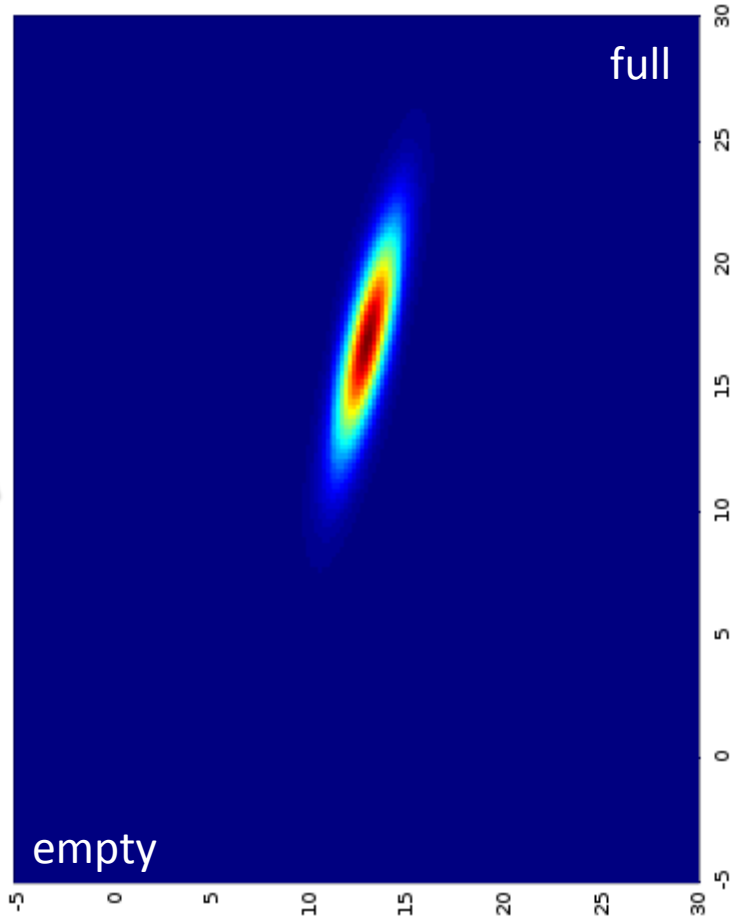


“Stochastic” KiBaM

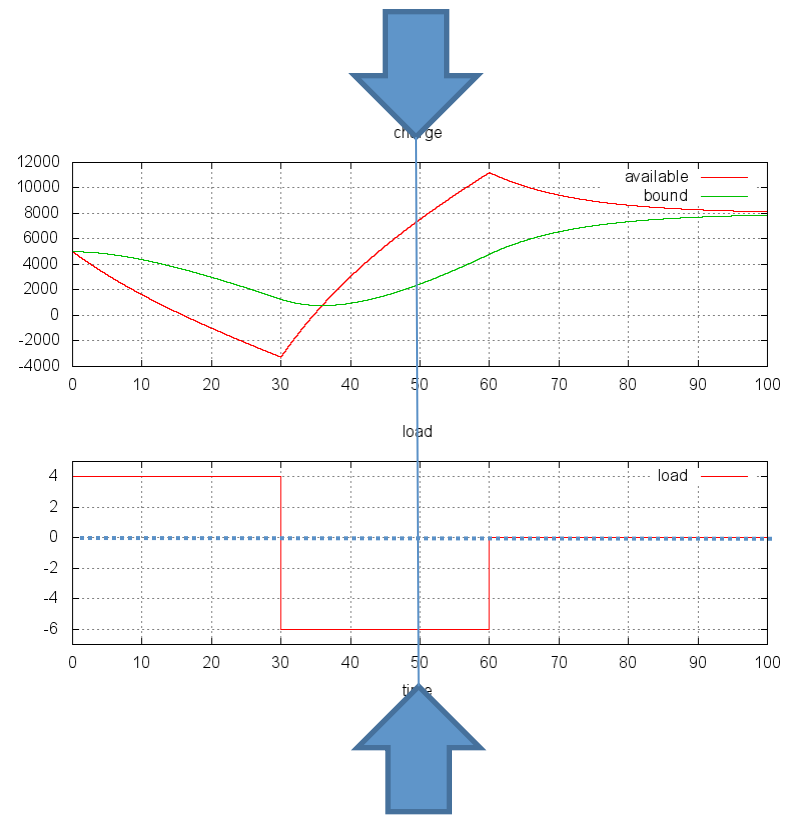
Battery Kinetics



A

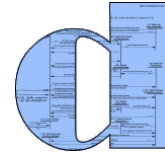


B

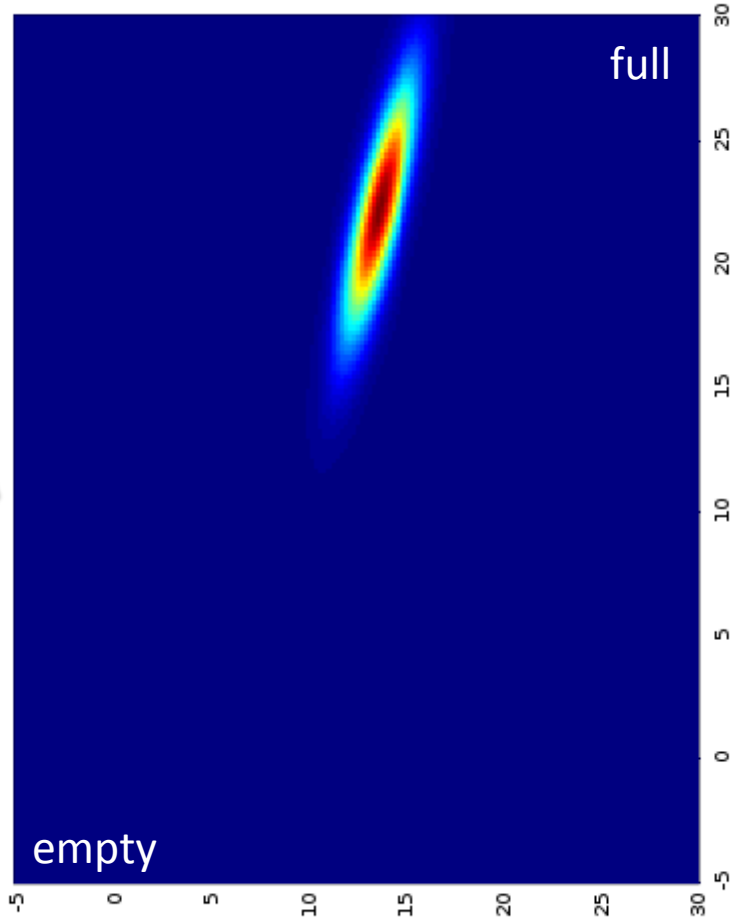


“Stochastic” KiBaM

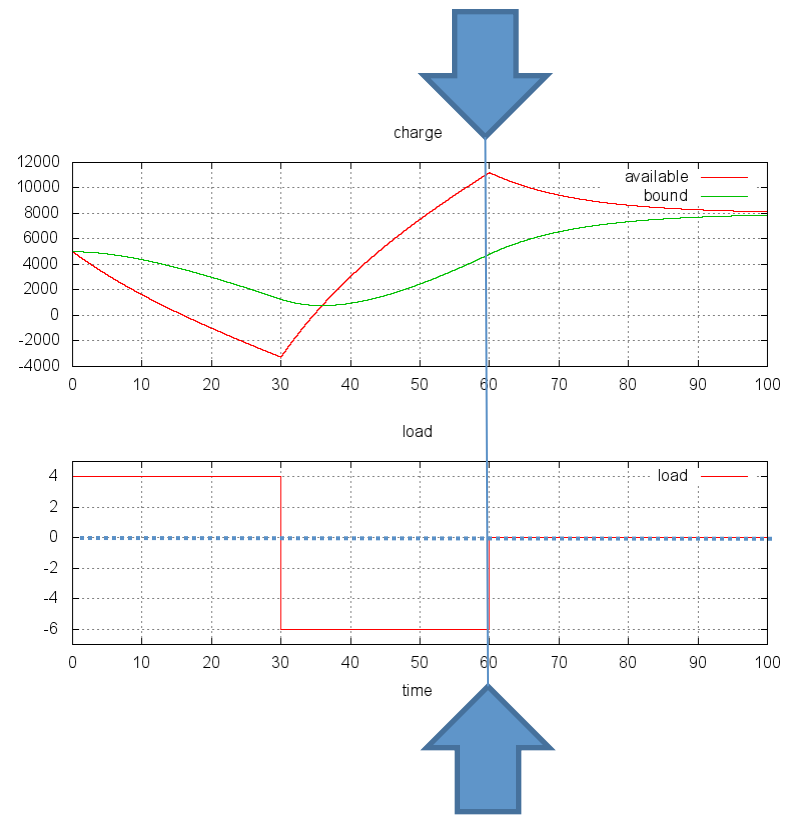
Battery Kinetics



A

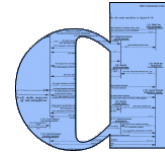


B

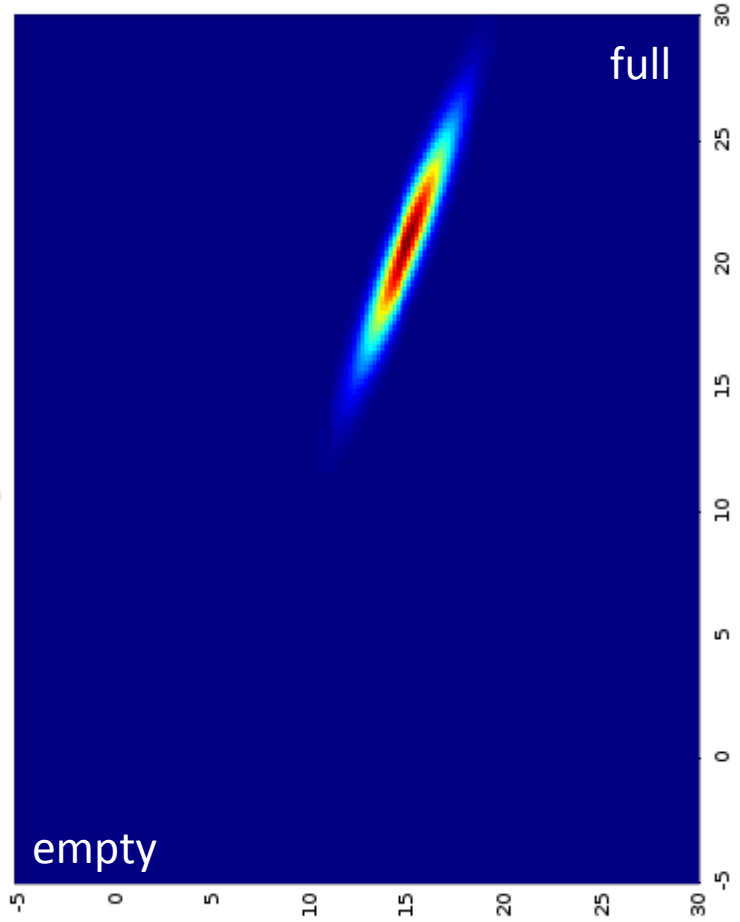


“Stochastic” KiBaM

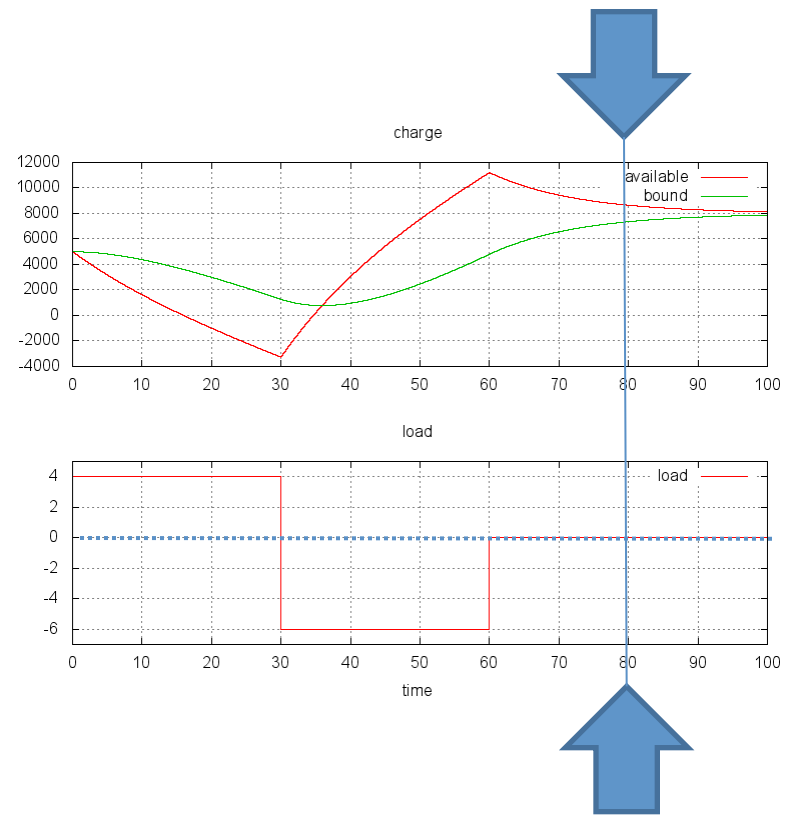
Battery Kinetics



A

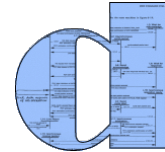


B

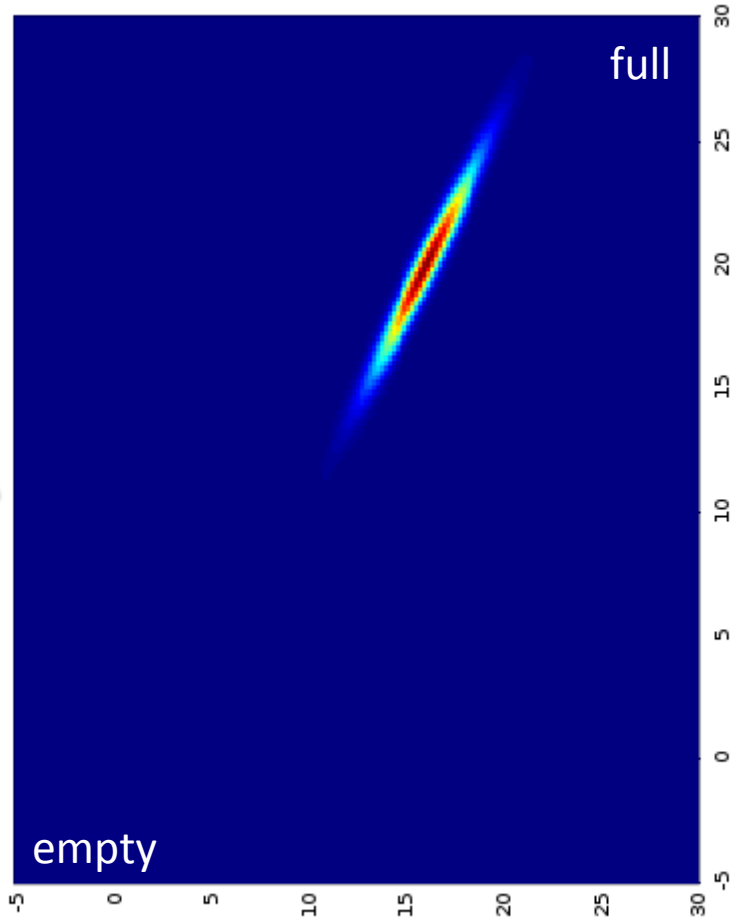


“Stochastic” KiBaM

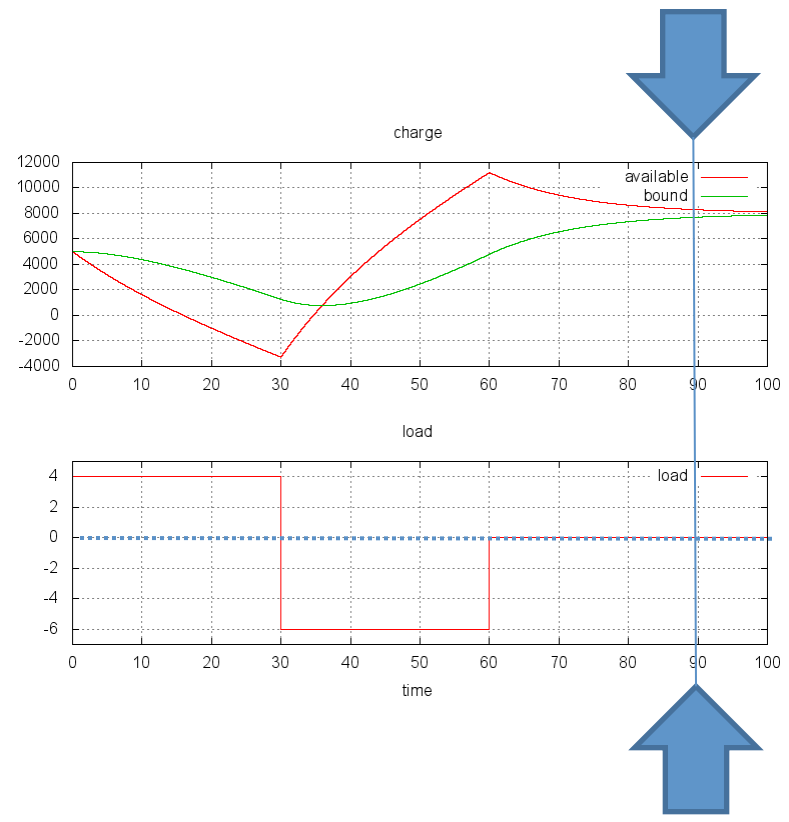
Battery Kinetics



A



B



“Stochastic” KiBaM

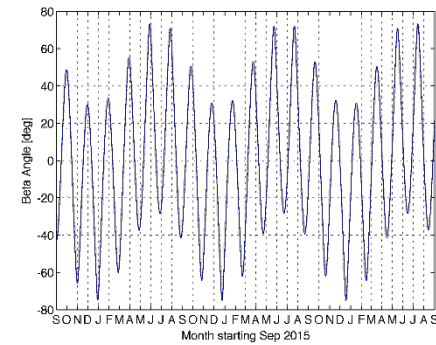


- 2U CubeSat
- Shipped in
- Payloads:
 - Optical camera
 - Highspeed UHF and SDR receiver
- Shipping failed after liftoff
- Satellite was recovered from wreckage and returned to manufacturer



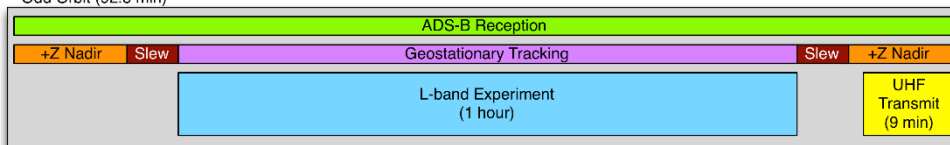


GOMX-3 mission planning



- Very tight power budget
- Needs dynamic and battery aware scheduling
- What we do:
 - Priced Timed Automata modelling with linear battery
 - Generate optimal schedules for 1 week or 1 day horizon
 - Evaluate schedules on “stochastic” KiBaM for robustness
 - Send to orbit, observe behaviour, update model

Odd Orbit (92.8 min)

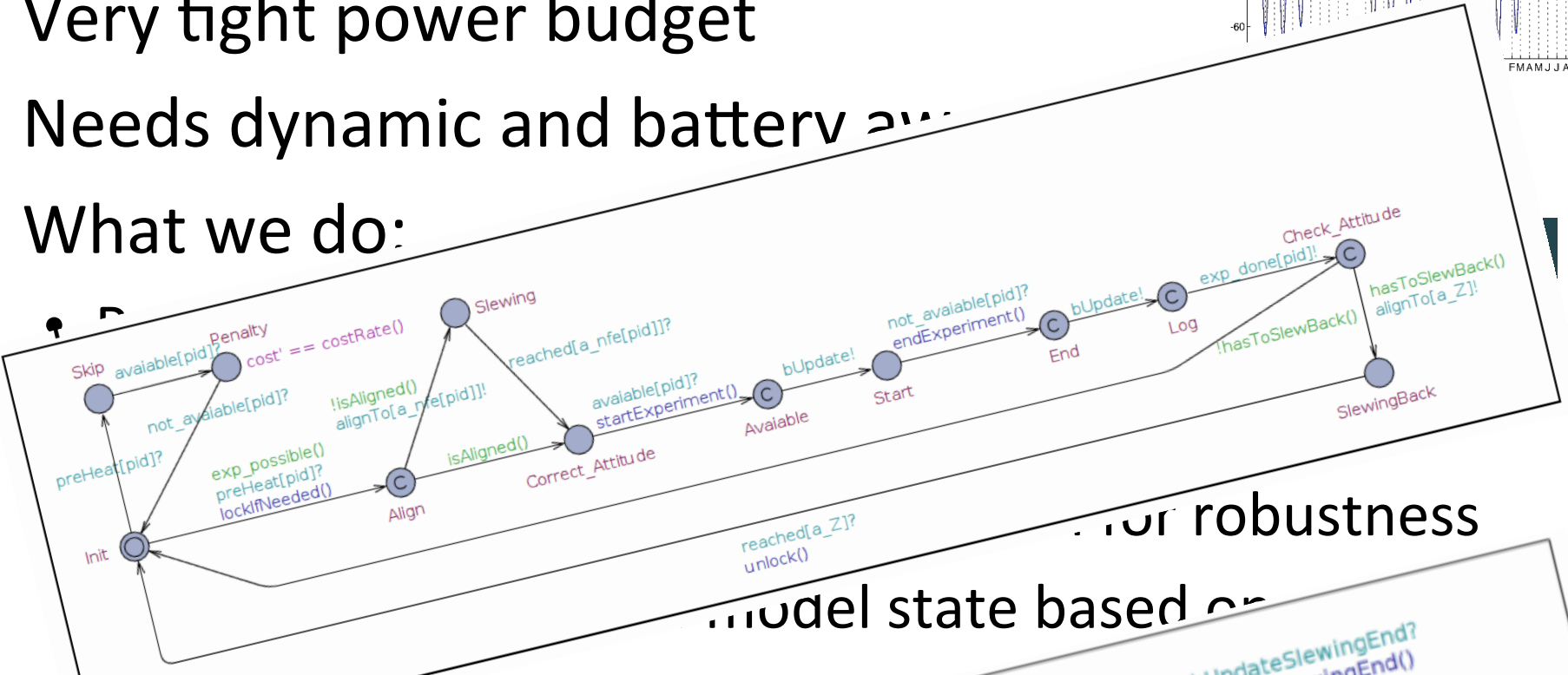
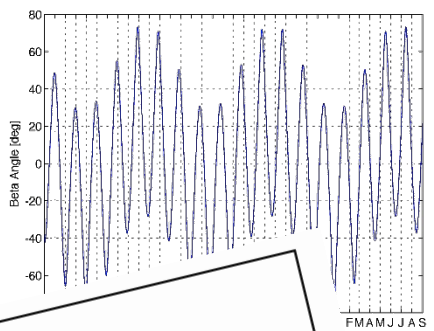


Even Orbit (92.8 min)



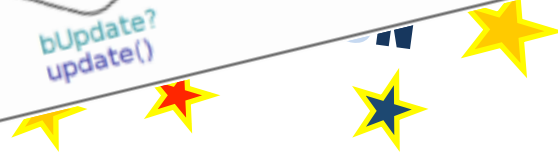
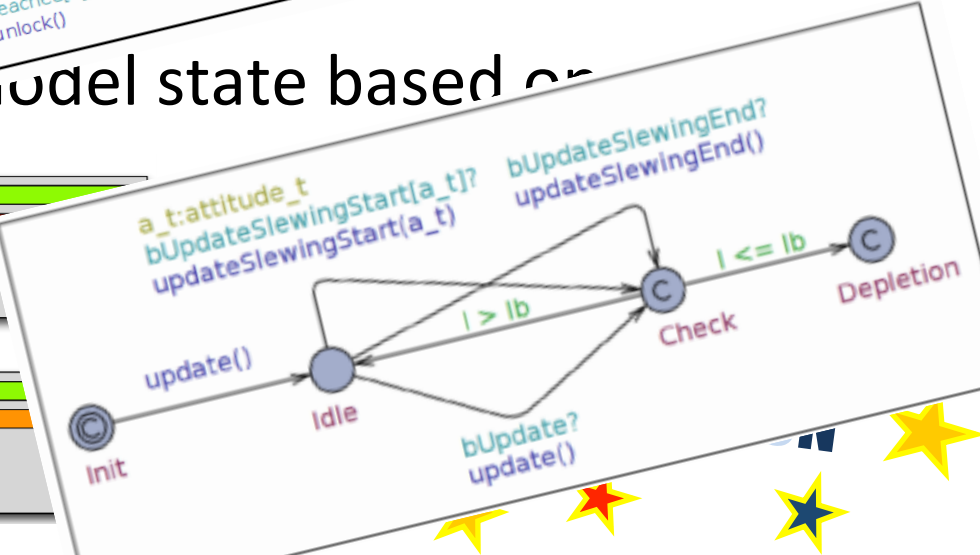
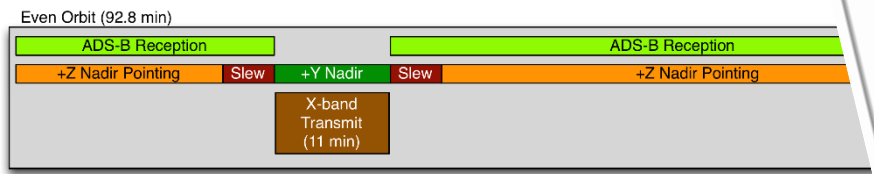
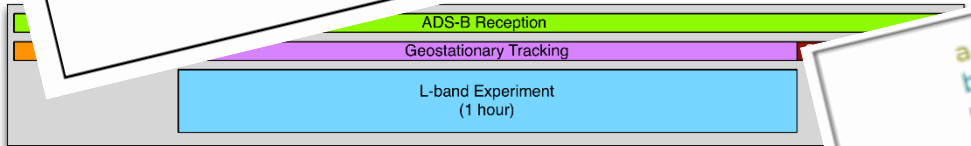
GOMX-3 mission planning

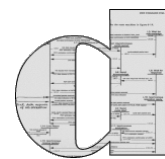
- Very tight power budget
- Needs dynamic and battery aware
- What we do:



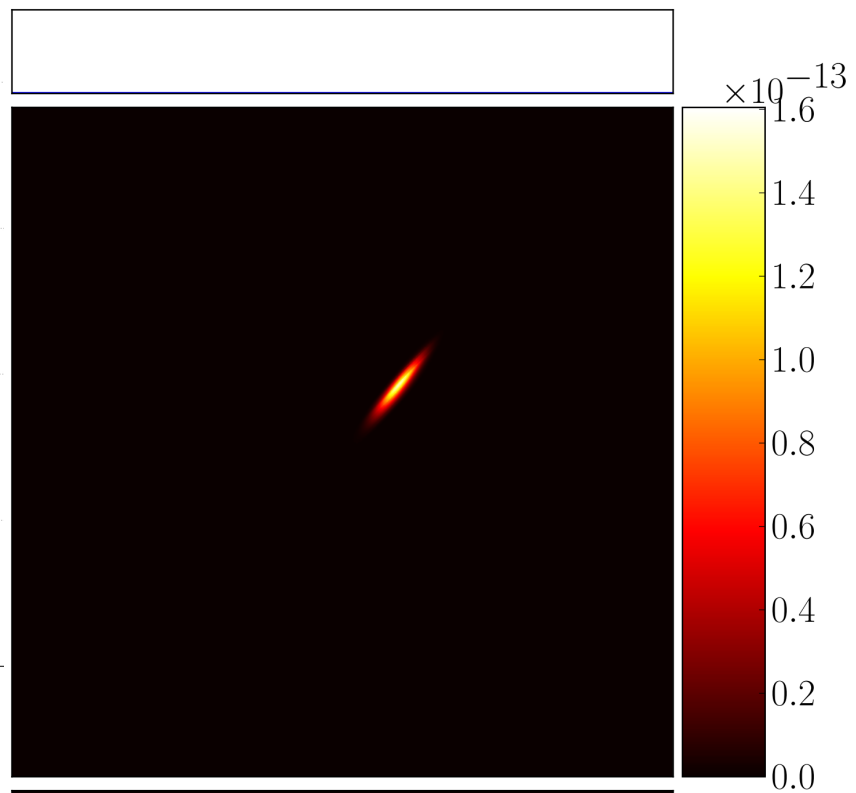
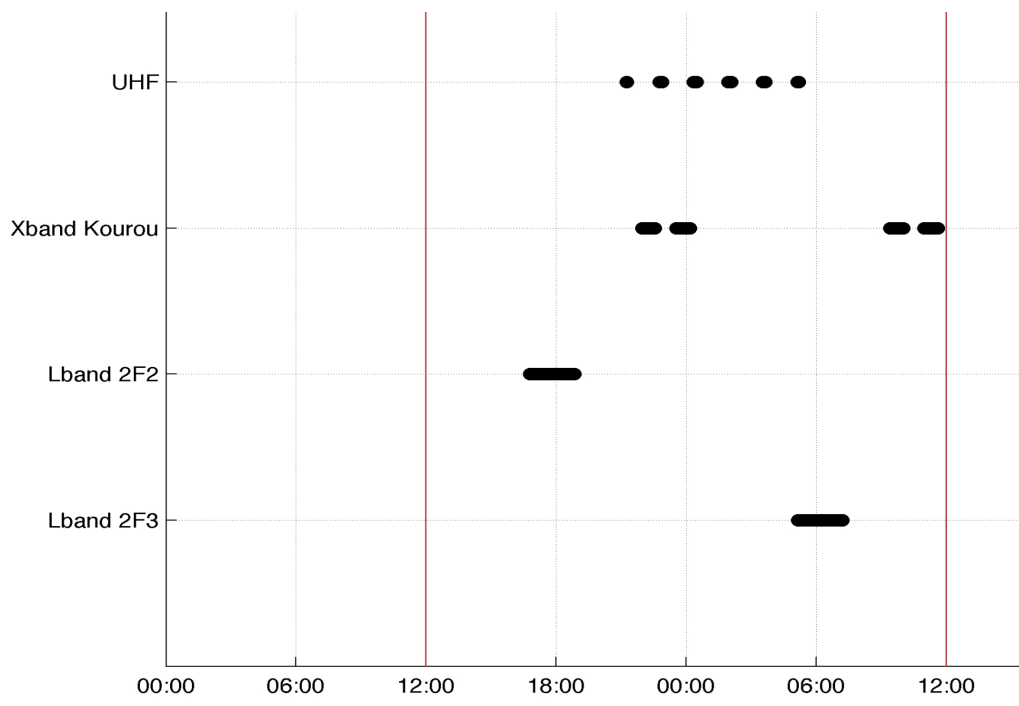
... for robustness

... model state based on





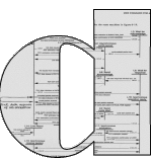
A one-day schedule



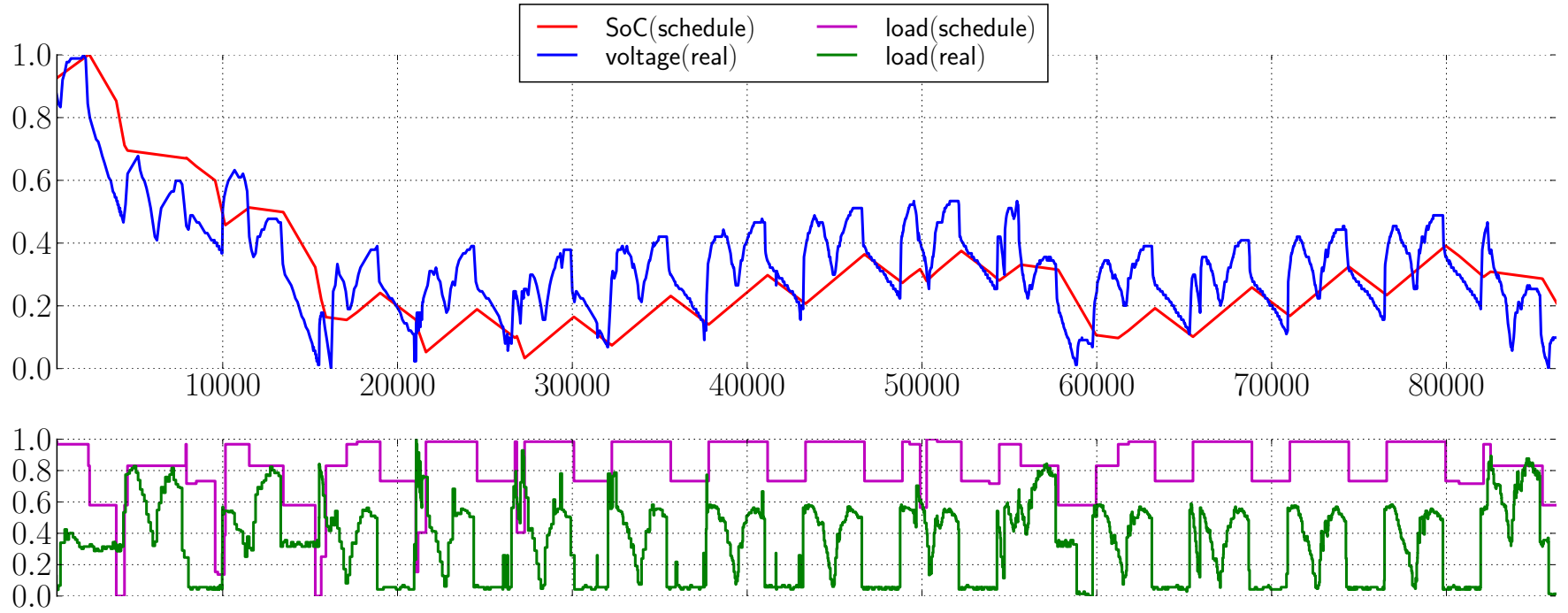
and its depletion risk

$6.81242244907e - 54$



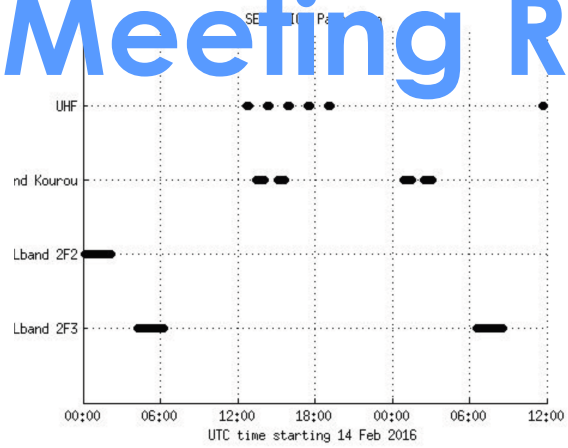


Meeting Reality, Safely



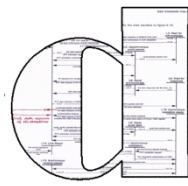


Meeting Reality



On-line and Compositional Learning of Controllers

with Application to Floor Heating



Kim G. Larsen, Marius Mikucionis,
Marco Muniz, Jiri Srba, Jakob H.
Taankvist

Aalborg University, DK



Cassting

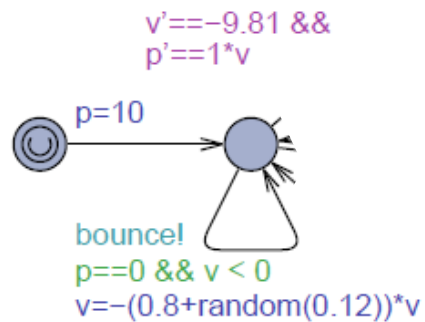


seluxit



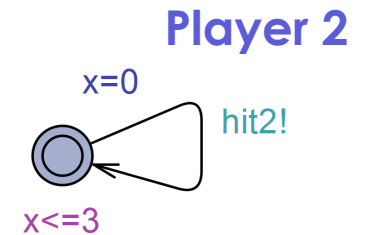
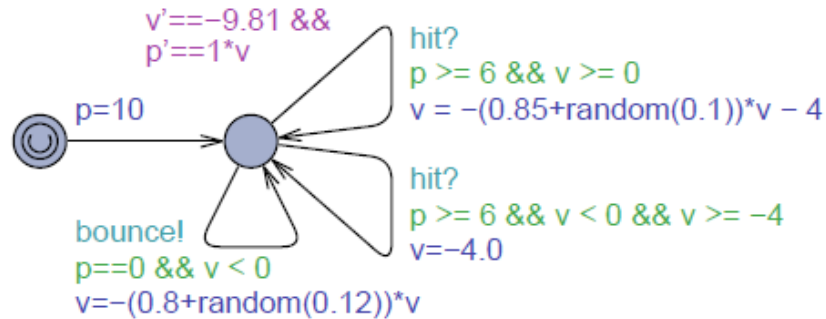
Stochastic Hybrid Systems

A Bouncing Ball



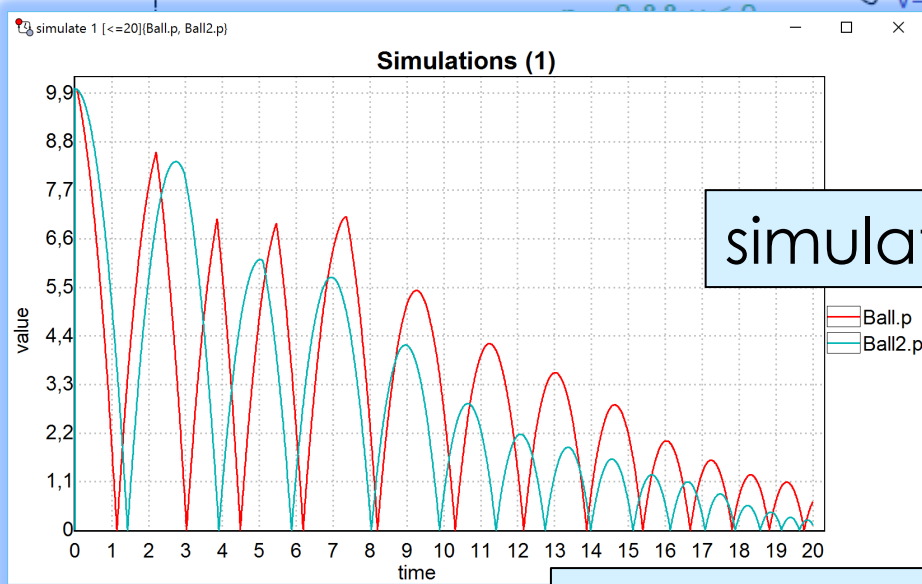
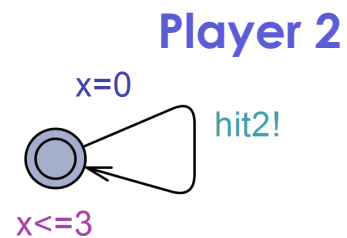
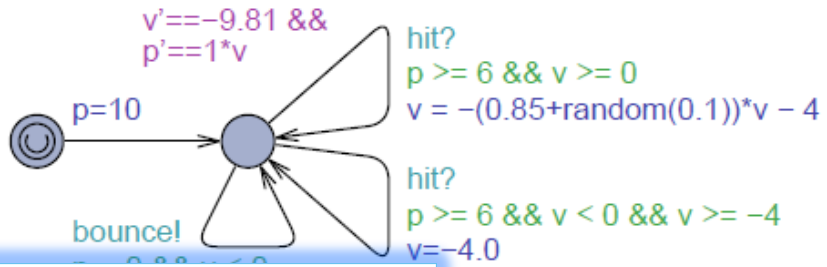
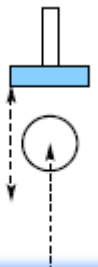
Stochastic Hybrid Systems

A Bouncing Ball



Stochastic Hybrid Systems

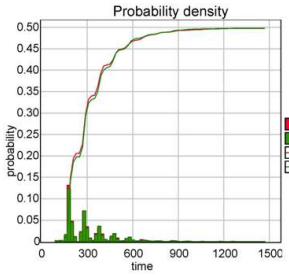
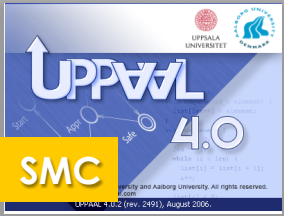
A Bouncing Ball



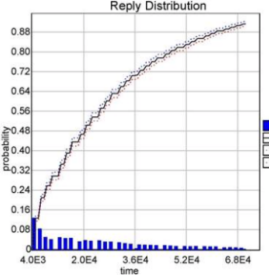
`simulate 1 [<=20] { Ball1.p, Ball2.p }`

$\Pr[\leq 20] (\langle \rangle (\text{time} \geq 12 \ \&\& \ \text{Ball1.p} > 4))$

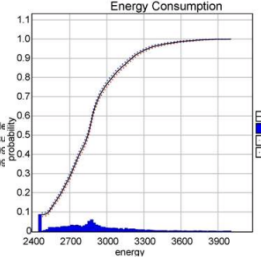
Other Applications



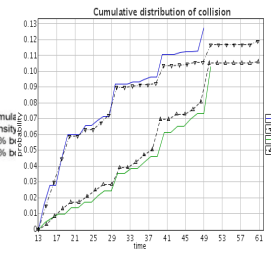
FIREWIRE



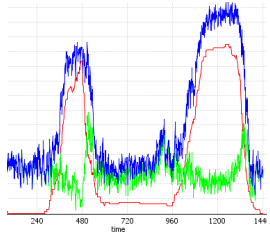
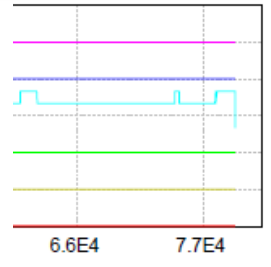
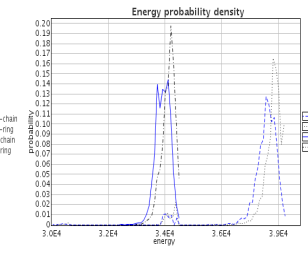
BLUETOOTH



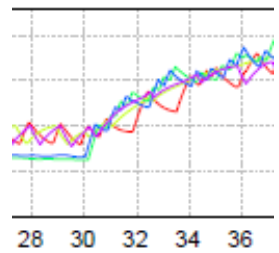
10 node LMAC



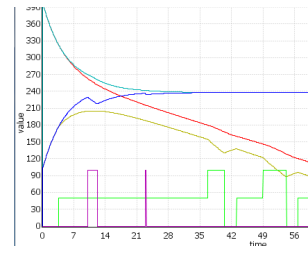
Schedulability Analysis for Mix Cr Sys



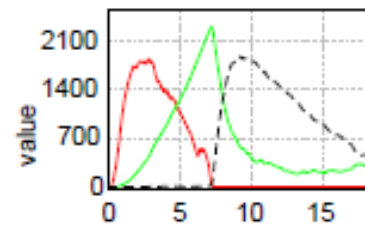
Smart Grid Demand / Response



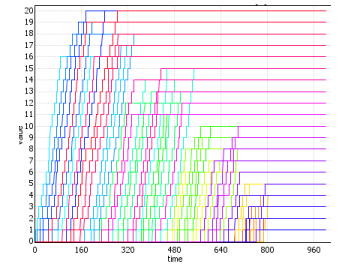
Energy Aware Buildings



Battery Scheduling



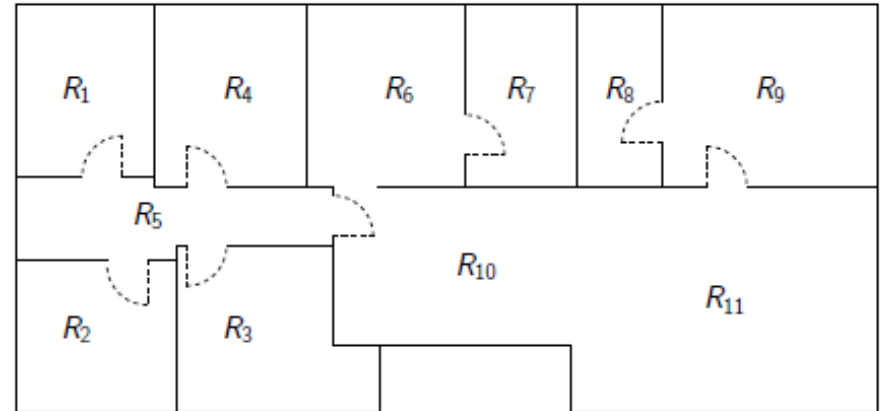
Genetic Oscillator (HBS)



Passenger Seating in Aircraft

Floor Heating Scenario

- Each room has a hot water loop that can be opened/closed
- Loops are controlled via activating / deactivating valves.
- Rooms equipped with wireless temperature sensors (report every 15 minutes).
- Each room has its user-defined target temperature.

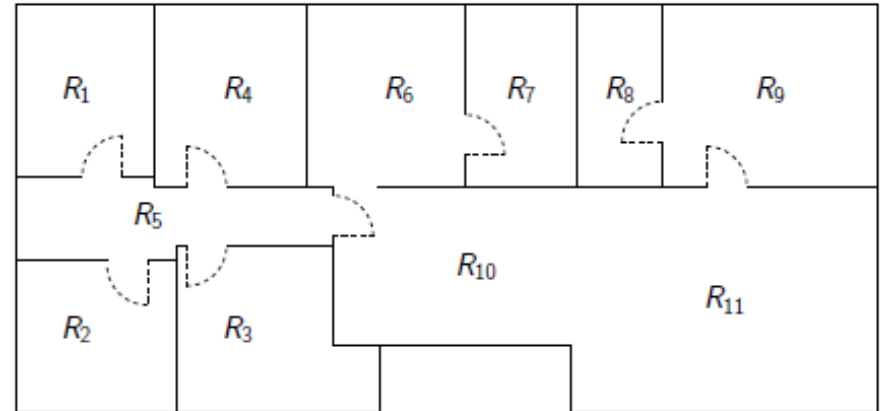


Control Task:

maintain room temperatures as close as possible to target temperatures

Additional Factors and Restrictions

- Heat exchange among the rooms (influenced by the door positions).
- Pipes are traversing under several rooms.
- Outside temperature and weather forecast.
- Capacity of the heating system.
- Temperature user-profiles for the different (groups of) rooms.

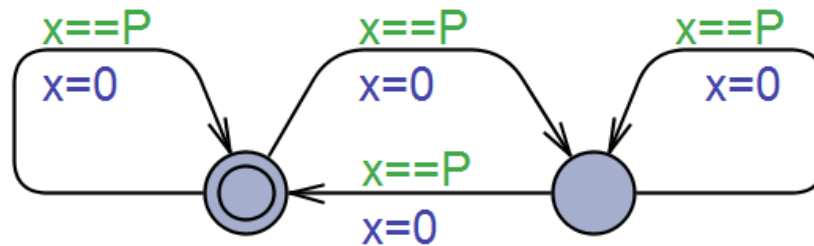


Control Task:

maintain room temperatures as close as possible to target temperatures

1-Room / 1-Window Game

Room



HeatOff
 $x \leq P \ \&\&$
 $T' = (T_e - T) * A$

HeatOn
 $x \leq P \ \&\&$
 $T' = (T_e - T) * A + H$

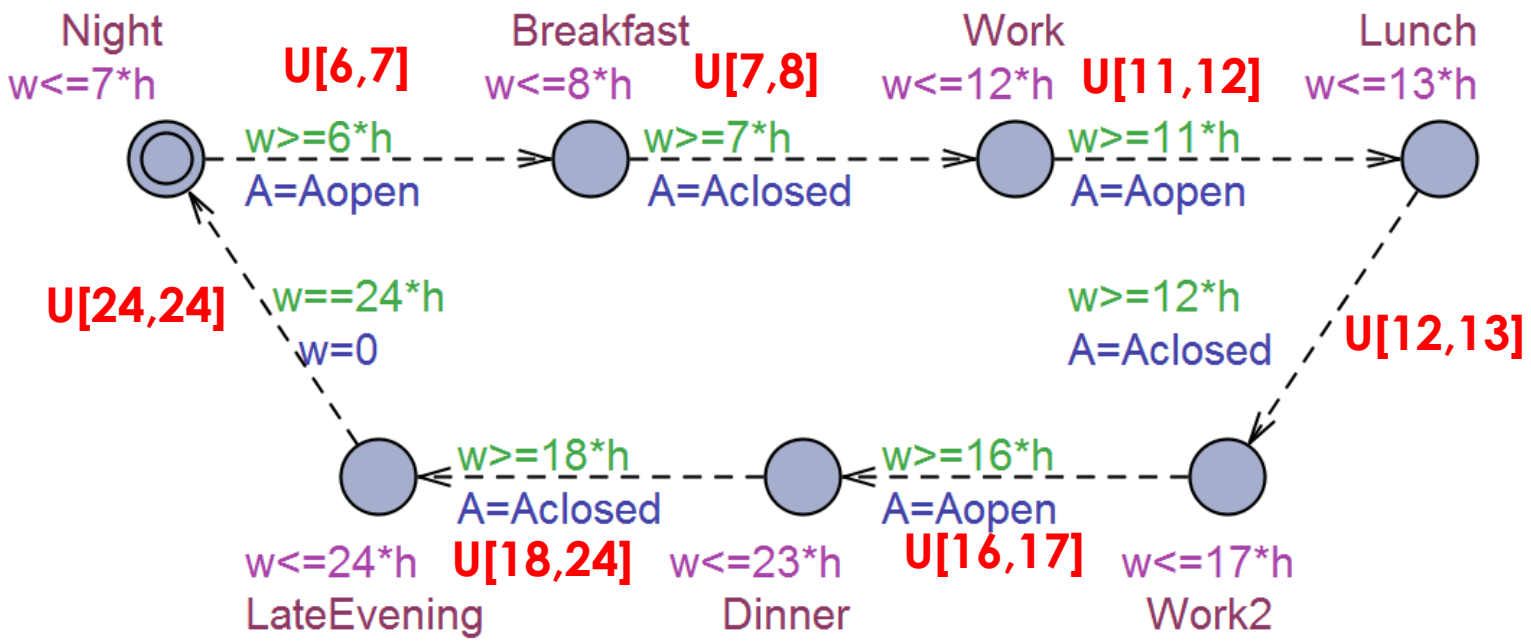
Monitor



$D' = (T_g - T) * (T_g - T)$

```
const double Tg = 21.0; // room temp. goal
const double Te = 15.0; // environment temp.
const double H = 0.04; // power of heater
const double Aclosed = 0.002; // heat loss when window closed
const double Aopen = 0.004; // heat loss when window open
const int P = 15; // heater switching period
const int h = 60; // 1 hour = 60 time units
```

1-Room / 1-Window Game

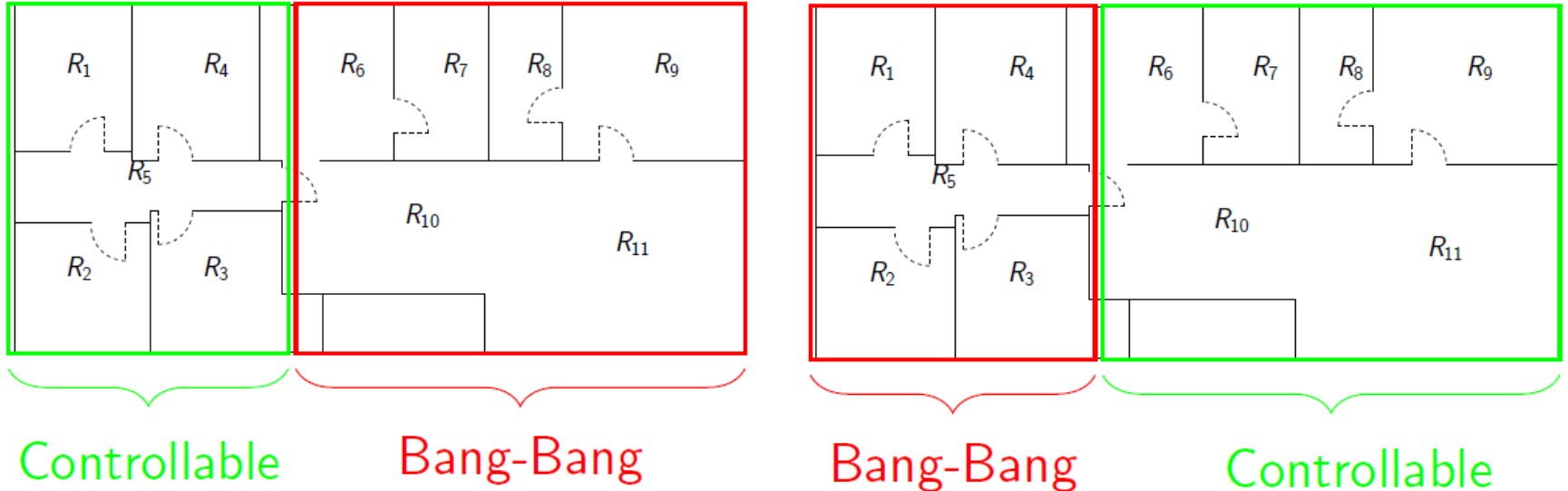


Window

Find strategy σ that minimizes **expectation** of

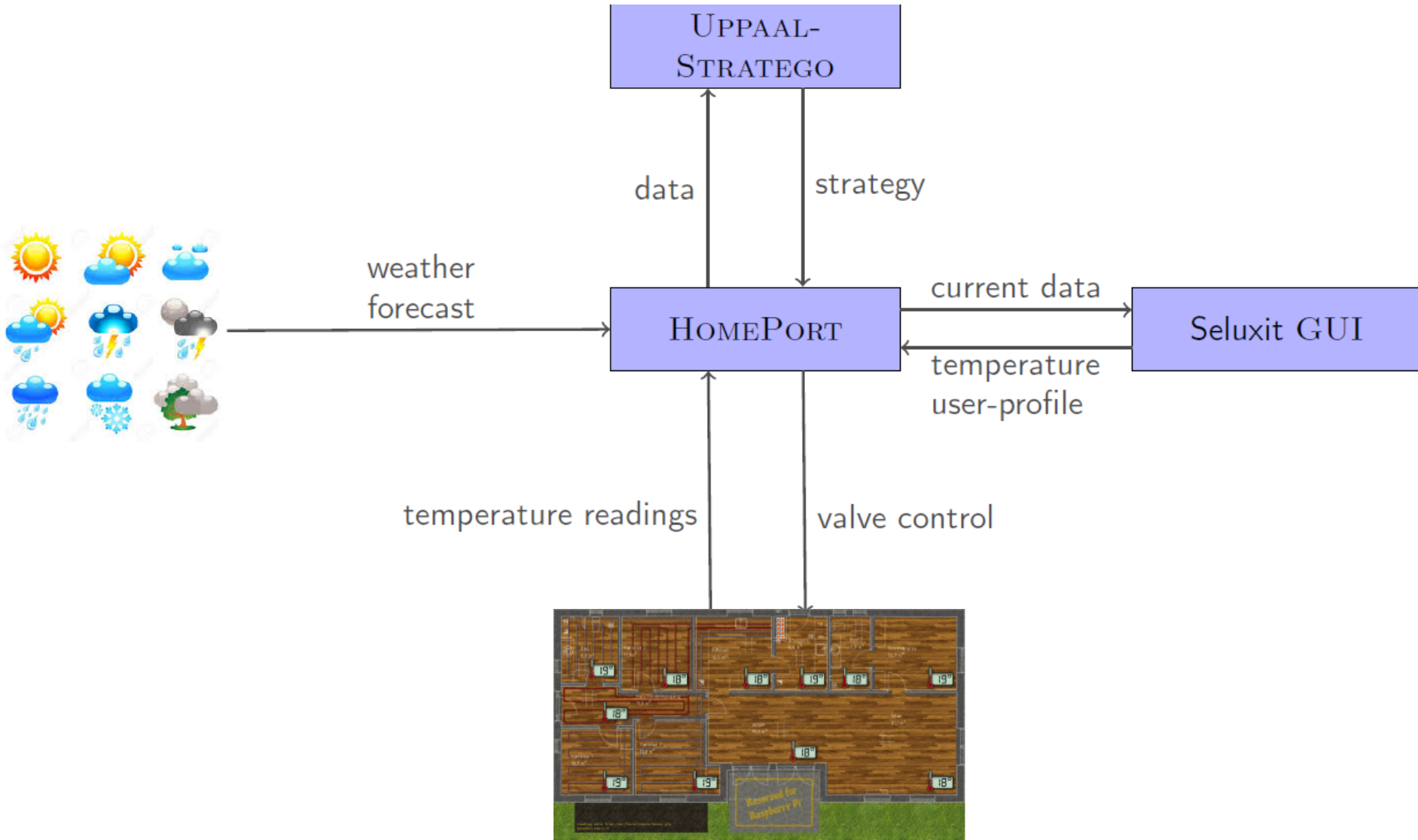
Compositional Synthesis

- Split the valves into controllable and fixed (controlled via Bang-Bang)
- Synthesize a strategy for controllable valves
- Swap the controllable and fixed valves and synthesise another strategy
- Merge strategies.

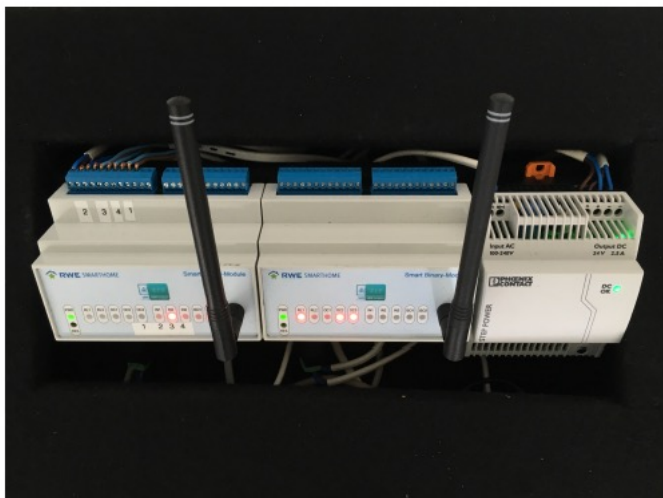
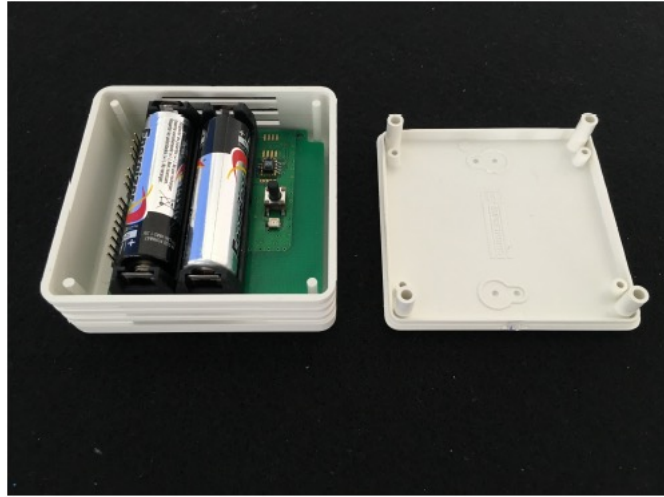


$(2^{15h} + 2^{16h})$ instead of 2^{11h} decision choices
 (in our case $h=3$)

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Latest News

3 day scenario

Weather	Distance			Energy		
	Bang-Bang	Stratego	imp.	Bang-Bang	Stratego	imp.
Aalborg	14583	8342	43%	14180	12626	10%
Anadyr	2385515	1483272	37%	23040	22475	2%
Ankara	17985	10464	41%	17468	15684	10%
Minneapolis	22052	12175	44%	18165	15882	12%
Murmansk	399421	187941	52%	22355	21011	6%

Weather	Distance			Energy		
	Bang-Bang	Stratego	imp.	Bang-Bang	Stratego	imp.
Aalborg	14583	8552	41%	14180	12590	11%
Anadyr	2385515	1503448	36%	23040	22371	2%
Ankara	17985	10511	41%	17468	15697	10%
Minneapolis	22052	12725	42%	18165	15837	12%
Murmansk	399421	191441	52%	22355	20923	6%

Evaluation of under modified parameters (0-20%)