

How do technical and scientific contributions of Foundation Models for robotics develop over time compared to those for language - a large-scale systematic analysis using LLMs

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Background



Over the last few years, Artificial Intelligence has increasingly shaped our daily lives in various tasks



Software Development



Content Creation



Autonomous Driving

Background



Foundation Models (FM) are a technological driver of that development, and have substantially enhanced Al's capabilities and broadened its range of application

Definition of Foundation Models

"Foundation Models are a type of Al technology that are trained on vast amounts of data that can be adapted to a wide range of

On the Opportunities and Risks of Foundation Models (Bommasani et. al., 2022)

tasks and operations"

Selected application domains of FMs

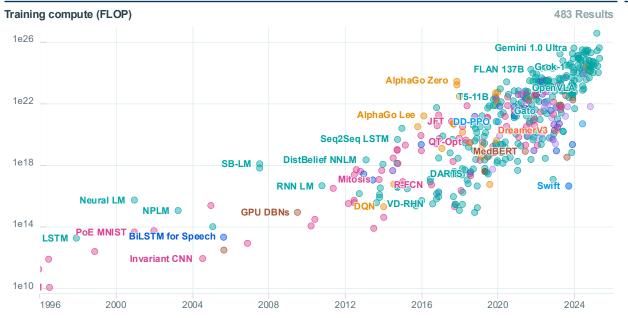
Radiology Music
Mathematics
Genomics CAD
Robotics Vision
Medicine Astronomy
Language Speech

Background



Epoch AI provides an overview of Foundation Model development trends including their different application domains

Notable Al Models Dataset



Epoch Al

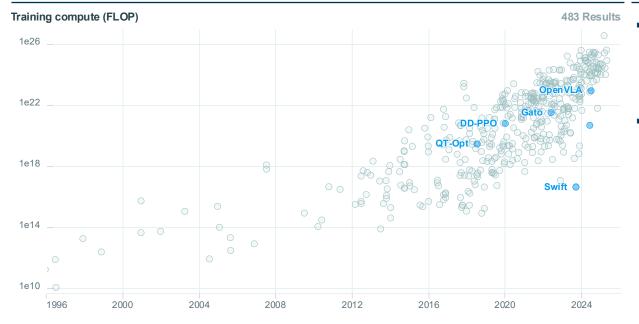
- Epoch AI is a multidisciplinary research institute investigating the trajectory of AI
- Their flagship dataset on notable AI models contains information on over 900 models that were state of the art or highly cited
- It tracks key factors driving machine learning progress and is created through manual paper review by the Epoch Al researchers

Research Gap



The extensive Epoch AI dataset does only include very few Foundation Models for Robotics and hence does not provide a holistic overview across all domains

Notable Al Models Dataset



Epoch Al

- The Epoch Al dataset also includes information on the application domain of the respective models
- For the robotics domain the dataset only includes 26 models in total, although there are over 400 publications matching a search query on "Foundation Model" and "Robotics" on ArXiv

Research Question



How do technical and scientific contributions of Foundation Models for robotics develop over time compared to those for language?

Objective

The objective is to create a comprehensive overview of robotics models and their characteristics - like the Epoch Al dataset - by developing a software tool, which automates the manual paper review and utilizes LLMs for the information retrieval process to extend the currently existing overviews

Research Questions

- 1. Are NLP tools able to extract relevant objective parameters from previously identified papers? What is the quality of the results from the automated solution compared to the Epoch Al dataset?
- What is the **status quo in FM development** for the specific field **of Robotics** and how do the models compare in their characteristics to other fields?
- 3. Are there **statistically relevant differences** between the robotics domain and other domains (such as language)?

Methodology



To structurally compare the different models, a standardized approach will be used to extract the following information from all publications

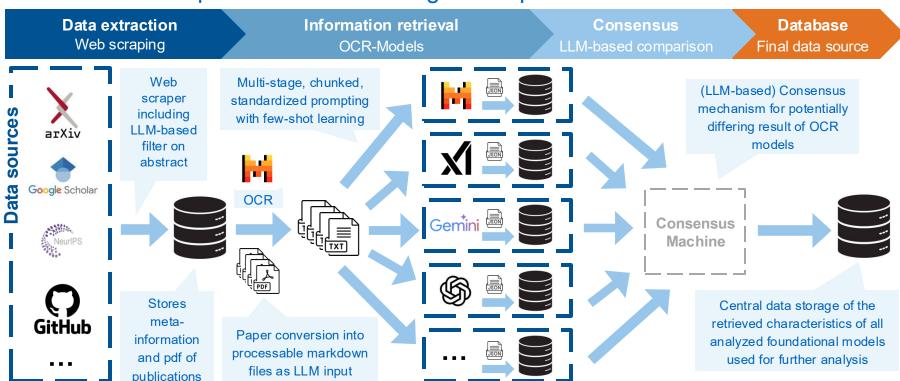
	•	
- Meta information —	- Model information	Training information •
Model name	Domain	Training dataset
Authors	Parameters	Training dataset size
Organization	Input modality	Epochs
Organization type	Output modality	Batch size
Organization country	Architecture	Training time
Citations	Base model	Training hardware
Publication date	Accessibility	Hardware quantity

As some publications might not always include all information, fields with only few datapoints might be neglected later if the extracted data does not allow for a reliable comparison.

Methodology



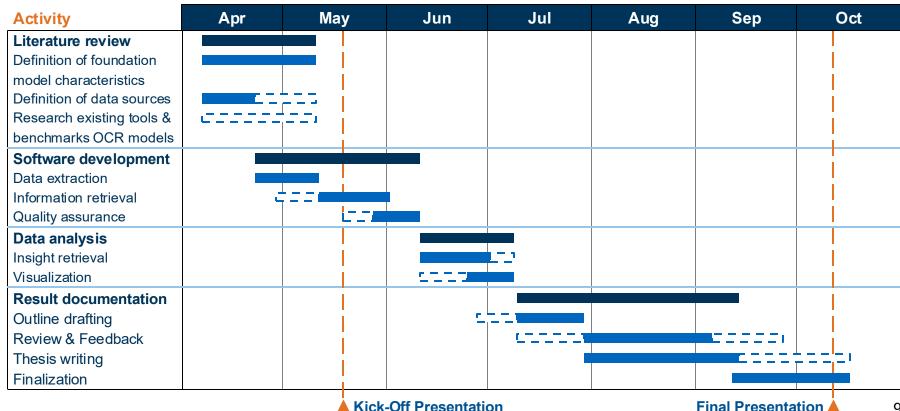
A LLM-based multilayer software tool will be developed for validated information retrieval from the publications describing the respective models



Timeline



Expected timeline for the master thesis





Q&A