



# Compiler Construction I

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SoSe 2019

Topic:

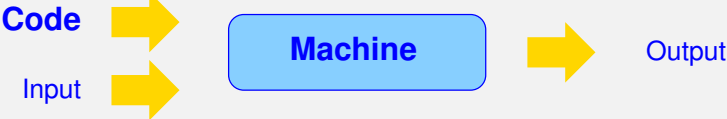
Introduction

# Extremes of Program Execution

## Interpretation:



## Compilation:



# Interpretation vs. Compilation

## Interpretation

- No precomputation on program text necessary
  - ⇒ no/small startup-overhead
- More context information allows for specific aggressive optimization

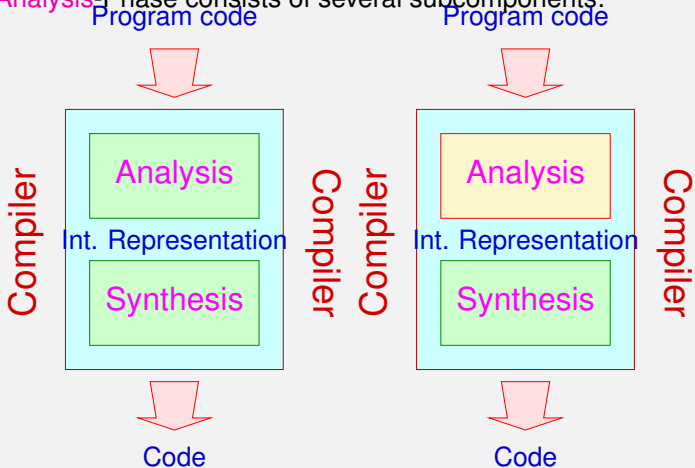
## Compilation

- Program components are analyzed once, during preprocessing, instead of multiple times during execution
  - ⇒ smaller runtime-overhead
- Runtime complexity of optimizations less important than in interpreter

# Compiler

general Compiler setup:

The **Analysis**-Phase consists of several subcomponents:

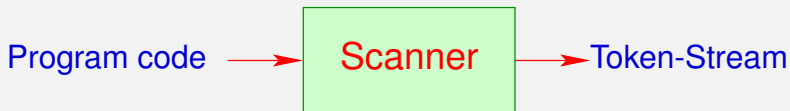


Program code

Topic:

Lexical Analysis

# The Lexical Analysis



- A **Token** is a sequence of characters, which together form a unit.
- Tokens are subsumed in **classes**. For example:
  - **Names (Identifiers)** e.g. `xyz`, `pi`, ...
  - **Constants** e.g. `42`, `3.14`, `"abc"`, ...
  - **Operators** e.g. `+`, ...
  - **Reserved terms** e.g. `if`, `int`, ...

# The Lexical Analysis - Siever

Classified tokens allow for further **pre-processing**:

- **Dropping** irrelevant fragments e.g. **Spacing**, **Comments**,...
- **Collecting Pragmas**, i.e. directives for the compiler, often implementation dependent, directed at the code generation process, e.g. **OpenMP**-Statements;
- **Replacing** of Tokens of particular classes with their meaning / internal representation, e.g.
  - **Constants**;
  - **Names**: typically managed centrally in a **Symbol**-table, maybe compared to reserved terms (if not already done by the scanner) and possibly replaced with an index or internal format (⇒ **Name Mangling**).



# The Lexical Analysis

## Discussion:

- Scanner and Siever are often combined into a single component, mostly by providing appropriate callback actions in the event that the scanner detects a token.
- Scanners are mostly not written manually, but **generated** from a specification.

Specification



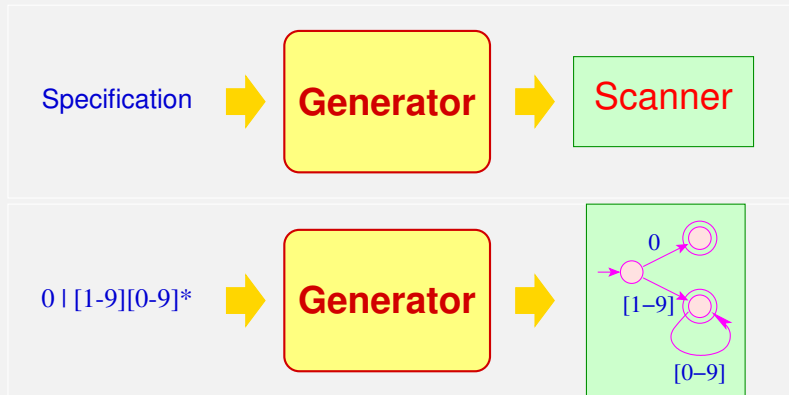
**Generator**



**Scanner**

# The Lexical Analysis - Generating:

... in our case:



Specification of Token-classes: Regular expressions;  
Generated Implementation: Finite automata + X

# Chapter 1: Basics: Regular Expressions

# Regular Expressions

## Basics

- Program code is composed from a finite **alphabet**  $\Sigma$  of input characters, e.g. Unicode
- The sets of textfragments of a token class is in general **regular**.
- Regular languages can be specified by **regular expressions**.

## Definition Regular Expressions

The set  $\mathcal{E}_\Sigma$  of (non-empty) **regular expressions** is the smallest set  $\mathcal{E}$  with:

- $\epsilon \in \mathcal{E}$  ( $\epsilon$  a new symbol not from  $\Sigma$ );
- $a \in \mathcal{E}$  for all  $a \in \Sigma$ ;
- $(e_1 \mid e_2), (e_1 \cdot e_2), e_1^* \in \mathcal{E}$  if  $e_1, e_2 \in \mathcal{E}$ .



Stephen Kleene

# Regular Expressions

... Example:

$$\begin{aligned} & ((a \cdot b^*) \cdot a) \\ & (a \mid b) \\ & ((a \cdot b) \cdot (a \cdot b)) \end{aligned}$$

**Attention:**

- We distinguish between characters  $a, 0, \$, \dots$  and **Meta-symbols**  $(, |, ), \dots$
- To avoid (ugly) parantheses, we make use of **Operator-Precedences:**

$$* > \cdot > |$$

and omit “.”

- Real Specification-languages offer additional constructs:

$$\begin{aligned} e? & \equiv (\epsilon \mid e) \\ e^+ & \equiv (e \cdot e^*) \end{aligned}$$

and omit “ $\epsilon$ ”

# Regular Expressions

Specification needs **Semantics**

...Example:

Specification	Semantics
$abab$	$\{abab\}$
$a \mid b$	$\{a, b\}$
$ab^*a$	$\{ab^n a \mid n \geq 0\}$

For  $e \in \mathcal{E}_\Sigma$  we define the specified language  $\llbracket e \rrbracket \subseteq \Sigma^*$  **inductively** by:

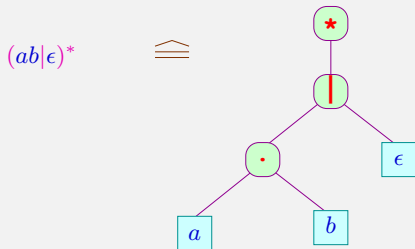
$$\begin{aligned}\llbracket \epsilon \rrbracket &= \{\epsilon\} \\ \llbracket a \rrbracket &= \{a\} \\ \llbracket e^* \rrbracket &= (\llbracket e \rrbracket)^* \\ \llbracket e_1 \mid e_2 \rrbracket &= \llbracket e_1 \rrbracket \cup \llbracket e_2 \rrbracket \\ \llbracket e_1 \cdot e_2 \rrbracket &= \llbracket e_1 \rrbracket \cdot \llbracket e_2 \rrbracket\end{aligned}$$

## Keep in Mind:

- The operators  $(\_)^*$ ,  $\cup$ ,  $\cdot$  are interpreted in the context of sets of words:

$$\begin{aligned}(L)^* &= \{w_1 \dots w_k \mid k \geq 0, w_i \in L\} \\ L_1 \cdot L_2 &= \{w_1 w_2 \mid w_1 \in L_1, w_2 \in L_2\}\end{aligned}$$

- Regular expressions are internally represented as **annotated ranked trees**:



**Inner nodes:** Operator-applications;

**Leaves:** particular symbols or  $\epsilon$ .

# Regular Expressions

## Example: Identifiers in Java:

le = [a-zA-Z\\_\\\$]

di = [0-9]

Id = {le} ({le} | {di})\*

Float = {di}\* (\\.{di}|{di}\\.){di}\* ((e|E) (\\+|\\-)?{di}+)?

## Remarks:

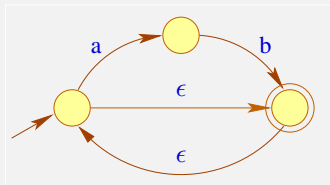
- “le” and “di” are **token classes**.
- **Defined Names** are enclosed in “{”, “}”.
- Symbols are distinguished from **Meta**-symbols via “\\”.



## Chapter 2: Basics: Finite Automata

# Finite Automata

## Example:



**Nodes:** States;

**Edges:** Transitions;

**Labels:** Consumed input;

# Finite Automata



Michael Rabin



Dana Scott

## Definition Finite Automata

A **non-deterministic** finite automaton (NFA) is a tuple  $A = (Q, \Sigma, \delta, I, F)$  with:

$Q$	a finite set of states;
$\Sigma$	a finite alphabet of inputs;
$I \subseteq Q$	the set of start states;
$F \subseteq Q$	the set of final states and
$\delta$	the set of transitions (-relation)

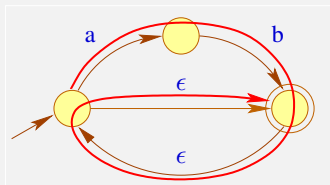
For an NFA, we reckon:

## Definition Deterministic Finite Automata

Given  $\delta : Q \times \Sigma \rightarrow Q$  a function and  $|I| = 1$ , then we call the NFA  $A$  **deterministic** (DFA).

# Finite Automata

- **Computations** are paths in the graph.
- **Accepting** computations lead from  $I$  to  $F$ .
- An **accepted word** is the sequence of labels along an accepting computation ...



# Finite Automata

Once again, more formally:

- We define the **transitive closure**  $\delta^*$  of  $\delta$  as the smallest set  $\delta'$  with:

$$\begin{aligned} (p, \epsilon, p) &\in \delta' && \text{and} \\ (p, xw, q) &\in \delta' && \text{if } (p, x, p_1) \in \delta \text{ and } (p_1, w, q) \in \delta'. \end{aligned}$$

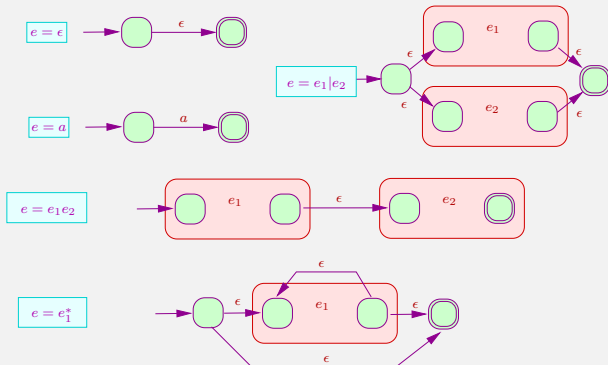
$\delta^*$  characterizes for a path between the states  $p$  and  $q$  the words obtained by concatenating the labels along it.

- The set of all accepting words, i.e.  $A$ 's **accepted language** can be described compactly as:

$$\mathcal{L}(A) = \{w \in \Sigma^* \mid \exists i \in I, f \in F : (i, w, f) \in \delta^*\}$$

## Chapter 3: Converting Regular Expressions to NFAs

# In Linear Time from Regular Expressions to NFAs



## Thompson's Algorithm

Produces  $\mathcal{O}(n)$  states for regular expressions of length  $n$ .



Ken Thompson

# A formal approach to Thompson's Algorithm



Gerard Berry Viktor S. Glushkov

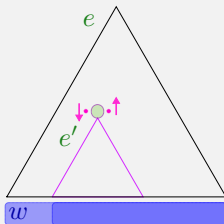
## Berry-Sethi Algorithm Glushkov Automaton

Produces exactly  $n + 1$  states without  $\epsilon$ -transitions  
and demonstrates  $\rightarrow$  *Equality Systems* and  $\rightarrow$  *Attribute Grammars*

### Idea:

An automaton covering the syntax tree of a regular expression  $e$  tracks (conceptionally via markers " $\bullet$ "), which subexpressions  $e'$  are reachable consuming the rest of input  $w$ .

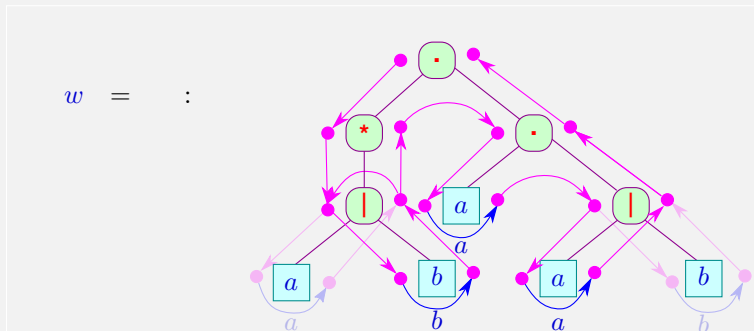
- markers contribute an entry or exit point into the automaton for this subexpression
- edges for each layer of subexpression are modelled after Thompson's automata





# Berry-Sethi Approach

... for example:



# Berry-Sethi Approach

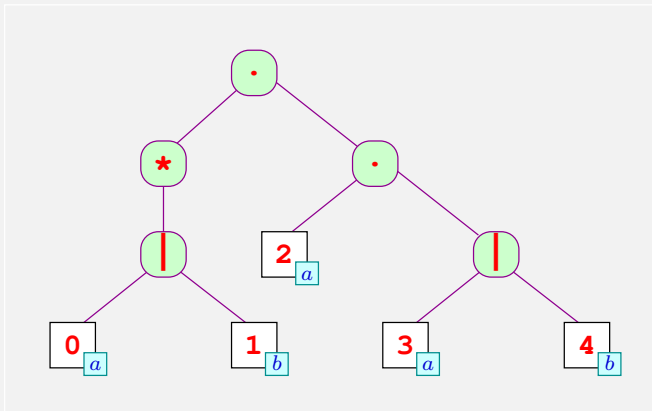
## In general:

- Input is only consumed at the leaves.
- Navigating the tree does not consume input  $\rightarrow$   $\epsilon$ -transitions
- For a formal construction we need **identifiers** for states.
- For a node **n**'s **identifier** we take the **subexpression**, corresponding to the subtree dominated by **n**.
- There are possibly **identical subexpressions** in one regular expression.

$\implies$  we enumerate the leaves ...

# Berry-Sethi Approach

... for example:



## Berry-Sethi Approach (naive version)

### Construction (naive version):

States:  $\bullet r, r \bullet$  with  $r$  nodes of  $e$ ;

Start state:  $\bullet e$ ;

Final state:  $e \bullet$ ;

Transitions: for leaves  $r \equiv \boxed{i \mid x}$  we require:  $(\bullet r, x, r \bullet)$ .

The leftover transitions are:

$r$	Transitions
$r_1 \mid r_2$	$(\bullet r, \epsilon, \bullet r_1)$ $(\bullet r, \epsilon, \bullet r_2)$ $(r_1 \bullet, \epsilon, r \bullet)$ $(r_2 \bullet, \epsilon, r \bullet)$
$r_1 \cdot r_2$	$(\bullet r, \epsilon, \bullet r_1)$ $(r_1 \bullet, \epsilon, \bullet r_2)$ $(r_2 \bullet, \epsilon, r \bullet)$

$r$	Transitions
$r_1^*$	$(\bullet r, \epsilon, r \bullet)$ $(\bullet r, \epsilon, \bullet r_1)$ $(r_1 \bullet, \epsilon, \bullet r_1)$ $(r_1 \bullet, \epsilon, r \bullet)$
$r_1?$	$(\bullet r, \epsilon, r \bullet)$ $(\bullet r, \epsilon, \bullet r_1)$ $(r_1 \bullet, \epsilon, r \bullet)$

# Berry-Sethi Approach

## Discussion:

- Most transitions navigate through the expression
- The resulting automaton is in general **nondeterministic**

⇒ **Strategy for the sophisticated version:**  
Avoid generating  $\epsilon$ -transitions

## Idea:

Pre-compute helper attributes during **D**(ePTH)**F**(IRST)**S**(EARCH)!

## Necessary node-attributes:

**first** the set of read states below  $r$ , which **may** be reached **first**, when descending into  $r$ .

**next** the set of read states, which **may** be reached **first** in the traversal **after**  $r$ .

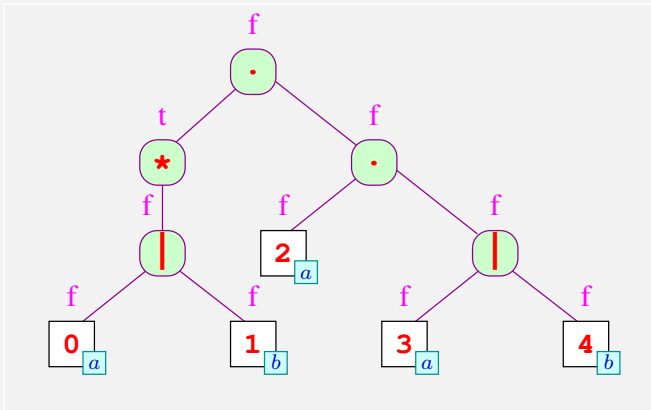
**last** the set of read states below  $r$ , which **may** be reached **last** when descending into  $r$ .

**empty** can the subexpression  $r$  consume  $\epsilon$  ?

## Berry-Sethi Approach: 1st step

$\text{empty}[r] = t$  if and only if  $\epsilon \in \llbracket r \rrbracket$

... for example:



## Berry-Sethi Approach: 1st step

### Implementation:

DFS **post-order** traversal

for leaves  $r \equiv \boxed{i \mid x}$  we find  $\text{empty}[r] = (x \equiv \epsilon)$ .

Otherwise:

$$\text{empty}[r_1 \mid r_2] = \text{empty}[r_1] \vee \text{empty}[r_2]$$

$$\text{empty}[r_1 \cdot r_2] = \text{empty}[r_1] \wedge \text{empty}[r_2]$$

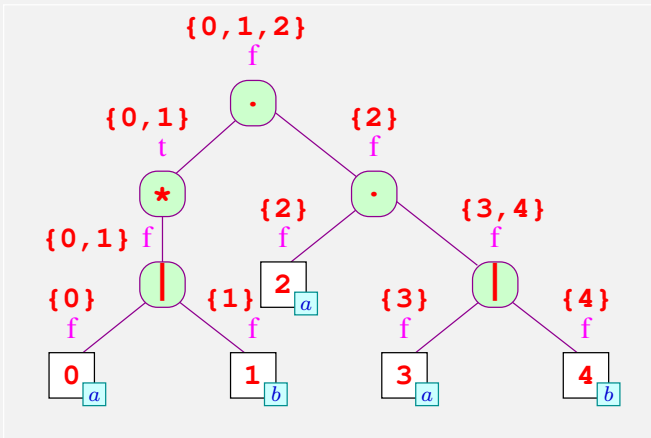
$$\text{empty}[r_1^*] = t$$

$$\text{empty}[r_1?] = t$$

## Berry-Sethi Approach: 2nd step

The **may-set** of **first reached read states**: The set of read states, that may be reached from  $\bullet r$  (i.e. while descending into  $r$ ) via sequences of  $\epsilon$ -transitions:  $\text{first}[r] = \{i \text{ in } r \mid (\bullet r, \epsilon, \bullet \boxed{i \mid x}) \in \delta^*, x \neq \epsilon\}$

... for example:





## Berry-Sethi Approach: 2nd step

### Implementation:

DFS *post-order* traversal

for leaves  $r \equiv \boxed{i \mid x}$  we find  $\text{first}[r] = \{i \mid x \neq \epsilon\}$ .

Otherwise:

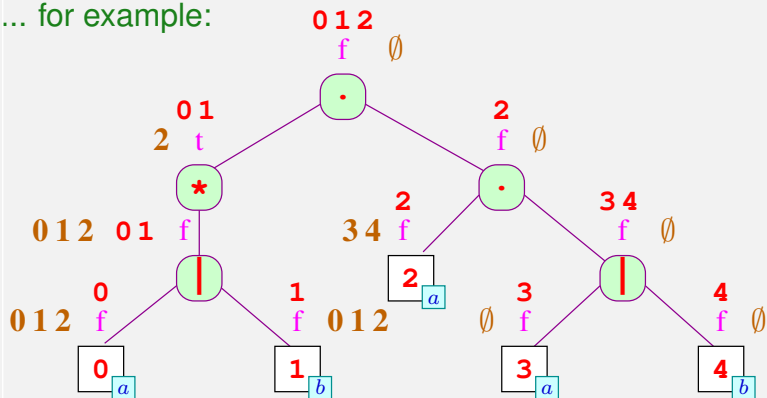
$$\begin{aligned} \text{first}[r_1 \mid r_2] &= \text{first}[r_1] \cup \text{first}[r_2] \\ \text{first}[r_1 \cdot r_2] &= \begin{cases} \text{first}[r_1] \cup \text{first}[r_2] \\ \text{first}[r_1] \end{cases} & \begin{array}{l} \text{if } \text{empty}[r_1] = t \\ \text{if } \text{empty}[r_1] = f \end{array} \\ \text{first}[r_1^*] &= \text{first}[r_1] \\ \text{first}[r_1?] &= \text{first}[r_1] \end{aligned}$$

## Berry-Sethi Approach: 3rd step

The **may-set** of **next read states**: The set of read states reached after reading  $r$ , that may be reached next via sequences of  $\epsilon$ -transitions.

$$\text{next}[r] = \{i \mid (r \bullet, \epsilon, \bullet \boxed{i} \boxed{x}) \in \delta^*, x \neq \epsilon\}$$

... for example:



## Berry-Sethi Approach: 3rd step

### Implementation:

DFS **pre-order** traversal

For the root, we find:  $\text{next}[e] = \emptyset$

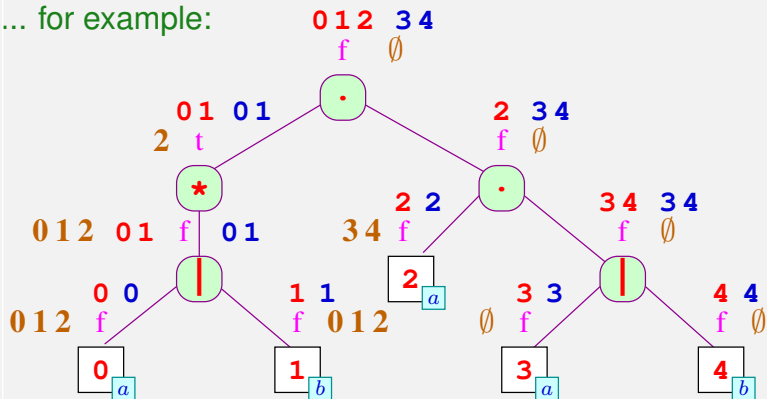
Apart from that we distinguish, based on the **context**:

$r$	Equalities
$r_1 \mid r_2$	$\text{next}[r_1] = \text{next}[r]$ $\text{next}[r_2] = \text{next}[r]$
$r_1 \cdot r_2$	$\text{next}[r_1] = \begin{cases} \text{first}[r_2] \cup \text{next}[r] & \text{if } \text{empty}[r_2] = t \\ \text{first}[r_2] & \text{if } \text{empty}[r_2] = f \end{cases}$ $\text{next}[r_2] = \text{next}[r]$
$r_1^*$	$\text{next}[r_1] = \text{first}[r_1] \cup \text{next}[r]$
$r_1?$	$\text{next}[r_1] = \text{next}[r]$

## Berry-Sethi Approach: 4th step

The **may-set** of **last reached read states**: The set of read states, which may be reached last during the traversal of  $r$  connected to the root via  $\epsilon$ -transitions only:  $\text{last}[r] = \{i \text{ in } r \mid (\boxed{i \ x} \bullet, \epsilon, r \bullet) \in \delta^*, x \neq \epsilon\}$

... for example:



## Berry-Sethi Approach: 4th step

### Implementation:

DFS **post-order** traversal

for leaves  $r \equiv \boxed{i \mid x}$  we find  $\text{last}[r] = \{i \mid x \neq \epsilon\}$ .

Otherwise:

$$\begin{aligned} \text{last}[r_1 \mid r_2] &= \text{last}[r_1] \cup \text{last}[r_2] \\ \text{last}[r_1 \cdot r_2] &= \begin{cases} \text{last}[r_1] \cup \text{last}[r_2] & \text{if } \text{empty}[r_2] = t \\ \text{last}[r_2] & \text{if } \text{empty}[r_2] = f \end{cases} \\ \text{last}[r_1^*] &= \text{last}[r_1] \\ \text{last}[r_1^?] &= \text{last}[r_1] \end{aligned}$$

## Berry-Sethi Approach: (sophisticated version)

### Construction (sophisticated version):

Create an automaton based on the syntax tree's new attributes:

States:  $\{\bullet e\} \cup \{i\bullet \mid i \text{ a leaf}\}$

Start state:  $\bullet e$

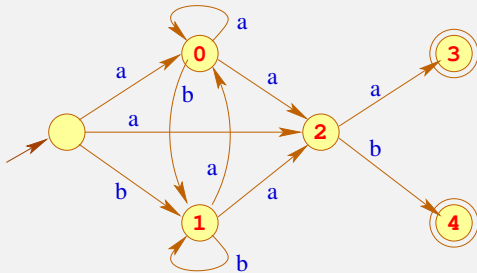
Final states:  $\text{last}[e]$  if  $\text{empty}[e] = f$   
 $\{\bullet e\} \cup \text{last}[e]$  otherwise

Transitions:  $(\bullet e, a, i\bullet)$  if  $i \in \text{first}[e]$  and  $i$  labeled with  $a$ .  
 $(i\bullet, a, i'\bullet)$  if  $i' \in \text{next}[i]$  and  $i'$  labeled with  $a$ .

We call the resulting automaton  $A_e$ .

# Berry-Sethi Approach

... for example:



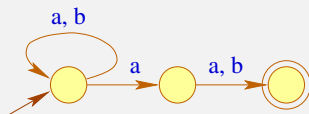
## Remarks:

- This construction is known as **Berry-Sethi-** or **Glushkov-**construction.
- It is used for **XML** to define **Content Models**
- The result may not be, what we had in mind...

# Chapter 4: Turning NFAs deterministic



The expected outcome:



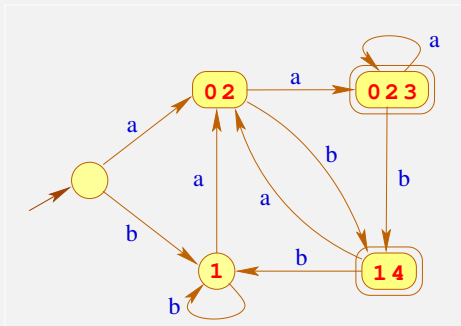
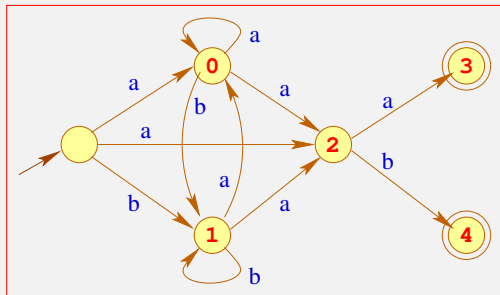
## Remarks:

- ideal automaton would be even more compact  
( $\rightarrow$  *Antimirov automata, Follow Automata*)
- but Berry-Sethi is rather directly constructed
- Anyway, we need a **deterministic** version

$\Rightarrow$  Powerset-Construction

# Powerset Construction

... for example:



# Powerset Construction

## Theorem:

For every non-deterministic automaton  $A = (Q, \Sigma, \delta, I, F)$  we can compute a deterministic automaton  $\mathcal{P}(A)$  with

$$\mathcal{L}(A) = \mathcal{L}(\mathcal{P}(A))$$

## Construction:

States: Powersets of  $Q$ ;

Start state:  $I$ ;

Final states:  $\{Q' \subseteq Q \mid Q' \cap F \neq \emptyset\}$ ;

Transitions:  $\delta_{\mathcal{P}}(Q', a) = \{q \in Q \mid \exists p \in Q' : (p, a, q) \in \delta\}$ .

# Powerset Construction

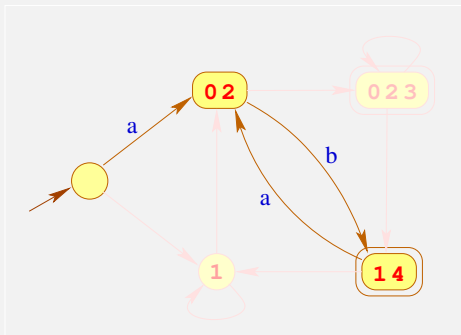
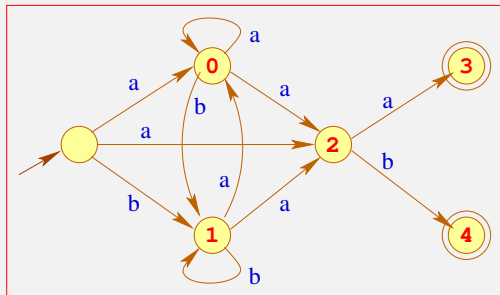
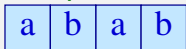
## Observation:

There are exponentially many powersets of  $Q$

- **Idea:** Consider only **contributing** powersets. Starting with the set  $Q_{\mathcal{P}} = \{I\}$  we only add further states **by need** ...
- i.e., whenever we can reach them from a state in  $Q_{\mathcal{P}}$
- However, the resulting automaton can become enormously **huge** ... which is (sort of) not happening in **practice**
- Therefore, in tools like **grep** a regular expression's **DFA** is never created!
- Instead, only the sets, directly necessary for interpreting the input are generated **while processing the input**

# Powerset Construction

... for example:



## Remarks:

- For an input sequence of length  $n$ , maximally  $O(n)$  sets are generated
- Once a set/edge of the DFA is generated, they are stored within a hash-table.
- Before generating a new transition, we check this table for already existing edges with the desired label.

## Summary:

### Theorem:

For each regular expression  $e$  we can compute a deterministic automaton  $A = \mathcal{P}(A_e)$  with

$$\mathcal{L}(A) = \llbracket e \rrbracket$$

# Chapter 5: Scanner design

# Scanner design

Input (simplified): a set of rules:

$$\begin{array}{ll} e_1 & \{ \text{action}_1 \} \\ e_2 & \{ \text{action}_2 \} \\ & \dots \\ e_k & \{ \text{action}_k \} \end{array}$$

Output: a program,

- ... reading a maximal prefix  $w$  from the input, that satisfies  $e_1 \mid \dots \mid e_k$ ;
- ... determining the minimal  $i$ , such that  $w \in \llbracket e_i \rrbracket$ ;
- ... executing  $\text{action}_i$  for  $w$ .



## Implementation:

### Idea:

- Create the DFA  $\mathcal{P}(A_e) = (Q, \Sigma, \delta, q_0, F)$  for the expression  $e = (e_1 \mid \dots \mid e_k)$ ;
- Define the sets:

$$F_1 = \{q \in F \mid q \cap \text{last}[e_1] \neq \emptyset\}$$

$$F_2 = \{q \in (F \setminus F_1) \mid q \cap \text{last}[e_2] \neq \emptyset\}$$

...

$$F_k = \{q \in (F \setminus (F_1 \cup \dots \cup F_{k-1})) \mid q \cap \text{last}[e_k] \neq \emptyset\}$$

- For input  $w$  we find:  $\delta^*(q_0, w) \in F_i$  iff the scanner must execute  $\text{action}_i$  for  $w$

## Implementation:

### Idea (cont'd):

- The scanner manages two pointers  $\langle A, B \rangle$  and the related states  $\langle q_A, q_B \rangle \dots$
- Pointer  $A$  points to the last position in the input, after which a state  $q_A \in F$  was reached;
- Pointer  $B$  tracks the current position.

s	t	d	o	u	t	.	w	r	i	t	e	l	n		(	"	H	a	l	l	o	"	)	;
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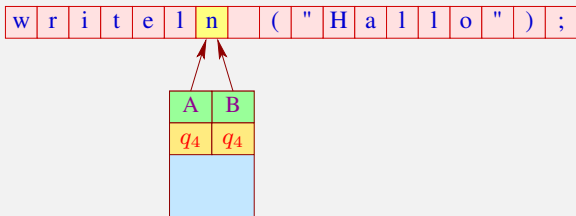


## Implementation:

### Idea (cont'd):

- The current state being  $q_B = \emptyset$ , we consume input up to position  $A$  and reset:

$$\begin{array}{ll} B & := A; & A & := \perp; \\ q_B & := q_0; & q_A & := \perp \end{array}$$



## Extension: States

- Now and then, it is handy to differentiate between particular **scanner states**.
- In different states, we want to recognize different token classes with different precedences.
- Depending on the consumed input, the scanner state can be changed

### Example: Comments

Within a comment, identifiers, constants, comments, ... are ignored

Input (generalized):

a set of rules:

```
<state> { e1 { action1 yybegin(state1); }  
          e2 { action2 yybegin(state2); }  
          ...  
          ek { actionk yybegin(statek); }  
        }
```

- The statement `yybegin (statei);` resets the current state to `statei.`
- The start state is called (e.g. `flex JFlex`) `YYINITIAL`.

... for example:

```
<YYINITIAL>    /*" { yybegin(COMMENT); }  
<COMMENT>     { " * /" { yybegin(YYINITIAL); }  
               . | \n { }  
               }
```

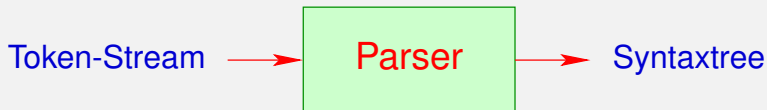
## Remarks:

- “.” matches all characters different from “\n”.
- For every state we generate the scanner respectively.
- Method `yybegin (STATE);` switches between different scanners.
- Comments might be directly implemented as (admittedly overly complex) token-class.
- Scanner-states are especially handy for implementing **preprocessors**, expanding special fragments in regular programs.

Topic:

Syntactic Analysis

# Syntactic Analysis

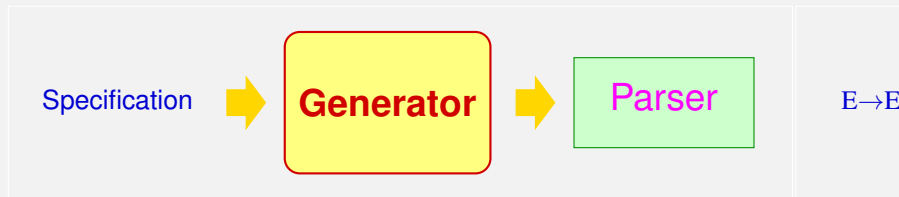


- Syntactic analysis tries to integrate Tokens into larger program units.
- Such units may possibly be:
  - Expressions;
  - Statements;
  - Conditional branches;
  - loops; ...



## Discussion:

In general, parsers are not developed by hand, but **generated** from a specification:



Specification of the hierarchical structure: contextfree grammars

Generated implementation: Pushdown automata + X

# Chapter 1: Basics of Contextfree Grammars

## Basics: Context-free Grammars

- Programs of programming languages can have arbitrary numbers of tokens, but only finitely many **Token-classes**.
- This is why we choose the set of **Token-classes** to be the finite alphabet of terminals  $T$ .
- The nested structure of program components can be described elegantly via **context-free** grammars...

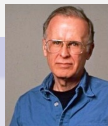
### Definition: Context-Free Grammar

A **context-free grammar** (CFG) is a 4-tuple  $G = (N, T, P, S)$  with:

- $N$  the set of **nonterminals**,
- $T$  the set of **terminals**,
- $P$  the set of **productions** or **rules**, and
- $S \in N$  the **start symbol**



Noam Chomsky



John Backus

## Conventions

The rules of context-free grammars take the following form:

$$A \rightarrow \alpha \quad \text{with} \quad A \in N, \quad \alpha \in (N \cup T)^*$$

... for example:

$$S \rightarrow a S b$$

$$S \rightarrow \epsilon$$

Specified language:  $\{a^n b^n \mid n \geq 0\}$

### Conventions:

In examples, we specify nonterminals and terminals in general implicitly:

- nonterminals are:  $A, B, C, \dots, \langle \text{exp} \rangle, \langle \text{stmt} \rangle, \dots;$
- terminals are:  $a, b, c, \dots, \text{int}, \text{name}, \dots;$

... a practical example:

```
 $S$        $\rightarrow$   $\langle \text{stmt} \rangle$   
 $\langle \text{stmt} \rangle$   $\rightarrow$   $\langle \text{if} \rangle$  |  $\langle \text{while} \rangle$  |  $\langle \text{rexp} \rangle$ ;  
 $\langle \text{if} \rangle$     $\rightarrow$   $\text{if} ( \langle \text{rexp} \rangle ) \langle \text{stmt} \rangle \text{ else } \langle \text{stmt} \rangle$   
 $\langle \text{while} \rangle$   $\rightarrow$   $\text{while} ( \langle \text{rexp} \rangle ) \langle \text{stmt} \rangle$   
 $\langle \text{rexp} \rangle$   $\rightarrow$   $\text{int}$  |  $\langle \text{lexp} \rangle$  |  $\langle \text{lexp} \rangle = \langle \text{rexp} \rangle$  | ...  
 $\langle \text{lexp} \rangle$   $\rightarrow$   $\text{name}$  | ...
```

### More conventions:

- For every nonterminal, we collect the right hand sides of rules and list them together.
- The  $j$ -th rule for  $A$  can be identified via the pair  $(A, j)$  (with  $j \geq 0$ ).

## Pair of grammars:

$E \rightarrow E+E^0$		$E * E^1$		$(E)^2$		name <sup>3</sup>		int <sup>4</sup>
-----------------------	--	-----------	--	---------	--	-------------------	--	------------------

$E \rightarrow E+T^0$		$T^1$						
$T \rightarrow T * F^0$		$F^1$						
$F \rightarrow (E)^0$		name <sup>1</sup>		int <sup>2</sup>				

$E \rightarrow E+E^0$		$E * E^1$		$(E)^2$		name <sup>3</sup>		int <sup>4</sup>
-----------------------	--	-----------	--	---------	--	-------------------	--	------------------

$E \rightarrow E+T^0$		$T^1$						
$T \rightarrow T * F^0$		$F^1$						
$F \rightarrow (E)^0$		name <sup>1</sup>		int <sup>2</sup>				

Both grammars describe the same language

## Derivation

Grammars are **term rewriting systems**. The rules offer feasible rewriting steps. A sequence of such rewriting steps  $\alpha_0 \rightarrow \dots \rightarrow \alpha_m$  is called **derivation**.

... for example:

$$\begin{aligned} \underline{E} &\rightarrow \underline{E} + T \\ &\rightarrow \underline{T} + T \\ &\rightarrow T * \underline{F} + T \\ &\rightarrow \underline{T} * \text{int} + T \\ &\rightarrow \underline{F} * \text{int} + T \\ &\rightarrow \text{name} * \text{int} + \underline{T} \\ &\rightarrow \text{name} * \text{int} + \underline{F} \\ &\rightarrow \text{name} * \text{int} + \text{int} \end{aligned}$$

### Definition

The rewriting relation  $\rightarrow$  is a relation on words over  $N \cup T$ , with

$$\alpha \rightarrow \alpha' \quad \text{iff} \quad \alpha = \alpha_1 A \alpha_2 \quad \wedge \quad \alpha' = \alpha_1 \beta \alpha_2 \quad \text{for an} \quad A \rightarrow \beta \in P$$

The **reflexive** and **transitive** closure of  $\rightarrow$  is denoted as:  $\rightarrow^*$

# Derivation

## Remarks:

- The relation  $\rightarrow$  depends on the grammar
- In each step of a derivation, we may choose:
  - \* a spot, determining **where** we will rewrite.
  - \* a rule, determining **how** we will rewrite.
- The language, specified by  $G$  is:

$$\mathcal{L}(G) = \{w \in T^* \mid S \rightarrow^* w\}$$

## Attention:

The order, in which disjunct fragments are rewritten is not relevant.

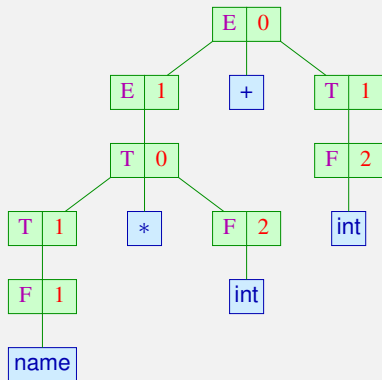


# Derivation Tree

Derivations of a symbol are represented as **derivation trees**:

... for example:

$\underline{E}$   $\rightarrow^0$   $\underline{E} + T$   
 $\rightarrow^1$   $\underline{T} + T$   
 $\rightarrow^0$   $\underline{T} * \underline{F} + T$   
 $\rightarrow^2$   $\underline{T} * \text{int} + T$   
 $\rightarrow^1$   $\underline{F} * \text{int} + T$   
 $\rightarrow^1$   $\text{name} * \text{int} + \underline{T}$   
 $\rightarrow^1$   $\text{name} * \text{int} + \underline{F}$   
 $\rightarrow^2$   $\text{name} * \text{int} + \text{int}$



A **derivation tree** for  $A \in N$ :

**inner nodes:** rule applications

**root:** rule application for  $A$

**leaves:** terminals or  $\epsilon$

The successors of  $(B, i)$  correspond to right hand sides of the rule

## Special Derivations

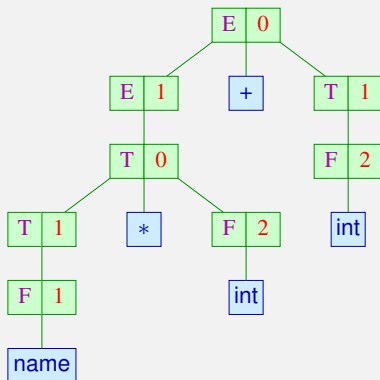
### Attention:

In contrast to arbitrary derivations, we find special ones, always rewriting the **leftmost** (or rather **rightmost**) occurrence of a nonterminal.

- These are called **leftmost** (or rather **rightmost**) derivations and are denoted with the index  $L$  (or  $R$  respectively).
- Leftmost (or rightmost) derivations correspond to a left-to-right (or right-to-left) **preorder**-DFS-traversal of the derivation tree.
- **Reverse** rightmost derivations correspond to a left-to-right **postorder**-DFS-traversal of the derivation tree

# Special Derivations

... for example:



**Leftmost** derivation:

$(E, 0) (E, 1) (T, 0) (T, 1) (F, 1) (F, 2) (T, 1) (F, 2)$

**Rightmost** derivation:

$(E, 0) (T, 1) (F, 2) (E, 1) (T, 0) (F, 2) (T, 1) (F, 1)$

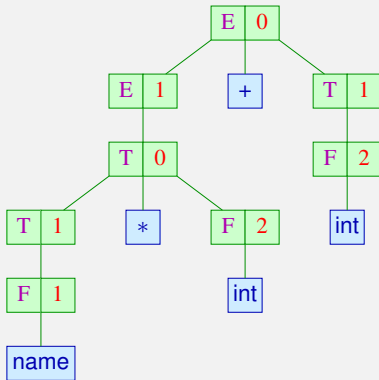
**Reverse rightmost** derivation:

$(F, 1) (T, 1) (F, 2) (T, 0) (E, 1) (F, 2) (T, 1) (E, 0)$

# Unique Grammars

The concatenation of leaves of a derivation tree  $t$  are often called  $\text{yield}(t)$ .

... for example:



gives rise to the concatenation:

`name * int + int .`

# Unique Grammars

## Definition:

Grammar  $G$  is called **unique**, if for every  $w \in T^*$  there is maximally one derivation tree  $t$  of  $G$  with  $\text{yield}(t) = w$ .

... in our example:

$E \rightarrow E + E^0$	$E * E^1$	$(E)^2$	$\text{name}^3$	$\text{int}^4$
$E \rightarrow E + T^0$	$T^1$			
$T \rightarrow T * F^0$	$F^1$			
$F \rightarrow (E)^0$	$\text{name}^1$	$\text{int}^2$		

The first one is ambiguous, the second one is unique

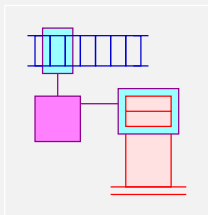
## Conclusion:

- A derivation tree represents a possible hierarchical structure of a word.
- For programming languages, only those grammars with a unique structure are of interest.
- Derivation trees are one-to-one corresponding with leftmost derivations as well as (reverse) rightmost derivations.
- **Leftmost derivations** correspond to a **top-down** reconstruction of the syntax tree.
- **Reverse rightmost derivations** correspond to a **bottom-up** reconstruction of the syntax tree.

## Chapter 2: Basics of Pushdown Automata

## Basics of Pushdown Automata

Languages, specified by context free grammars are accepted by  
**Pushdown Automata:**



The pushdown is used e.g. to verify correct nesting of braces.



## Example:

**States:** 0, 1, 2

**Start state:** 0

**Final states:** 0, 2

0	<i>a</i>	11
1	<i>a</i>	11
11	<i>b</i>	2
12	<i>b</i>	2

### Conventions:

- We do **not** differentiate between pushdown symbols and states
- The rightmost / upper pushdown symbol represents the state
- Every transition consumes / modifies the upper part of the pushdown

## Definition: Pushdown Automaton

A pushdown automaton (PDA) is a tuple  $M = (Q, T, \delta, q_0, F)$  with:

- $Q$  a finite set of states;
- $T$  an input alphabet;
- $q_0 \in Q$  the start state;
- $F \subseteq Q$  the set of final states and
- $\delta \subseteq Q^+ \times (T \cup \{\epsilon\}) \times Q^*$  a finite set of transitions



Friedrich Bauer



Klaus Samelson

We define **computations** of pushdown automata with the help of transitions; a particular **computation state** (the current **configuration**) is a pair:

$$(\gamma, w) \in Q^* \times T^*$$

consisting of the **pushdown content** and the **remaining input**.

... for example:

**States:** 0, 1, 2  
**Start state:** 0  
**Final states:** 0, 2

0	a	11
1	a	11
11	b	2
12	b	2

$(0, a a a b b b) \vdash (11, a a b b b)$   
 $\vdash (111, a b b b)$   
 $\vdash (1111, b b b)$   
 $\vdash (112, b b)$   
 $\vdash (12, b)$   
 $\vdash (2, \epsilon)$

A computation step is characterized by the relation  $\vdash \subseteq (Q^* \times T^*)^2$  with

$$(\alpha\gamma, xw) \vdash (\alpha\gamma', w) \quad \text{for} \quad (\gamma, x, \gamma') \in \delta$$

## Remarks:

- The relation  $\vdash$  depends on the pushdown automaton  $M$
- The reflexive and transitive closure of  $\vdash$  is denoted by  $\vdash^*$
- Then, the language accepted by  $M$  is

$$\mathcal{L}(M) = \{w \in T^* \mid \exists f \in F : (q_0, w) \vdash^* (f, \epsilon)\}$$

We accept with a **final state** together with **empty input**.

## Definition: Deterministic Pushdown Automaton

The pushdown automaton  $M$  is **deterministic**, if every configuration has maximally one successor configuration.

This is exactly the case if for distinct transitions

$(\gamma_1, x, \gamma_2), (\gamma'_1, x', \gamma'_2) \in \delta$  we can assume:

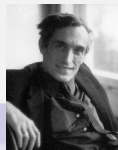
Is  $\gamma_1$  a suffix of  $\gamma'_1$ , then  $x \neq x' \wedge x \neq \epsilon \neq x'$  is valid.

... for example:

0	$a$	11
1	$a$	11
11	$b$	2
12	$b$	2

... this obviously holds

# Pushdown Automata



M. Schützenberger



A. Öttinger

## Theorem:

For each context free grammar  $G = (N, T, P, S)$  a pushdown automaton  $M$  with  $\mathcal{L}(G) = \mathcal{L}(M)$  can be built.

The theorem is so important for us, that we take a look at **two** constructions for automata, motivated by both of the special derivations:

- $M_G^L$  to build **Leftmost derivations**
- $M_G^R$  to build **reverse Rightmost derivations**

## Chapter 3: Top-down Parsing

# Item Pushdown Automaton

Construction: Item Pushdown Automaton  $M_G^L$

- Reconstruct a **Leftmost derivation**.
- Expand nonterminals using a rule.
- Verify successively, that the chosen rule matches the input.

⇒ The states are now **Items** (= rules with a **bullet**):

$$[A \rightarrow \alpha \bullet \beta], \quad A \rightarrow \alpha \beta \in P$$

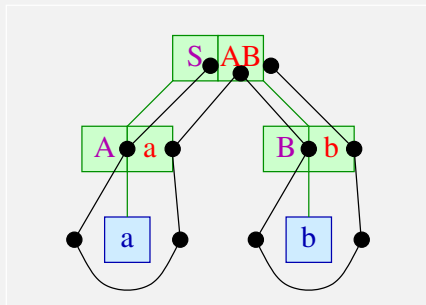
The bullet marks the spot, how far the rule is already processed



# Item Pushdown Automaton – Example

Our example:

$S \rightarrow AB$      $A \rightarrow a$      $B \rightarrow b$



## Item Pushdown Automaton – Example

We add another rule  $S' \rightarrow S \$$  for initialising the construction:

**Start state:**  $[S' \rightarrow \bullet S \$]$

**End state:**  $[S' \rightarrow S \bullet \$]$

**Transition relations:**

$[S' \rightarrow \bullet S \$]$	$\epsilon$	$[S' \rightarrow \bullet S \$] [S \rightarrow \bullet A B]$
$[S \rightarrow \bullet A B]$	$\epsilon$	$[S \rightarrow \bullet A B] [A \rightarrow \bullet a]$
$[A \rightarrow \bullet a]$	$a$	$[A \rightarrow a \bullet]$
$[S \rightarrow \bullet A B] [A \rightarrow a \bullet]$	$\epsilon$	$[S \rightarrow A \bullet B]$
$[S \rightarrow A \bullet B]$	$\epsilon$	$[S \rightarrow A \bullet B] [B \rightarrow \bullet b]$
$[B \rightarrow \bullet b]$	$b$	$[B \rightarrow b \bullet]$
$[S \rightarrow A \bullet B] [B \rightarrow b \bullet]$	$\epsilon$	$[S \rightarrow A B \bullet]$
$[S' \rightarrow \bullet S \$] [S \rightarrow A B \bullet]$	$\epsilon$	$[S' \rightarrow S \bullet \$]$

# Item Pushdown Automaton

The item pushdown automaton  $M_G^L$  has three kinds of transitions:

**Expansions:**  $([A \rightarrow \alpha \bullet B \beta], \epsilon, [A \rightarrow \alpha \bullet B \beta] [B \rightarrow \bullet \gamma])$  for  
 $A \rightarrow \alpha B \beta, B \rightarrow \gamma \in P$

**Shifts:**  $([A \rightarrow \alpha \bullet a \beta], a, [A \rightarrow \alpha a \bullet \beta])$  for  $A \rightarrow \alpha a \beta \in P$

**Reduces:**  $([A \rightarrow \alpha \bullet B \beta] [B \rightarrow \gamma \bullet], \epsilon, [A \rightarrow \alpha B \bullet \beta])$  for  
 $A \rightarrow \alpha B \beta, B \rightarrow \gamma \in P$

Items of the form:  $[A \rightarrow \alpha \bullet]$  are also called **complete**

The item pushdown automaton shifts the bullet around the derivation tree ...

# Item Pushdown Automaton

## Discussion:

- The **expansions** of a computation form a **leftmost derivation**
- Unfortunately, the expansions are chosen **nondeterministically**
- For proving correctness of the construction, we show that for every item  $[A \rightarrow \alpha \bullet B \beta]$  the following holds:

$$([A \rightarrow \alpha \bullet B \beta], w) \vdash^* ([A \rightarrow \alpha B \bullet \beta], \epsilon) \quad \text{iff} \quad B \rightarrow^* w$$

- **LL-Parsing** is based on the item pushdown automaton and tries to make the expansions deterministic ...

# Item Pushdown Automaton

Example:  $S' \rightarrow S \$$      $S \rightarrow \epsilon \mid a S b$

The transitions of the according Item Pushdown Automaton:

0	$[S' \rightarrow \bullet S \$]$	$\epsilon$	$[S' \rightarrow \bullet S \$] [S \rightarrow \bullet]$
1	$[S' \rightarrow \bullet S \$]$	$\epsilon$	$[S' \rightarrow \bullet S \$] [S \rightarrow \bullet a S b]$
2	$[S \rightarrow \bullet a S b]$	$a$	$[S \rightarrow a \bullet S b]$
3	$[S \rightarrow a \bullet S b]$	$\epsilon$	$[S \rightarrow a \bullet S b] [S \rightarrow \bullet]$
4	$[S \rightarrow a \bullet S b]$	$\epsilon$	$[S \rightarrow a \bullet S b] [S \rightarrow \bullet a S b]$
5	$[S \rightarrow a \bullet S b] [S \rightarrow \bullet]$	$\epsilon$	$[S \rightarrow a S \bullet b]$
6	$[S \rightarrow a \bullet S b] [S \rightarrow a S b \bullet]$	$\epsilon$	$[S \rightarrow a S \bullet b]$
7	$[S \rightarrow a S \bullet b]$	$b$	$[S \rightarrow a S b \bullet]$
8	$[S' \rightarrow \bullet S \$] [S \rightarrow \bullet]$	$\epsilon$	$[S' \rightarrow S \bullet \$]$
9	$[S' \rightarrow \bullet S \$] [S \rightarrow a S b \bullet]$	$\epsilon$	$[S' \rightarrow S \bullet \$]$

Conflicts arise between the transitions (0, 1) and (3, 4), resp..

# Topdown Parsing

## Problem:

Conflicts between the transitions prohibit an implementation of the item pushdown automaton as deterministic pushdown automaton.

## Idea 1: GLL Parsing

For each conflict, we create a virtual copy of the complete stack and continue deriving in parallel.

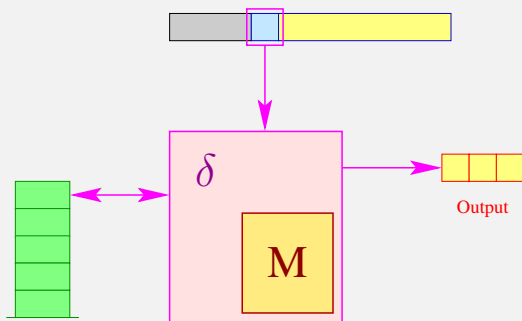
## Idea 2: Recursive Descent & Backtracking

Depth-first search for an appropriate derivation.

## Idea 3: Recursive Descent & Lookahead

Conflicts are resolved by considering a lookup of the next input symbol.

## Structure of the $LL(1)$ -Parser:



- The parser accesses a frame of length 1 of the input;
- it corresponds to an item pushdown automaton, essentially;
- table  $M[q, w]$  contains the rule of choice.

# Topdown Parsing

## Idea:

- Emanate from the item pushdown automaton
- Consider **the next input symbol** to determine the appropriate rule for the next expansion
- A grammar is called  **$LL(1)$**  if a unique choice is always possible

## Definition:

A reduced grammar is called  **$LL(1)$** , if for each two distinct rules  $A \rightarrow \alpha$ ,  $A \rightarrow \alpha' \in P$  and each derivation  $S \xrightarrow{*}_L u A \beta$  with  $u \in T^*$  the following is valid:

$$\text{First}_1(\alpha \beta) \cap \text{First}_1(\alpha' \beta) = \emptyset$$



Philip Lewis



Richard Stearns



# Topdown Parsing

## Example 1:

$S \rightarrow$  if (  $E$  )  $S$  else  $S$  |  
while (  $E$  )  $S$  |  
 $E$  ;  
 $E \rightarrow$  id

is  $LL(1)$ , since  $First_1(E) = \{id\}$

## Example 2:

$S \rightarrow$  if (  $E$  )  $S$  else  $S$  |  
if (  $E$  )  $S$  |  
while (  $E$  )  $S$  |  
 $E$  ;  
 $E \rightarrow$  id

... is not  $LL(k)$  for any  $k > 0$ .

# Lookahead Sets

## Definition: $\text{First}_1$ -Sets

For a set  $L \subseteq T^*$  we define:

$$\text{First}_1(L) = \{\epsilon \mid \epsilon \in L\} \cup \{u \in T \mid \exists v \in T^* : uv \in L\}$$

Example:  $S \rightarrow \epsilon \mid aSb$

$\text{First}_1(S)$
$\epsilon$
$ab$
$abbb$
$abbbb$
$\dots$

$\equiv$  the yield's prefix of length 1

# Lookahead Sets

## Arithmetics:

$\text{First}_1(\_)$  is **distributive** with union and concatenation:

$$\begin{aligned}\text{First}_1(\emptyset) &= \emptyset \\ \text{First}_1(L_1 \cup L_2) &= \text{First}_1(L_1) \cup \text{First}_1(L_2) \\ \text{First}_1(L_1 \cdot L_2) &= \text{First}_1(\text{First}_1(L_1) \cdot \text{First}_1(L_2)) \\ &:= \text{First}_1(L_1) \odot_1 \text{First}_1(L_2)\end{aligned}$$

$\odot_1$  being 1 – concatenation

### Definition: 1-concatenation

Let  $L_1, L_2 \subseteq T \cup \{\epsilon\}$  with  $L_1 \neq \emptyset \neq L_2$ . Then:

$$L_1 \odot_1 L_2 = \begin{cases} L_1 & \text{if } \epsilon \notin L_1 \\ (L_1 \setminus \{\epsilon\}) \cup L_2 & \text{otherwise} \end{cases}$$

If all rules of  $G$  are productive, then all sets  $\text{First}_1(A)$  are non-empty.

## Lookahead Sets

For  $\alpha \in (N \cup T)^*$  we are interested in the set:

$$\text{First}_1(\alpha) = \text{First}_1(\{w \in T^* \mid \alpha \rightarrow^* w\})$$

**Idea:** Treat  $\epsilon$  separately:  $\text{First}_1(A) = F_\epsilon(A) \cup \{\epsilon \mid A \rightarrow^* \epsilon\}$

- Let  $\text{empty}(X) = \text{true}$  iff  $X \rightarrow^* \epsilon$ .
- $F_\epsilon(X_1 \dots X_m) = \bigcup_{i=1}^j F_\epsilon(X_i)$  if  $\bigwedge_{i=1}^{j-1} \text{empty}(X_i) \wedge \neg \text{empty}(X_j)$

We characterize the  $\epsilon$ -free  $\text{First}_1$ -sets with an inequality system:

$$\begin{aligned} F_\epsilon(a) &= \{a\} & \text{if } a \in T \\ F_\epsilon(A) &\supseteq F_\epsilon(X_j) & \text{if } A \rightarrow X_1 \dots X_m \in P, \\ & & \bigwedge_{i=1}^{j-1} \text{empty}(X_i) \end{aligned}$$

# Lookahead Sets

for example...

$$\begin{aligned} E &\rightarrow E + T^0 \mid T^1 \\ T &\rightarrow T * F^0 \mid F^1 \\ F &\rightarrow ( E )^0 \mid \text{name}^1 \mid \text{int}^2 \end{aligned}$$

with  $\text{empty}(E) = \text{empty}(T) = \text{empty}(F) = \text{false}$

... we obtain:

$$\begin{aligned} F_\epsilon(S') &\supseteq F_\epsilon(E) & F_\epsilon(E) &\supseteq F_\epsilon(E) \\ F_\epsilon(E) &\supseteq F_\epsilon(T) & F_\epsilon(T) &\supseteq F_\epsilon(T) \\ F_\epsilon(T) &\supseteq F_\epsilon(F) & F_\epsilon(F) &\supseteq \{ (, \text{name}, \text{int} \} \end{aligned}$$

# Fast Computation of Lookahead Sets

## Observation:

- The form of each inequality of these systems is:

$$x \supseteq y \quad \text{resp.} \quad x \supseteq d$$

for variables  $x, y$  und  $d \in \mathbb{D}$ .

- Such systems are called **pure unification problems**
- Such problems can be solved in **linear** space/time.

for example:  $\mathbb{D} = 2^{\{a,b,c\}}$

$$x_0 \supseteq \{a\}$$

$$x_1 \supseteq \{b\}$$

$$x_2 \supseteq \{c\}$$

$$x_3 \supseteq \{c\}$$

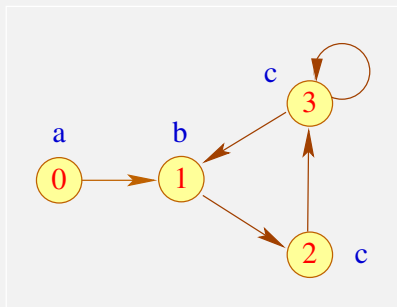
$$x_1 \supseteq x_0$$

$$x_2 \supseteq x_1$$

$$x_3 \supseteq x_2$$

$$x_1 \supseteq x_3$$

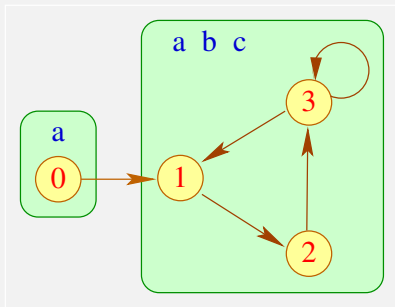
$$x_3 \supseteq x_3$$



# Fast Computation of Lookahead Sets



Frank DeRemer  
& Tom Pennello



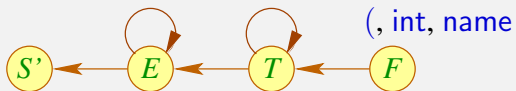
## Proceeding:

- Create the **Variable Dependency Graph** for the inequality system.
- Whithin a **Strongly Connected Component** ( $\rightarrow$  Tarjan) all variables have the same value
- Is there no ingoing edge for an SCC, its value is computed via the smallest upper bound of all values within the SCC
- In case of ingoing edges, their values are also to be considered for the upper bound

# Fast Computation of Lookahead Sets

... for our example grammar:

$\text{First}_1$  :





# Item Pushdown Automaton as LL(1)-Parser

back to the example:  $S' \rightarrow S \$$      $S \rightarrow \epsilon \mid a S b$

The transitions in the according Item Pushdown Automaton:

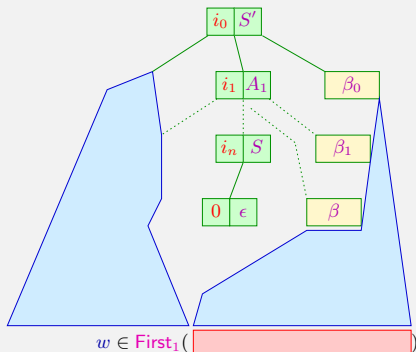
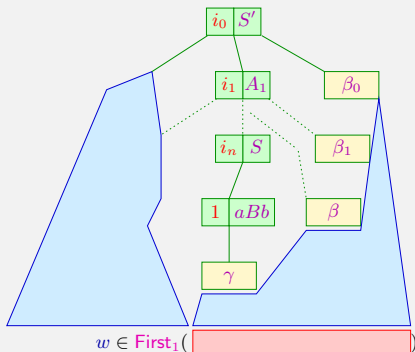
0	$[S' \rightarrow \bullet S \$]$	$\epsilon$	$[S' \rightarrow \bullet S \$] [S \rightarrow \bullet]$
1	$[S' \rightarrow \bullet S \$]$	$\epsilon$	$[S' \rightarrow \bullet S \$] [S \rightarrow \bullet a S b]$
2	$[S \rightarrow \bullet a S b]$	$a$	$[S \rightarrow a \bullet S b]$
3	$[S \rightarrow a \bullet S b]$	$\epsilon$	$[S \rightarrow a \bullet S b] [S \rightarrow \bullet]$
4	$[S \rightarrow a \bullet S b]$	$\epsilon$	$[S \rightarrow a \bullet S b] [S \rightarrow \bullet a S b]$
5	$[S \rightarrow a \bullet S b] [S \rightarrow \bullet]$	$\epsilon$	$[S \rightarrow a S \bullet b]$
6	$[S \rightarrow a \bullet S b] [S \rightarrow a S b \bullet]$	$\epsilon$	$[S \rightarrow a S \bullet b]$
7	$[S \rightarrow a S \bullet b]$	$b$	$[S \rightarrow a S b \bullet]$
8	$[S' \rightarrow \bullet S \$] [S \rightarrow \bullet]$	$\epsilon$	$[S' \rightarrow S \bullet \$]$
9	$[S' \rightarrow \bullet S \$] [S \rightarrow a S b \bullet]$	$\epsilon$	$[S' \rightarrow S \bullet \$]$

Conflicts arise between transitions (0, 1) or (3, 4) resp..

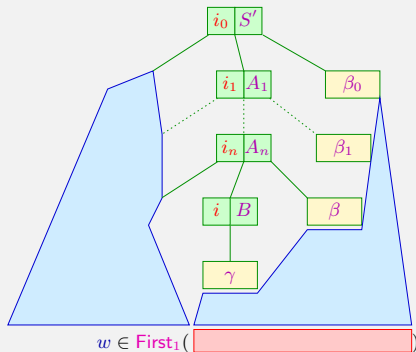
# Item Pushdown Automaton as LL(1)-Parser

... in detail:  $S' \rightarrow S \$$      $S \rightarrow \epsilon^0 \mid a S b^1$

$\text{First}_1(\text{input})$	\$	a	b
$S$	?	?	?



# Item Pushdown Automaton as LL(1)-Parser



Inequality system for  $\text{Follow}_1(B) = \text{First}_1(\beta) \odot_1 \dots \odot_1 \text{First}_1(\beta_0)$

$$\text{Follow}_1(S) \supseteq \{\epsilon\}$$

$$\text{Follow}_1(B) \supseteq F_\epsilon(X_j) \quad \text{if} \quad A \rightarrow \alpha B X_1 \dots X_m \in P, \\ \text{empty}(X_1) \wedge \dots \wedge \text{empty}(X_{j-1})$$

$$\text{Follow}_1(B) \supseteq \text{Follow}_1(A) \quad \text{if} \quad A \rightarrow \alpha B X_1 \dots X_m \in P, \\ \text{empty}(X_1) \wedge \dots \wedge \text{empty}(X_m)$$

# Item Pushdown Automaton as LL(1)-Parser

Is  $G$  an  $LL(1)$ -grammar, we can index a lookahead-table with items and nonterminals:

## LL(1)-Lookahead Table

We set  $M[B, w] = i$  with  $B \rightarrow \gamma^i$  if  $w \in \text{First}_1(\gamma) \odot_1 \text{Follow}_1(B)$

... for example:  $S' \rightarrow S \$$      $S \rightarrow \epsilon^0 \mid a S b^1$

$\text{First}_1(S) = \{\epsilon, a\}$      $\text{Follow}_1(S) = \{b, \$\}$

$S$ -rule 0 :             $\text{First}_1(\epsilon) \odot_1 \text{Follow}_1(S) = \{b, \$\}$

$S$ -rule 1 :             $\text{First}_1(aSb) \odot_1 \text{Follow}_1(S) = \{a\}$

	\$	$a$	$b$
$S$	0	1	0

# Item Pushdown Automaton as LL(1)-Parser

For example:  $S' \rightarrow S \$$      $S \rightarrow \epsilon^0 \mid a S b^1$

The transitions of the according Item Pushdown Automaton:

0	$[S' \rightarrow \bullet S \$]$	$\epsilon$	$[S' \rightarrow \bullet S \$] [S \rightarrow \bullet]$
1	$[S' \rightarrow \bullet S \$]$	$\epsilon$	$[S' \rightarrow \bullet S \$] [S \rightarrow \bullet a S b]$
2	$[S \rightarrow \bullet a S b]$	$a$	$[S \rightarrow a \bullet S b]$
3	$[S \rightarrow a \bullet S b]$	$\epsilon$	$[S \rightarrow a \bullet S b] [S \rightarrow \bullet]$
4	$[S \rightarrow a \bullet S b]$	$\epsilon$	$[S \rightarrow a \bullet S b] [S \rightarrow \bullet a S b]$
5	$[S \rightarrow a \bullet S b] [S \rightarrow \bullet]$	$\epsilon$	$[S \rightarrow a S \bullet b]$
6	$[S \rightarrow a \bullet S b] [S \rightarrow a S b \bullet]$	$\epsilon$	$[S \rightarrow a S \bullet b]$
7	$[S \rightarrow a S \bullet b]$	$b$	$[S \rightarrow a S b \bullet]$
8	$[S' \rightarrow \bullet S \$] [S \rightarrow \bullet]$	$\epsilon$	$[S' \rightarrow S \bullet \$]$
9	$[S' \rightarrow \bullet S \$] [S \rightarrow a S b \bullet]$	$\epsilon$	$[S' \rightarrow S \bullet \$]$

Lookahead table:

	$\$$	$a$	$b$
$S$	0	1	0

# Left Recursion

## Attention:

Many grammars are not  $LL(k)$  !

A reason for that is:

## Definition

Grammar  $G$  is called **left-recursive**, if

$$A \rightarrow^+ A\beta \quad \text{for an } A \in N, \beta \in (T \cup N)^*$$

Example:

$$\begin{array}{l} E \rightarrow E + T^0 \mid T^1 \\ T \rightarrow T * F^0 \mid F^1 \\ F \rightarrow (E)^0 \mid \text{name}^1 \mid \text{int}^2 \end{array}$$

... is left-recursive

# Left Recursion

## Theorem:

Let a grammar  $G$  be reduced and left-recursive, then  $G$  is not  $LL(k)$  for any  $k$ .

## Proof:

Let wlog.  $A \rightarrow A\beta \mid \alpha \in P$   
and  $A$  be reachable from  $S$

Assumption:  $G$  is  $LL(k)$

$$\Rightarrow \text{First}_k(\alpha \beta^n \gamma) \cap \\ \text{First}_k(\alpha \beta^{n+1} \gamma) = \emptyset$$

**Case 1:**  $\beta \rightarrow^* \epsilon$  — Contradiction !!!

**Case 2:**  $\beta \rightarrow^* w \neq \epsilon \implies \text{First}_k(\alpha w^k \gamma) \cap \text{First}_k(\alpha w^{k+1} \gamma) \neq \emptyset$

## Right-Regular Context-Free Parsing

Recurring scheme in programming languages: Lists of sth...

$$S \rightarrow b \mid S a b$$

Alternative idea: **Regular Expressions**

$$S \rightarrow ( b a )^* b$$

### Definition: Right-Regular Context-Free Grammar

A **right-regular context-free grammar (RR-CFG)** is a 4-tuple  $G = (N, T, P, S)$  with:

- $N$  the set of **nonterminals**,
- $T$  the set of **terminals**,
- $P$  the set of **rules** with **regular expressions of symbols** as rhs,
- $S \in N$  the **start symbol**

**Example:** Arithmetic Expressions

$$S \rightarrow E$$

$$E \rightarrow T ( + T )^*$$

$$T \rightarrow F ( * F )^*$$

$$F \rightarrow ( E ) \mid \text{name} \mid \text{int}$$



## Idea 1: Rewrite the rules from $G$ to $\langle G \rangle$ :

$A$	$\rightarrow$	$\langle \alpha \rangle$	if	$A \rightarrow \alpha \in P$
$\langle \alpha \rangle$	$\rightarrow$	$\alpha$	if	$\alpha \in N \cup T$
$\langle \epsilon \rangle$	$\rightarrow$	$\epsilon$		
$\langle \alpha^* \rangle$	$\rightarrow$	$\epsilon \mid \langle \alpha \rangle \langle \alpha^* \rangle$	if	$\alpha \in \text{Regex}_{T,N}$
$\langle \alpha_1 \dots \alpha_n \rangle$	$\rightarrow$	$\langle \alpha_1 \rangle \dots \langle \alpha_n \rangle$	if	$\alpha_i \in \text{Regex}_{T,N}$
$\langle \alpha_1 \mid \dots \mid \alpha_n \rangle$	$\rightarrow$	$\langle \alpha_1 \rangle \mid \dots \mid \langle \alpha_n \rangle$	if	$\alpha_i \in \text{Regex}_{T,N}$

... and generate the according LL(k)-Parser  $M_{\langle G \rangle}^L$

### Example: Arithmetic Expressions cont'd

$S$	$\rightarrow$	$E$
$E$	$\rightarrow$	$T ( + T )^* \langle T ( + T )^* \rangle$
$T$	$\rightarrow$	$F ( * F )^* \langle F ( * F )^* \rangle$
$F$	$\rightarrow$	$( E ) \mid \text{name} \mid \text{int}$
$\langle T ( + T )^* \rangle$	$\rightarrow$	$T \langle ( + T )^* \rangle$
$\langle ( + T )^* \rangle$	$\rightarrow$	$\epsilon \mid \langle + T \rangle \langle ( + T )^* \rangle$
$\langle + T \rangle$	$\rightarrow$	$+ T$
$\langle F ( * F )^* \rangle$	$\rightarrow$	$F \langle ( * F )^* \rangle$
$\langle ( * F )^* \rangle$	$\rightarrow$	$\epsilon \mid \langle * F \rangle \langle ( * F )^* \rangle$
$\langle * F \rangle$	$\rightarrow$	$* F$



Reinhold Heckmann

## Definition:

An *RR-CFG*  $G$  is called *RLL(1)*,  
if the corresponding CFG  $\langle G \rangle$  is an *LL(1)* grammar.

## Discussion

- directly yields the table driven parser  $M_{\langle G \rangle}^L$  for *RLL(1)* grammars
- however: mapping regular expressions to recursive productions unnecessarily strains the stack  
→ instead directly construct automaton in the style of Berry-Sethi

## Idea 2: Recursive Descent RLL Parsers:

*Recursive descent* RLL(1)-parsers are an alternative to table-driven parsers; apart from the usual function `scan()`, we generate a program frame with the lookahead function `expect()` and the main parsing method `parse()`:

```
int next;
boolean expect(Set E){
    if ({ $\epsilon$ , next}  $\cap$  E =  $\emptyset$ ){
        cerr << "Expected" << E << "found" << next;
        return false;
    }
    return true;
}
void parse(){
    next = scan();
    if (!expect(First1(S))) exit(0);
    S();
    if (!expect({EOF})) exit(0);
}
```

## Idea 2: Recursive Descent RLL Parsers:

For each  $A \rightarrow \alpha \in P$ , we introduce:

```
void A(){
    generate( $\alpha$ )
}
```

with the meta-program *generate* being defined by structural decomposition of  $\alpha$ :

```
 $generate(r_1 \dots r_k)$  =  $generate(r_1)$ 
                        if (!expect( $First_1(r_2)$ )) exit(0);
                         $generate(r_2)$ 
                         $\vdots$ 
                        if (!expect( $First_1(r_k)$ )) exit(0);
                         $generate(r_k)$ 
 $generate(\epsilon)$       = ;
 $generate(a)$           = consume();
 $generate(A)$          = A();
```

## Idea 2: Recursive Descent RLL Parsers:

```
generate( $r^*$ )           = while ( next  $\in F_\epsilon(r)$  ) {  
                           generate( $r$ )  
                           }  
generate( $r_1 \mid \dots \mid r_k$ ) = switch(next) {  
                           labels( $\text{First}_1(r_1)$ ) generate( $r_1$ ) break ;  
                           :  
                           labels( $\text{First}_1(r_k)$ ) generate( $r_k$ ) break ;  
                           }  
labels( $\{\alpha_1, \dots, \alpha_m\}$ ) = label( $\alpha_1$ ): ... label( $\alpha_m$ ):  
label( $\alpha$ )                       = case  $\alpha$   
label( $\epsilon$ )                       = default
```

## Discussion

- A practical implementation of an  $RLL(1)$ -parser via recursive descent is a straight-forward idea
- However, **only a subset** of the deterministic contextfree languages can be parsed this way.
- As soon as  $First_1(\_)$  sets are not disjoint any more,
  - **Solution 1:** Introduce *ranked* grammars, and decide conflicting lookahead always in favour of the higher ranked alternative
    - relation to  $LL$  parsing not so clear any more
    - not so clear for  $\_*$  operator how to decide
  - **Solution 2:** Going from  $LL(1)$  to  $LL(k)$   
The size of the occurring sets is rapidly increasing with larger  $k$   
*Unfortunately*, even  $LL(k)$  parsers are not sufficient to accept all deterministic contextfree languages. (regular lookahead  $\rightarrow LL(*)$ )
- In practical systems, this often motivates the implementation of  $k = 1$  only ...

# Chapter 4: Bottom-up Analysis

# Shift-Reduce Parser



Donald Knuth

## Idea:

We *delay* the decision whether to reduce until we know, whether the input matches the right-hand-side of a rule!

**Construction:** Shift-Reduce parser  $M_G^R$

- The input is shifted successively to the pushdown.
- Is there a **complete right-hand side** (a **handle**) atop the pushdown, it is replaced (**reduced**) by the corresponding left-hand side



# Shift-Reduce Parser

## Example:

$S \rightarrow AB$

$A \rightarrow a$

$B \rightarrow b$

The pushdown automaton:

**States:**  $q_0, f, a, b, A, B, S;$

**Start state:**  $q_0$

**End state:**  $f$

$q_0$	$a$	$q_0 a$
$a$	$\epsilon$	$A$
$A$	$b$	$Ab$
$b$	$\epsilon$	$B$
$AB$	$\epsilon$	$S$
$q_0 S$	$\epsilon$	$f$

# Shift-Reduce Parser

## Construction:

In general, we create an automaton  $M_G^R = (Q, T, \delta, q_0, F)$  with:

- $Q = T \cup N \cup \{q_0, f\}$  ( $q_0, f$  fresh);
- $F = \{f\}$ ;
- Transitions:

$$\begin{aligned} \delta = & \{(q, x, qx) \mid q \in Q, x \in T\} \cup // \text{ Shift-transitions} \\ & \{(q \alpha, \epsilon, qA) \mid q \in Q, A \rightarrow \alpha \in P\} \cup // \text{ Reduce-transitions} \\ & \{(q_0 S, \epsilon, f)\} // \text{ finish} \end{aligned}$$

## Example-computation:

$$\begin{array}{l} (q_0, \ a \ b) \vdash \quad (q_0 \ a, \ b) \vdash \quad (q_0 \ A, \ b) \\ \vdash \quad (q_0 \ A \ b, \ \epsilon) \vdash \quad (q_0 \ AB, \ \epsilon) \\ \vdash \quad (q_0 \ S, \ \epsilon) \vdash \quad (f, \ \epsilon) \end{array}$$

# Shift-Reduce Parser

## Observation:

- The sequence of reductions corresponds to a **reverse rightmost-derivation** for the input
- To prove correctness, we have to prove:

$$(\epsilon, w) \vdash^* (A, \epsilon) \quad \text{iff} \quad A \rightarrow^* w$$

- The shift-reduce pushdown automaton  $M_G^R$  is in general also **non-deterministic**
- For a deterministic parsing-algorithm, we have to identify computation-states for reduction

$\implies$  LR-Parsing

# Reverse Rightmost Derivations in Shift-Reduce-Parsers

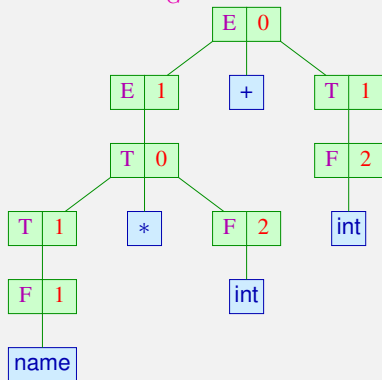
**Idea:** Observe *reverse rightmost*-derivations of  $M_G^R$ !

Input:

counter \* 2 + 40

Pushdown:

( $q_0$ )



**Generic Observation:**

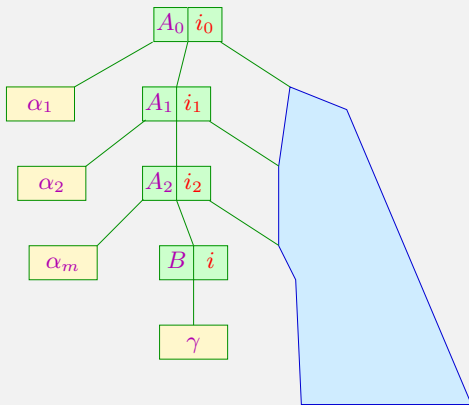
In a sequence of configurations of  $M_G^R$

$$(q_0 \alpha \gamma, v) \vdash (q_0 \alpha B, v) \vdash^* (q_0 S, \epsilon)$$

we call  $\alpha \gamma$  a **viable prefix** for the complete item  $[B \rightarrow \gamma \bullet]$ .

## Bottom-up Analysis: Viable Prefix

$\alpha\gamma$  is viable for  $[B \rightarrow \gamma\bullet]$  iff  $S \rightarrow_R^* \alpha B v$

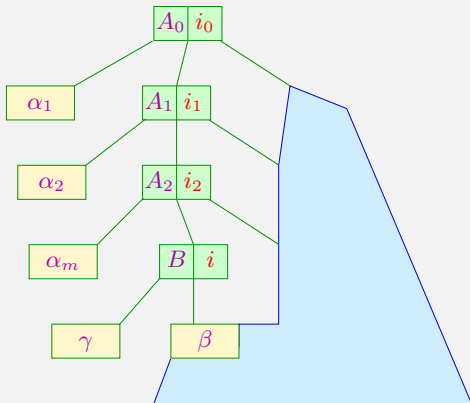


... with  $\alpha = \alpha_1 \dots \alpha_m$

Conversely, for an arbitrary valid word  $\alpha'$  we can determine the set of all later on possibly matching rules ...

## Bottom-up Analysis: Admissible Items

The item  $[B \rightarrow \gamma \bullet \beta]$  is called **admissible** for  $\alpha'$  iff  $S \xrightarrow*_R \alpha B v$  with  $\alpha' = \alpha \gamma$ :



... with  $\alpha = \alpha_1 \dots \alpha_m$

# Characteristic Automaton

## Observation:

The set of viable prefixes from  $(N \cup T)^*$  for (admissible) items can be computed from the content of the **shift-reduce parser's** pushdown with the help of a finite automaton:

**States:** Items

**Start state:**  $[S' \rightarrow \bullet S]$

**Final states:**  $\{[B \rightarrow \gamma \bullet] \mid B \rightarrow \gamma \in P\}$

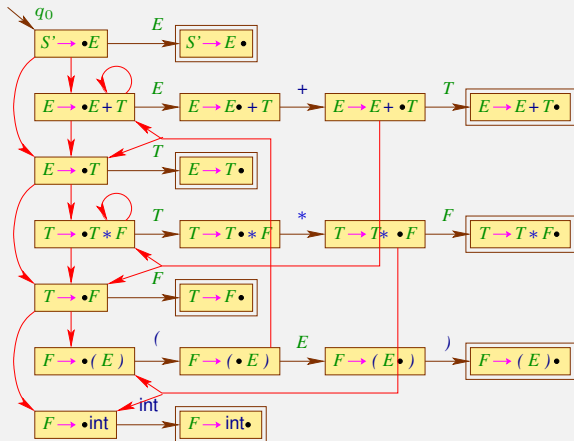
**Transitions:**

- (1)  $([A \rightarrow \alpha \bullet X \beta], X, [A \rightarrow \alpha X \bullet \beta]), \quad X \in (N \cup T), A \rightarrow \alpha X \beta \in P;$
- (2)  $([A \rightarrow \alpha \bullet B \beta], \epsilon, [B \rightarrow \bullet \gamma]), \quad A \rightarrow \alpha B \beta, B \rightarrow \gamma \in P;$

The automaton  $c(G)$  is called **characteristic automaton** for  $G$ .

# Characteristic Automaton

For example:

$$\begin{array}{l} E \rightarrow E + T^0 \quad | \quad T^1 \\ T \rightarrow T * F^0 \quad | \quad F^1 \\ F \rightarrow (E)^0 \quad | \quad \text{int}^2 \end{array}$$


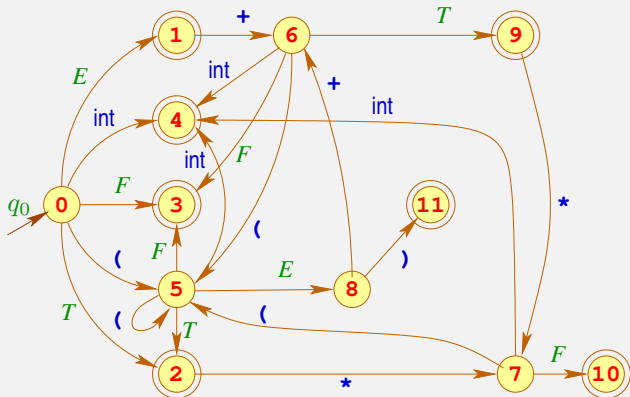


# Canonical LR(0)-Automaton

The **canonical LR(0)**-automaton  $LR(G)$  is created from  $c(G)$  by:

- 1 performing arbitrarily many  $\epsilon$ -transitions after every consuming transition
- 2 performing the powerset construction

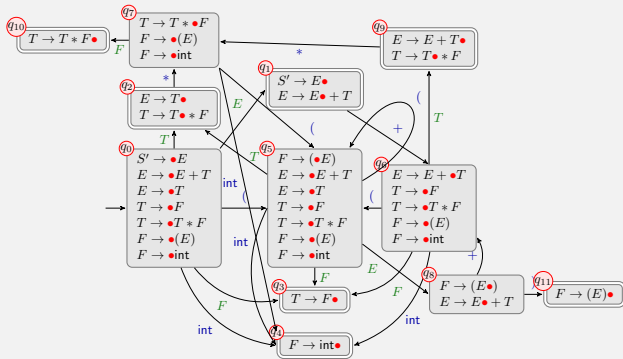
... for example:



# Canonical LR(0)-Automaton

For example:

$$\begin{array}{l}
 S' \rightarrow E \\
 E \rightarrow E + T \quad | \quad T \\
 T \rightarrow T * F \quad | \quad F \\
 F \rightarrow ( E ) \quad | \quad \text{int}
 \end{array}$$



# Canonical LR(0)-Automaton

## Observation:

The canonical LR(0)-automaton can be created **directly** from the grammar.

Therefore we need a helper function  $\delta_\epsilon^*$  ( $\epsilon$ -closure)

$$\delta_\epsilon^*(q) = q \cup \{ [B \rightarrow \bullet \gamma] \mid B \rightarrow \gamma \in P, \\ [A \rightarrow \alpha \bullet B' \beta'] \in q, \\ B' \rightarrow^* B \beta' \}$$

We define:

**States:** Sets of items;

**Start state:**  $\delta_\epsilon^* \{ [S' \rightarrow \bullet S] \}$

**Final states:**  $\{ q \mid [A \rightarrow \alpha \bullet] \in q \}$

**Transitions:**  $\delta(q, X) = \delta_\epsilon^* \{ [A \rightarrow \alpha X \bullet \beta] \mid [A \rightarrow \alpha \bullet X \beta] \in q \}$

# LR(0)-Parser

## Idea for a parser:

- The parser manages a viable prefix  $\alpha = X_1 \dots X_m$  on the pushdown and uses  $LR(G)$ , to identify reduction spots.
- It can reduce with  $A \rightarrow \gamma$ , if  $[A \rightarrow \gamma \bullet]$  is admissible for  $\alpha$

## Optimization:

We push the **states** instead of the  $X_i$  in order not to process the pushdown's content with the automaton anew all the time.

Reduction with  $A \rightarrow \gamma$  leads to popping the uppermost  $|\gamma|$  states and continue with the state on top of the stack and input  $A$ .

## Attention:

This parser is only **deterministic**, if each final state of the canonical  $LR(0)$ -automaton is **conflict** free.

# LR(0)-Parser

... for example:

$$q_1 = \{[S' \rightarrow E \bullet], \\ [E \rightarrow E \bullet + T]\}$$

$$q_2 = \{[E \rightarrow T \bullet], \\ [T \rightarrow T \bullet * F]\}$$

$$q_3 = \{[T \rightarrow F \bullet]\}$$

$$q_4 = \{[F \rightarrow \text{int} \bullet]\}$$

$$q_9 = \{[E \rightarrow E + T \bullet], \\ [T \rightarrow T \bullet * F]\}$$

$$q_{10} = \{[T \rightarrow T * F \bullet]\}$$

$$q_{11} = \{[F \rightarrow ( E ) \bullet]\}$$

The final states  $q_1, q_2, q_9$  contain more than one admissible item  
 $\Rightarrow$  non deterministic!

# LR(0)-Parser

## The construction of the $LR(0)$ -parser:

States:  $Q \cup \{f\}$  ( $f$  fresh)

Start state:  $q_0$

Final state:  $f$

### Transitions:

**Shift:**  $(p, a, pq)$  if  $q = \delta(p, a) \neq \emptyset$

**Reduce:**  $(p q_1 \dots q_m, \epsilon, pq)$  if  $[A \rightarrow X_1 \dots X_m \bullet] \in q_m,$   
 $q = \delta(p, A)$

**Finish:**  $(q_0 p, \epsilon, f)$  if  $[S' \rightarrow S \bullet] \in p$

with  $LR(G) = (Q, T, \delta, q_0, F)$ .

# LR(0)-Parser

## Correctness:

### we show:

The accepting computations of an  $LR(0)$ -parser are one-to-one related to those of a shift-reduce parser  $M_G^R$ .

### we conclude:

- The accepted language is exactly  $\mathcal{L}(G)$
- The sequence of reductions of an accepting computation for a word  $w \in T$  yields a **reverse rightmost derivation** of  $G$  for  $w$

## Attention:

Unfortunately, the  $LR(0)$ -parser is in general non-deterministic.

We identify two reasons:

### Reduce-Reduce-Conflict:

$$[A \rightarrow \gamma \bullet], [A' \rightarrow \gamma' \bullet] \in q \text{ with } A \neq A' \vee \gamma \neq \gamma'$$

### Shift-Reduce-Conflict:

$$[A \rightarrow \gamma \bullet], [A' \rightarrow \alpha \bullet a \beta] \in q \text{ with } a \in T$$

for a state  $q \in Q$ .

Those states are called  $LR(0)$ -unsuited.



# Revisiting the Conflicts of the LR(0)-Automaton

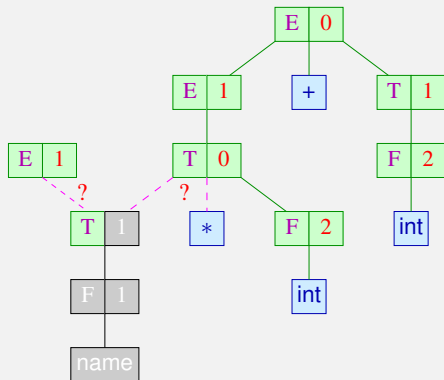
What differentiates the particular Reductions and Shifts?

Input:

\* 2 + 40

Pushdown:

( $q_0$   $T$ )


$$\begin{array}{l} E \rightarrow E + T^0 \quad | \quad T^1 \\ T \rightarrow T * F^0 \quad | \quad F^1 \\ F \rightarrow (E)^0 \quad | \quad int^2 \end{array}$$

# LR(k)-Grammars

**Idea:** Consider  $k$ -lookahead in conflict situations.

## Definition:

The reduced contextfree grammar  $G$  is called  $LR(k)$ -grammar, if for  $\text{First}_{|\alpha\beta|+k}(\alpha\beta w) = \text{First}_{|\alpha'\beta|+k}(\alpha'\beta'w')$  with:

$$\left. \begin{array}{l} S \xrightarrow{*}_R \alpha A w \rightarrow \alpha\beta w \\ S \xrightarrow{*}_R \alpha' A' w' \rightarrow \alpha'\beta'w' \end{array} \right\} \text{follows: } \alpha = \alpha' \wedge \beta = \beta' \wedge A = A'$$

## Strategy for testing Grammars for $LR(k)$ -property

- 1 Focus iteratively on all rightmost derivations  $S \xrightarrow{*}_R \alpha X w \rightarrow \alpha\beta w$
- 2 Iterate over  $k \geq 0$ 
  - 1 For each  $\gamma = \text{First}_{|\alpha\beta|+k}(\alpha\beta w)$  check if there exists a differently right-derivable  $\alpha'\beta'w'$  for which  $\gamma = \text{First}_{|\alpha'\beta|+k}(\alpha'\beta'w')$
  - 2 if there is none, we have found no objection against  $k$ , being enough lookahead to disambiguate  $\alpha\beta w$  from other rightmost derivations

# LR(k)-Grammars

for example:

$$(1) \quad S \rightarrow A \mid B \quad A \rightarrow aAb \mid 0 \quad B \rightarrow aBbb \mid 1$$

... is not  $LL(k)$  for any  $k$  — but  $LR(0)$ :

Let  $S \xrightarrow{*}_R \alpha X w \rightarrow \alpha \beta w$ . Then  $\alpha \underline{\beta}$  is of one of these forms:

$$\underline{A}, \underline{B}, a^n \underline{aAb}, a^n \underline{aBbb}, a^n \underline{0}, a^n \underline{1} \quad (n \geq 0)$$

$$(2) \quad S \rightarrow aAc \quad A \rightarrow Abb \mid b$$

... is also not  $LL(k)$  for any  $k$  — but again  $LR(0)$ :

Let  $S \xrightarrow{*}_R \alpha X w \rightarrow \alpha \beta w$ . Then  $\alpha \underline{\beta}$  is of one of these forms:

$$a \underline{b}, a \underline{Abb}, a \underline{Ac}$$

# LR(k)-Grammars

for example:

(3)  $S \rightarrow aAc \quad A \rightarrow bbA \mid b \quad \dots$  is not  $LR(0)$ , but  $LR(1)$ :

Let  $S \xrightarrow{*}_R \alpha X w \rightarrow \alpha \beta w$  with  $\{y\} = \text{First}_k(w)$  then  $\alpha \underline{\beta} y$  is of one of these forms:

$$ab^{2n} \underline{b}c, ab^{2n} \underline{bb}Ac, \underline{a}Ac$$

(4)  $S \rightarrow aAc \quad A \rightarrow bAb \mid b \quad \dots$  is not  $LR(k)$  for any  $k \geq 0$ :

Consider the rightmost derivations:

$$S \xrightarrow{*}_R ab^n Ab^n c \rightarrow ab^n \underline{bb}^n c$$

# LR(1)-Parsing

**Idea:** Let's equip items with 1-lookahead

## Definition LR(1)-Item

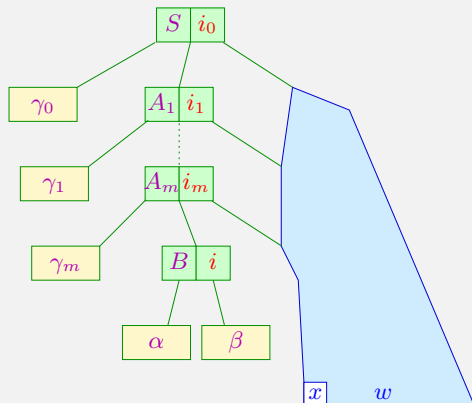
An  $LR(1)$ -item is a pair  $[B \rightarrow \alpha \bullet \beta, x]$  with

$$x \in \text{Follow}_1(B) = \bigcup \{ \text{First}_1(\nu) \mid S \rightarrow^* \mu B \nu \}$$

## Admissible LR(1)-Items

The item  $[B \rightarrow \alpha \bullet \beta, x]$  is *admissible* for  $\gamma \alpha$  if:

$$S \rightarrow_R^* \gamma B w \quad \text{with} \quad \{x\} = \text{First}_1(w)$$



... with  $\gamma_0 \dots \gamma_m = \gamma$

# The Characteristic LR(1)-Automaton

The set of admissible  $LR(1)$ -items for viable prefixes is again computed with the help of the finite automaton  $c(G, 1)$ .

The automaton  $c(G, 1)$ :

States:  $LR(1)$ -items

Start state:  $[S' \rightarrow \bullet S, \epsilon]$

Final states:  $\{[B \rightarrow \gamma \bullet, x] \mid B \rightarrow \gamma \in P, x \in \text{Follow}_1(B)\}$

Transitions:

- (1)  $([A \rightarrow \alpha \bullet X \beta, x], X, [A \rightarrow \alpha X \bullet \beta, x]), \quad X \in (N \cup T)$
- (2)  $([A \rightarrow \alpha \bullet B \beta, x], \epsilon, [B \rightarrow \bullet \gamma, x']),$   
 $A \rightarrow \alpha B \beta, B \rightarrow \gamma \in P,$   
 $x' \in \text{First}_1(\beta) \odot_1 \{x\}$

This automaton works like  $c(G)$  — but additionally manages a 1-prefix from  $\text{Follow}_1$  of the left-hand sides.

# The Canonical LR(1)-Automaton

The canonical LR(1)-automaton  $LR(G, 1)$  is created from  $c(G, 1)$ , by performing arbitrarily many  $\epsilon$ -transitions and then making the resulting automaton **deterministic ...**

But again, it can be constructed **directly** from the grammar; analogously to LR(0), we need the  $\epsilon$ -closure  $\delta_\epsilon^*$  as a helper function:

$$\delta_\epsilon^*(q) = q \cup \{ [C \rightarrow \bullet \gamma, x] \mid \begin{array}{l} C \rightarrow \gamma \in P, \\ [A \rightarrow \alpha \bullet B \beta', x'] \in q, \\ B \rightarrow^* C \beta, \\ x \in \text{First}_1(\beta \beta') \odot_1 \{x'\} \} \end{array}$$

Then, we define:

**States:** Sets of LR(1)-items;

**Start state:**  $\delta_\epsilon^* \{ [S' \rightarrow \bullet S, \epsilon] \}$

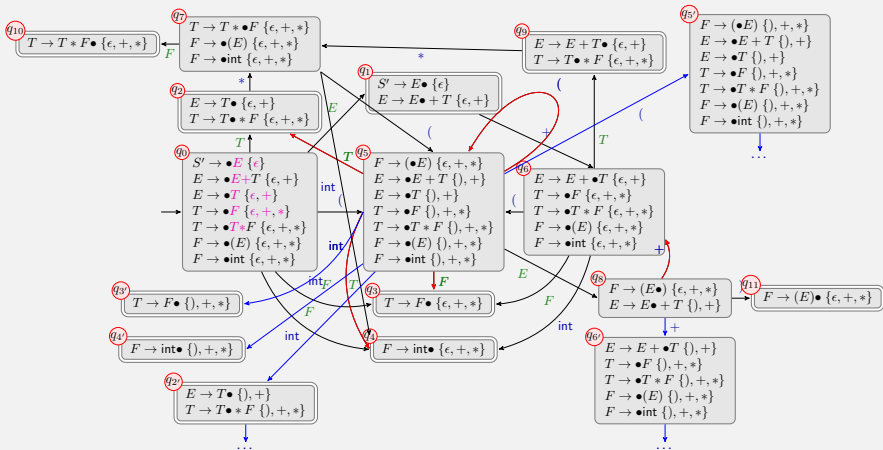
**Final states:**  $\{ q \mid [A \rightarrow \alpha \bullet, x] \in q \}$

**Transitions:**  $\delta(q, X) = \delta_\epsilon^* \{ [A \rightarrow \alpha X \bullet \beta, x] \mid [A \rightarrow \alpha \bullet X \beta, x] \in q \}$

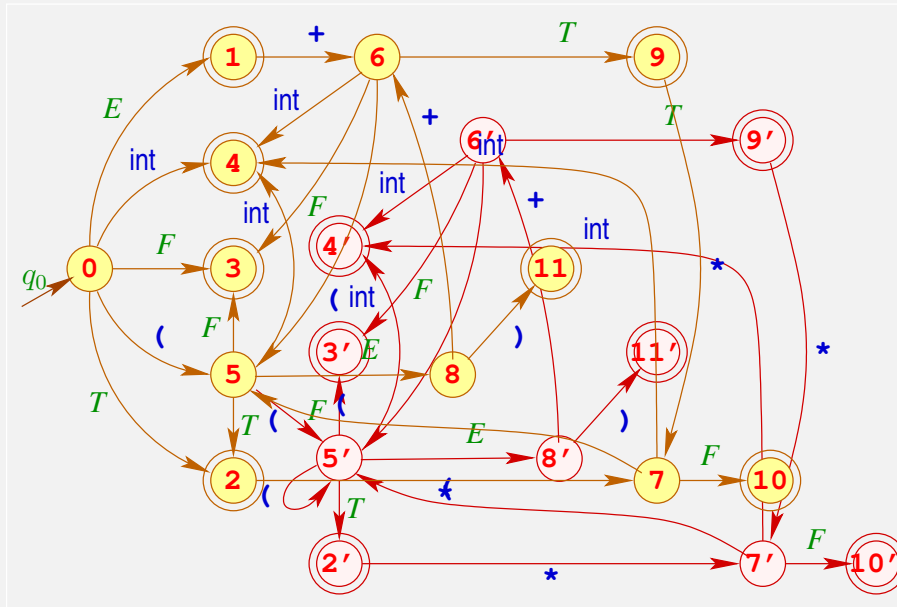


# Canonical LR(1)-Automaton

For example:

$$\begin{array}{l}
 S' \rightarrow E \\
 E \rightarrow E + T \quad | \quad T \\
 T \rightarrow T * F \quad | \quad F \\
 F \rightarrow (E) \quad | \quad \text{int}
 \end{array}$$


# The Canonical LR(1)-Automaton



# The Canonical LR(1)-Automaton

## Discussion:

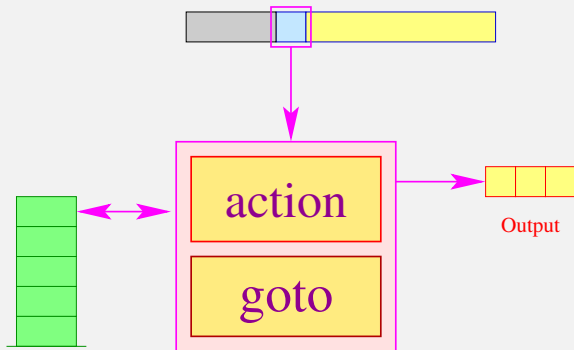
- In the example, the number of states was almost doubled  
... and it can become even worse
- The conflicts in states  $q_1, q_2, q_9$  are now resolved !  
e.g. we have:

$$\begin{array}{l} q_9 \\ E \rightarrow E+T \bullet \{ \epsilon, + \} \\ T \rightarrow T \bullet *F \{ \epsilon, +, * \} \end{array}$$

with:

$$\{ \epsilon, + \} \cap (\text{First}_1(*F) \odot_1 \{ \epsilon, +, * \}) = \{ \epsilon, + \} \cap \{ * \} = \emptyset$$

## The LR(1)-Parser:



- The **goto**-table encodes the transitions:

$$\text{goto}[q, X] = \delta(q, X) \in Q$$

- The **action**-table describes for every state  $q$  and possible lookahead  $w$  the necessary action.

# The LR(1)-Parser:

## The construction of the $LR(1)$ -parser:

States:  $Q \cup \{f\}$  ( $f$  fresh)

Start state:  $q_0$

Final state:  $f$

### Transitions:

**Shift:**  $(p, a, pq)$  if  $q = \text{goto}[q, a],$   
 $s = \text{action}[p, w]$

**Reduce:**  $(p q_1 \dots q_{|\beta|}, \epsilon, pq)$  if  $[A \rightarrow \beta \bullet] \in q_{|\beta|},$   
 $q = \text{goto}(p, A),$   
 $[A \rightarrow \beta \bullet] = \text{action}[q_{|\beta|}, w]$

**Finish:**  $(q_0 p, \epsilon, f)$  if  $[S' \rightarrow S \bullet] \in p$

with  $LR(G, 1) = (Q, T, \delta, q_0, F)$ .

# The LR(1)-Parser:

Possible actions are:

**shift** // Shift-operation  
**reduce** ( $A \rightarrow \gamma$ ) // Reduction with callback/output  
**error** // Error

... for example:

$S' \rightarrow E$   
 $E \rightarrow E + T^0 \mid T^1$   
 $T \rightarrow T * F^0 \mid F^1$   
 $F \rightarrow (E)^0 \mid \text{int}^1$

action	\$	int	(	)	+	*
$q_1$	$S', 0$				s	
$q_2$	$E, 1$				$E, 1$	s
$q'_2$			$E, 1$		$E, 1$	s
$q_3$	$T, 1$				$T, 1$	$T, 1$
$q'_3$			$T, 1$		$T, 1$	$T, 1$
$q_4$	$F, 1$				$F, 1$	$F, 1$
$q'_4$			$F, 1$		$F, 1$	$F, 1$
$q_9$	$E, 0$				$E, 0$	s
$q'_9$			$E, 0$		$E, 0$	s
$q_{10}$	$T, 0$				$T, 0$	$T, 0$
$q'_{10}$			$T, 0$		$T, 0$	$T, 0$
$q_{11}$	$F, 0$				$F, 0$	$F, 0$
$q'_{11}$			$F, 0$		$F, 0$	$F, 0$

# The Canonical LR(1)-Automaton

In general:

We identify two conflicts:

**Reduce-Reduce-Conflict:**

$$[A \rightarrow \gamma \bullet, x], [A' \rightarrow \gamma' \bullet, x] \in q \text{ with } A \neq A' \vee \gamma \neq \gamma'$$

**Shift-Reduce-Conflict:**

$$[A \rightarrow \gamma \bullet, x], [A' \rightarrow \alpha \bullet a \beta, y] \in q \\ \text{with } a \in T \text{ und } x \in \{a\} \odot_k \text{First}_k(\beta) \odot_k \{y\}.$$

for a state  $q \in Q$ .

Such states are now called **LR(1k)-unsuited**

**Theorem:**

A reduced contextfree grammar  $G$  is called **LR(k)** iff the canonical **LR(k)**-automaton  $LR(G, k)$  has no **LR(k)-unsuited** states.

# Precedences

Many parser generators give the chance to fix Shift-/Reduce-Conflicts by patching the **action** table either by hand or with *token precedences*.

... for example:

$$\begin{array}{l}
 S' \rightarrow E^0 \\
 E \rightarrow E + E^0 \\
 \quad | \quad E * E^1 \\
 \quad | \quad ( E )^2 \\
 \quad | \quad \text{int}^3
 \end{array}$$

Shift-/Reduce Conflict in state 8:

$$\begin{array}{l}
 [E \rightarrow E \bullet + E^0] \\
 [E \rightarrow E + E \bullet^0, +]
 \end{array}$$

$\langle \gamma E + E, + \omega \rangle \Rightarrow$  *Associativity*

Shift-/Reduce Conflict in state 7:

$$\begin{array}{l}
 [E \rightarrow E \bullet * E^1] \\
 [E \rightarrow E * E \bullet^1, *]
 \end{array}$$

Shift-/Reduce Conflict in state 6:

$$[E \rightarrow E * E \bullet^1, *]$$

action	\$	int	(	)	+	*
$q_0$	$S', 0$				s	s
$q_1$	$E, 3$			$E, 3$	$E, 3$	$E, 3$
$q_2$	s				s	s
$q_3$	s				s	s
$q_4$	dot/expr-simple			s	s	s
$q_5$	$E, 2$			$E, 2$	$E, 2$	$E, 2$
$q_6$	s			s	s	s
$q_7$	$E, 1$			$E, 1$	? $E, 1$	?s
$q_8$	$E, 0$			$E, 0$	? $E, 0$	?s
$q_9$	s			s	s	s



# What if precedences are not enough?

Example (very simplified lambda expressions):


$$E \rightarrow (E)^0 \mid \text{ident}^1 \mid L^2$$
$$L \rightarrow \langle \text{args} \rangle \Rightarrow E^0$$
$$\langle \text{args} \rangle \rightarrow ( \langle \text{idlist} \rangle )^0 \mid \text{ident}^1$$
$$\langle \text{idlist} \rangle \rightarrow \langle \text{idlist} \rangle \text{ident}^0 \mid \text{ident}^1$$

$E$  rightmost-derives these forms among others:

( ident ), ( ident )  $\Rightarrow$  ident , ...  $\Rightarrow$  at least  $LR(2)$

## Naive Idea:

poor man's  $LR(2)$  by combining the tokens  $)$  and  $\Rightarrow$  during lexical analysis into a single token  $)\Rightarrow$ .

 in this case obvious solution, but in general not so simple

# What if precedences are not enough?

In practice,  $LR(k)$ -parser generators working with the lookahead sets of sizes larger than  $k = 1$  are not common, since computing lookahead sets with  $k > 1$  blows up exponentially. However,

- 1 there exist several practical  $LR(k)$  grammars of  $k > 1$ , e.g. Java 1.6+ ( $LR(2)$ ), ANSI C, etc.
- 2 often, more lookahead is only exhausted locally
- 3 should we really give up, whenever we are confronted with a Shift-/Reduce-Conflict?



Victor Schneider



Dennis Mickunas

**Theorem:**  $LR(k)$ -to- $LR(1)$

Any  $LR(k)$  grammar can be directly transformed into an equivalent  $LR(1)$  grammar.

# LR(2) to LR(1)

... Example:

$$\begin{aligned} S &\rightarrow A b b^0 \mid B b c^1 \\ A &\rightarrow a A^0 \mid a^1 \\ B &\rightarrow a B^0 \mid a^1 \end{aligned}$$

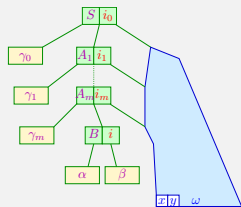
$S$  rightmost-derives one of these forms:

$$a^n \underline{a} b b, a^n \underline{a} b c, a^n \underline{a} A b b, a^n \underline{a} B b c, \underline{A} b b, \underline{B} b c \Rightarrow LR(2)$$

in  $LR(1)$ , you will have Reduce-/Reduce-Conflicts between the productions  $A, 1$  and  $B, 1$  as well as  $A, 0$  and  $B, 0$  under lookahead  $b$

# LR(2) to LR(1)

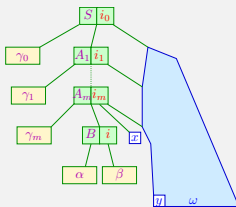
Basic Idea:



⇒

*Right-context-extraction*

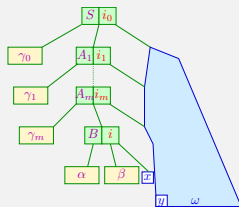
⇒



⇒

*Right-context-propagation*

⇒



in the example:

Right-context is already extracted, so we only perform

*Right-context-propagation:*

$$\begin{aligned}
 S &\rightarrow A b b^0 \mid B b c^1 \\
 A &\rightarrow a A^0 \mid a^1 \\
 B &\rightarrow a B^0 \mid a^1
 \end{aligned}$$

⇒

$$\begin{aligned}
 S &\rightarrow \langle A b \rangle b^0 \mid \langle B b \rangle c^1 \\
 \langle A b \rangle &\rightarrow a \langle A b \rangle^0 \mid a b^1 \\
 \langle B b \rangle &\rightarrow a \langle B b \rangle^0 \mid a b^1 \\
 A &\rightarrow a A^0 \mid a^1 \\
 B &\rightarrow a B^0 \mid a^1
 \end{aligned}$$

unreachable

# LR(2) to LR(1)

Example cont'd:

$$\begin{aligned} S &\rightarrow A' b^0 \mid B' c^1 \\ A' &\rightarrow a A'^0 \mid a b^1 \\ B' &\rightarrow a B'^0 \mid a b^1 \end{aligned}$$

$S$  rightmost-derives one of these forms:

$$a^n \underline{a} \underline{b} \underline{b}, a^n \underline{a} \underline{b} \underline{c}, a^n \underline{a} \underline{A}' \underline{b}, a^n \underline{a} \underline{B}' \underline{c}, \underline{A}' \underline{b}, \underline{B}' \underline{c} \Rightarrow LR(1)$$

# LR(2) to LR(1)

## Example 2:

$$\begin{array}{l}
 S \rightarrow bSS^0 \\
 | \quad a^1 \\
 | \quad aac^2
 \end{array}$$

$S$  rightmost-derives these forms among others:

$\underline{bSS}$ ,  $bS\underline{a}$ ,  $bS\underline{aac}$ ,  $\underline{b}aa$ ,  $\underline{b}aaca$ ,  $\underline{b}aaac$ ,  $\underline{b}aac\underline{aac}$ , ...  $\Rightarrow$  min.  $LR(2)$

in  $LR(1)$ , you will have (at least) Shift-/Reduce-Conflicts between the items  $[S \rightarrow a \bullet, a]$  and  $[S \rightarrow a \bullet ac]$

$[S \rightarrow a]$ 's right context is a nonterminal  $\Rightarrow$  perform *Right-context-extraction*

$$\begin{array}{l}
 S \rightarrow bSS^0 \\
 | \quad a^1 \\
 | \quad aac^2
 \end{array}
 \quad \Rightarrow \quad
 \begin{array}{l}
 S \rightarrow bSa \langle a/S \rangle^0 \mid bSb \langle b/S \rangle^{0'} \\
 | \quad a^1 \mid aac^2 \\
 \langle a/S \rangle \rightarrow \epsilon^0 \mid ac^1 \\
 \langle b/S \rangle \rightarrow SS^0Sa \langle a/S \rangle^0 \mid Sb \langle b/S \rangle^{0'}
 \end{array}$$

# LR(2) to LR(1)

## Example 2 cont'd:

$[S \rightarrow a]$ 's right context is now terminal  $a \Rightarrow$  perform *Right-context-propagation*

$$\begin{array}{lcl}
 S & \rightarrow & bSa \langle a/S \rangle^0 \\
 & | & bSb \langle b/S \rangle^{0'} \\
 & | & a^1 | aac^2 \\
 \langle a/S \rangle & \rightarrow & \epsilon^0 | ac^1 \\
 \langle b/S \rangle & \rightarrow & Sa \langle a/S \rangle^0 | Sb \langle b/S \rangle^{0'} \\
 \\ 
 S & \Rightarrow & S \\
 & & \langle a/S \rangle \\
 & & \langle b/S \rangle \\
 & & \langle Sa \rangle \\
 & & \langle \langle a/S \rangle a \rangle \\
 & & \langle \langle b/S \rangle a \rangle \\
 \\ 
 & & \rightarrow b \langle Sa \rangle \langle a/S \rangle^0 \\
 & & | bSb \langle b/S \rangle^{0'} \\
 & & | a^1 | aac^2 \\
 & & \rightarrow \epsilon^0 | ac^1 \\
 & & \rightarrow \langle Sa \rangle \langle a/S \rangle^0 | Sb \langle b/S \rangle^{0'} \\
 & & \rightarrow b \langle Sa \rangle \langle a/S \rangle a \langle \langle a/S \rangle a \rangle^0 \\
 & & | bSb \langle b/S \rangle a \langle \langle b/S \rangle a \rangle^{0'} \\
 & & | aa^1 | aac^2 \\
 & & \rightarrow a^0 | aca^1 \\
 & & \rightarrow \langle Sa \rangle \langle a/S \rangle a \langle \langle a/S \rangle a \rangle^0 | Sb \langle b/S \rangle^{0'}
 \end{array}$$

# LR(2) to LR(1)

## Example 2 finished:

With fresh nonterminals we get the final grammar

$$\begin{array}{l} S \rightarrow b S S^0 \\ \quad | a^1 \\ \quad | a a c^2 \end{array} \Rightarrow \begin{array}{l} S \rightarrow b C A^0 | b S b B^1 | a^2 | a a c^3 \\ A \rightarrow \epsilon^0 | a c^1 \\ B \rightarrow C A^0 | S b B^1 \\ C \rightarrow b C D^0 | b S b E^1 | a a^2 | a a c a^3 \\ D \rightarrow a^0 | a c a^1 \\ E \rightarrow C D^0 | S b E^1 \end{array}$$



## LR(2) to LR(1)

### Algorithm:

For a Rule  $A \rightarrow \alpha$ , which is *reduce-conflicting* under terminal  $x$

- $B \rightarrow \beta A$  is also considered *reduce-conflicting* under terminal  $x$
- $B \rightarrow \beta AC\gamma$  is transformed by *right-context-extraction* on  $C$ :

$$B \rightarrow \beta AC\gamma \Rightarrow B \rightarrow \beta Ax \langle x/C \rangle \gamma \quad \left| \quad y \in \text{First}_1(C) \setminus x \quad \beta Ay \langle y/C \rangle \gamma \right.$$

if  $\epsilon \in \text{First}_1(C)$  then consider  $B \rightarrow \beta A\gamma$  for r.-c.-extraction

- $B \rightarrow \beta Ax\gamma$  is transformed by *right-context-propagation* on  $A$ :

$$B \rightarrow \beta Ax\gamma \Rightarrow B \rightarrow \beta \langle Ax \rangle \gamma$$

- The appropriate rules, created from introducing  $\langle Ax \rangle \rightarrow \delta$  and  $\langle x/B \rangle \rightarrow \eta$  are added to the grammar

# LR(2) to LR(1)

## Right-Context-Propagation Algorithm:

For  $\langle Ax \rangle$  with  $A \rightarrow \alpha_1 \mid \dots \mid \alpha_k$ , if  $\alpha_i$  matches

- $\gamma A$  for some  $\gamma \in (N \cup T)^*$ , then  $\langle Ax \rangle \rightarrow \gamma \langle Ax \rangle$  is added
- else  $\langle Ax \rangle \rightarrow \alpha_i x$  is added

## Right-Context-Extraction Algorithm:

For  $\langle x/B \rangle$  with  $B \rightarrow \alpha_1 \mid \dots \mid \alpha_k$ , if  $\alpha_i$  matches

- $C \gamma$  for some  $\gamma \in (N \cup T)^*$ , then  $\langle x/B \rangle \rightarrow \langle x/C \rangle \gamma$  is added
- $x \gamma$  for some  $\gamma \in (N \cup T)^*$ , then  $\langle x/B \rangle \rightarrow \gamma$  is added
- $y \gamma$  for some  $\gamma \in (N \cup T)^*$  and  $y \neq x$ , then nothing is added

Topic:

Semantic Analysis

# Semantic Analysis

Scanner and parser accept programs with correct syntax.

- not all programs that are syntactically correct make *sense*
- the compiler may be able to *recognize* some of these
  - these programs are rejected and reported as *erroneous*
  - the language definition defines what *erroneous* means
- *semantic* analyses are necessary that, for instance:
  - check that *identifiers* are known and where they are defined
  - check the *type*-correct use of variables
- *semantic* analyses are also useful to
  - find possibilities to “*optimize*” the program
  - *warn* about possibly incorrect programs

~> a semantic analysis annotates the syntax tree with *attributes*

# Chapter 1: Attribute Grammars

# Attribute Grammars

- many computations of the semantic analysis as well as the code generation operate on the syntax tree
- what is computed at a given node only depends on the *type* of that node (which is usually a non-terminal)
- we call this a *local* computation:
  - only accesses already computed information from neighbouring nodes
  - computes new information for the current node and other neighbouring nodes

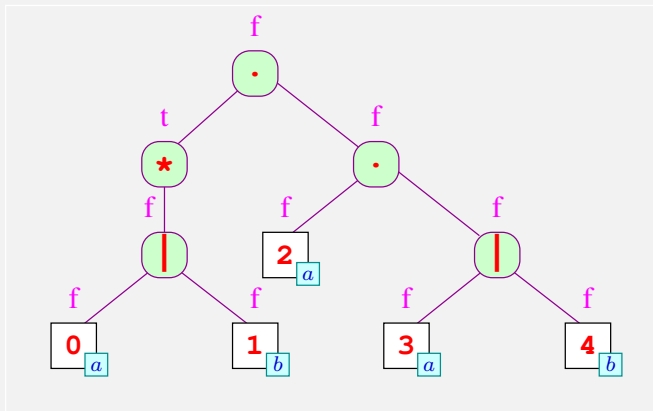
## Definition attribute grammar

An *attribute grammar* is a *CFG* extended by

- a set of attributes for each non-terminal and terminal
  - local attribute equations
- in order to be able to evaluate the attribute equations, all attributes mentioned in that equation have to be evaluated already  
↪ the nodes of the syntax tree need to be visited in a certain *sequence*

## Example: Computation of the $\text{empty}[r]$ Attribute

Consider the syntax tree of the regular expression  $(a|b)^*a(a|b)$ :



$\leadsto$  equations for  $\text{empty}[r]$  are computed from bottom to top (aka **bottom-up**)

# Implementation Strategy

- attach an attribute **empty** to every node of the syntax tree
- compute the attributes in a **depth-first post-order** traversal:
  - at a leaf, we can compute the value of **empty** without considering other nodes
  - the attribute of an inner node only depends on the attribute of its children
- the **empty** attribute is a **synthetic** attribute
- The **local** dependencies between the attributes are dependent on the **type** of the node

in general:

## Definition

An attribute is called

- **synthetic** if its value is always propagated upwards in the tree (in the direction leaf  $\rightarrow$  root)
- **inherited** if its value is always propagated downwards in the tree (in the direction root  $\rightarrow$  leaf)



# Attribute Equations for *empty*

In order to compute an attribute *locally*, we need to specify attribute equations for each node.

These equations depend on the *type* of the node:

for leaves:  $r \equiv \boxed{i \mid x}$  we define  $\text{empty}[r] = (x \equiv \epsilon)$ .

otherwise:

$$\text{empty}[r_1 \mid r_2] = \text{empty}[r_1] \vee \text{empty}[r_2]$$

$$\text{empty}[r_1 \cdot r_2] = \text{empty}[r_1] \wedge \text{empty}[r_2]$$

$$\text{empty}[r_1^*] = t$$

$$\text{empty}[r_1?] = t$$

# Specification of General Attribute Systems

## General Attribute Systems

In general, for establishing attribute systems we need a flexible way to *refer to parents and children*:

↪ We use consecutive indices to refer to neighbouring attributes

$\text{attribute}_k[0]$  : the attribute of the current root node  
 $\text{attribute}_k[i]$  : the attribute of the  $i$ -th child ( $i > 0$ )

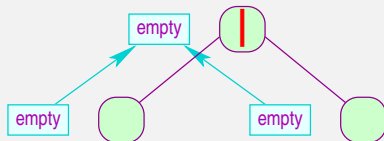
... in the example:

$x$	:	$\text{empty}[0]$	:=	$(x \equiv \epsilon)$
	:	$\text{empty}[0]$	:=	$\text{empty}[1] \vee \text{empty}[2]$
·	:	$\text{empty}[0]$	:=	$\text{empty}[1] \wedge \text{empty}[2]$
*	:	$\text{empty}[0]$	:=	$t$
?	:	$\text{empty}[0]$	:=	$t$

# Observations

- the *local* attribute equations need to be evaluated using a *global* algorithm that knows about the dependencies of the equations
- in order to construct this algorithm, we need
  - 1 a sequence in which the nodes of the tree are visited
  - 2 a sequence within each node in which the equations are evaluated
- this *evaluation strategy* has to be compatible with the *dependencies* between attributes

We visualize the attribute dependencies  $D(p)$  of a production  $p$  in a *Local Dependency Graph*:



Let  $p = N_0 \mapsto N_1 | N_2$  in

$$D(p) = \{ (\text{empty}[1], \text{empty}[0]), (\text{empty}[2], \text{empty}[0]) \}$$

$\rightsquigarrow$  arrows point in the direction of information flow

# Observations

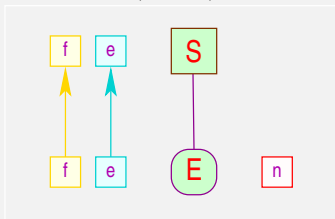
- in order to infer an evaluation strategy, it is not enough to consider the *local* attribute dependencies at each node
- the evaluation strategy must also depend on the *global* dependencies, that is, on the information flow between nodes
- the global dependencies thus change with each new syntax tree
- in the example, the parent node is always depending on children only
  - ↳ a depth-first post-order traversal is possible
- in general, variable dependencies can be much *more complex*

# Simultaneous Computation of Multiple Attributes

Computing **empty**, **first**, **next** from regular expressions:

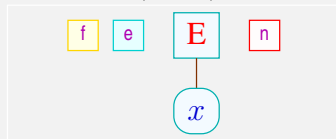
$$\begin{array}{l}
 \boxed{S \rightarrow E} : \quad \text{empty}[0] := \text{empty}[1] \\
 \quad \quad \quad \text{first}[0] := \text{first}[1] \\
 \quad \quad \quad \text{next}[1] := \emptyset \\
 \\
 \boxed{E \rightarrow x} : \quad \text{empty}[0] := (x \equiv \epsilon) \\
 \quad \quad \quad \text{first}[0] := \{x \mid x \neq \epsilon\} \\
 \quad \quad \quad // \quad (\text{no equation for next})
 \end{array}$$

$D(S \rightarrow E)$ :



$$D(S \rightarrow E) = \{ \text{---} (\text{empty}[1], \text{empty}[0]), \\
 \text{---} (\text{first}[1], \text{first}[0]) \}$$

$D(E \rightarrow x)$ :

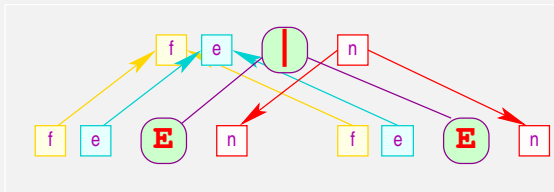


$$D(E \rightarrow x) = \{ \quad \}$$

# Regular Expressions: Rules for Alternative

$$\boxed{E \rightarrow E|E} : \begin{array}{ll} \text{empty}[0] & := \text{empty}[1] \vee \text{empty}[2] \\ \text{first}[0] & := \text{first}[1] \cup \text{first}[2] \\ \text{next}[1] & := \text{next}[0] \\ \text{next}[2] & := \text{next}[0] \end{array}$$

$D(E \rightarrow E|E) :$

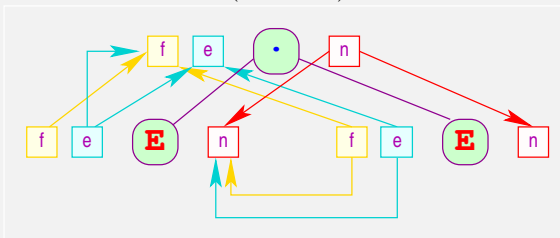


$$D(E \rightarrow E|E) = \{ \begin{array}{l} (\text{empty}[1], \text{empty}[0]), \\ (\text{empty}[2], \text{empty}[0]), \\ (\text{first}[1], \text{first}[0]), \\ (\text{first}[2], \text{first}[0]), \\ (\text{next}[0], \text{next}[2]), \\ (\text{next}[0], \text{next}[1]) \end{array} \}$$

# Regular Expressions: Rules for Concatenation

$$\boxed{E \rightarrow E \cdot E} \quad : \quad \begin{aligned} \text{empty}[0] &:= \text{empty}[1] \wedge \text{empty}[2] \\ \text{first}[0] &:= \text{first}[1] \cup (\text{empty}[1] ? \text{first}[2] : \emptyset) \\ \text{next}[1] &:= \text{first}[2] \cup (\text{empty}[2] ? \text{next}[0] : \emptyset) \\ \text{next}[2] &:= \text{next}[0] \end{aligned}$$

$D(E \rightarrow E \cdot E) :$



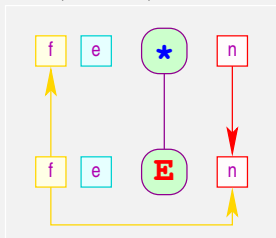
$$D(E \rightarrow E \cdot E) = \{ \begin{aligned} &(\text{empty}[1], \text{empty}[0]), \\ &(\text{empty}[2], \text{empty}[0]), \\ &(\text{empty}[2], \text{next}[1]), \\ &(\text{empty}[1], \text{first}[0]), \\ &(\text{first}[1], \text{first}[0]), \\ &(\text{first}[2], \text{first}[0]), \\ &(\text{first}[2], \text{next}[1]), \\ &(\text{next}[0], \text{next}[2]), \\ &(\text{next}[0], \text{next}[1]) \end{aligned} \}$$

# Regular Expressions: Kleene-Star and '?'

$E \rightarrow E^*$  :    empty[0] :=  $t$   
                           first[0] := first[1]  
                           next[1] := first[1]  $\cup$  next[0]

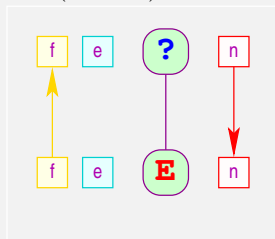
$E \rightarrow E?$  :    empty[0] :=  $t$   
                           first[0] := first[1]  
                           next[1] := next[0]

$D(E \rightarrow E^*) :$



$D(E \rightarrow E^*) = \{$      $(first[1], first[0]),$   
                            $(first[1], next[2]),$   
                            $(next[0], next[1])\}$

$D(E \rightarrow E?) :$



$D(E \rightarrow E?) = \{$      $(first[1], first[0]),$   
                            $(next[0], next[1])\}$



# Challenges for General Attribute Systems

## Static evaluation

Is there a static evaluation strategy, which is generally applicable?

- an evaluation strategy can only exist, if for *any* derivation tree the dependencies between attributes are *acyclic*
- it is *DEXPTIME*-complete to check for cyclic dependencies [Jazayeri, Odgen, Rounds, 1975]

## Ideas

- 1 Let the *User* specify the strategy
- 2 Determine the strategy dynamically
- 3 Automate *subclasses* only

## Subclass: Strongly Acyclic Attribute Dependencies

**Idea:** For all nonterminals  $X$  compute a set  $\mathcal{R}(X)$  of relations between its attributes, as an *overapproximation of the global dependencies* between root attributes of every production for  $X$ .

Describe  $\mathcal{R}(X)$ s as sets of relations, similar to  $D(p)$  by

- setting up each production  $X \mapsto X_1 \dots X_k$ 's effect on the relations of  $\mathcal{R}(X)$
- compute effect on all so far accumulated evaluations of each rhs  $X_i$ 's  $\mathcal{R}(X_i)$
- iterate until stable

## Subclass: Strongly Acyclic Attribute Dependencies

The 2-ary operator  $L[i]$  **re-decorates** relations from  $L$

$$L[i] = \{(a[i], b[i]) \mid (a, b) \in L\}$$

$\pi_0$  projects only onto relations between **root elements only**

$$\pi_0(S) = \{(a, b) \mid (a[0], b[0]) \in S\}$$

**root-projects** the **transitive closure** of relations from the  $L_i$ s and  $D(p)$

$$\llbracket p \rrbracket^\#(L_1, \dots, L_k) = \pi_0((D(p) \cup L_1[1] \cup \dots \cup L_k[k])^+)$$

$\mathcal{R}$  maps symbols to relations (global attributes dependencies)

$$\mathcal{R}(X) = \bigcup \{ \llbracket p \rrbracket^\#(\mathcal{R}(X_1), \dots, \mathcal{R}(X_k)) \mid p : X \rightarrow X_1 \dots X_k \} \mid X \in N$$

$$\mathcal{R}(X) \supseteq \emptyset \quad \mid X \in N \quad \wedge \quad \mathcal{R}(a) = \emptyset \quad \mid a \in T$$

### Strongly Acyclic Grammars

The system of inequalities  $\mathcal{R}(X)$

- characterizes the class of strongly acyclic Dependencies
- has a unique least solution  $\mathcal{R}^*(X)$  (as  $\llbracket \cdot \rrbracket^\#$  is monotonic)

## Subclass: Strongly Acyclic Attribute Dependencies

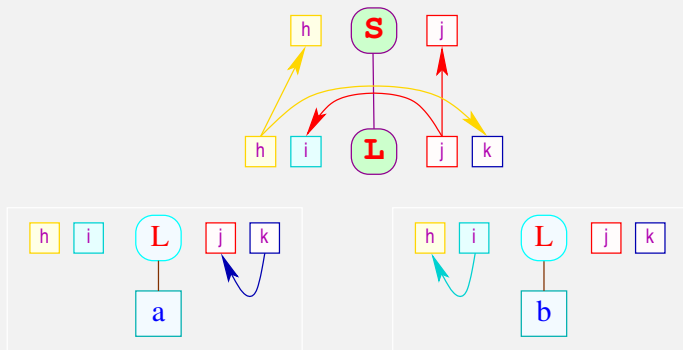
### Strongly Acyclic Grammars

If all  $D(p) \cup \mathcal{R}^*(X_1)[1] \cup \dots \cup \mathcal{R}^*(X_k)[k]$  are acyclic for all  $p \in G$ ,  $G$  is strongly acyclic.

**Idea:** we compute the least solution  $R^*(X)$  of  $R(X)$  by a fixpoint computation, starting from  $R(X) = \emptyset$ .

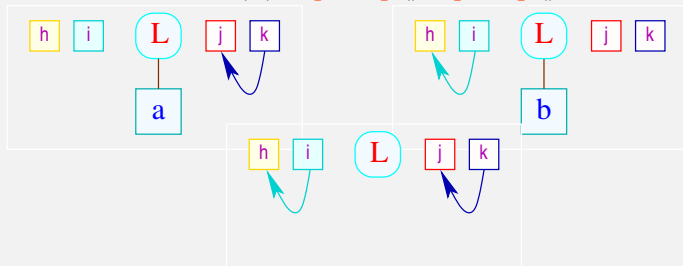
# Example: Strong Acyclic Test

Given grammar  $S \rightarrow L, L \rightarrow a \mid b$ . Dependency graphs  $D_p$ :



# Example: Strong Acyclic Test

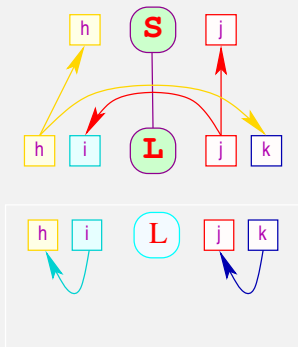
Start with computing  $\mathcal{R}(L) = \llbracket L \rightarrow a \rrbracket^\#() \sqcup \llbracket L \rightarrow b \rrbracket^\#()$ :



- 1 terminal symbols do not contribute dependencies check for cycles!
- 2 transitive closure of all relations in  $(D(L \rightarrow a))^+$  and  $(D(L \rightarrow b))^+$
- 3 apply  $\pi_0$
- 4  $\mathcal{R}(L) = \{(k, j), (i, h)\}$

## Example: Strong Acyclic Test

Continue with  $\mathcal{R}(S) = \llbracket S \rightarrow L \rrbracket^\#(\mathcal{R}(L))$ :

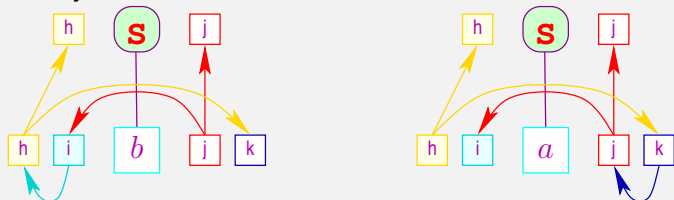


- 1 re-decorate and embed  $\mathcal{R}(L)[1]$
- 2 transitive closure of all relations  
 $(D(S \rightarrow L) \cup \{(k[1], j[1])\} \cup \{(i[1], h[1])\})^+$
- 3 apply  $\pi_0$
- 4  $\mathcal{R}(S) = \{\}$

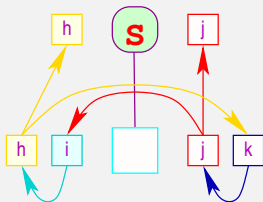
check for cycles!

# Strong Acyclic and Acyclic

The grammar  $S \rightarrow L, L \rightarrow a \mid b$  has only two derivation trees which are both acyclic:



It is *not strongly acyclic* since the over-approximated global dependence graph for the non-terminal  $L$  contributes to a cycle when computing  $\mathcal{R}(S)$ :

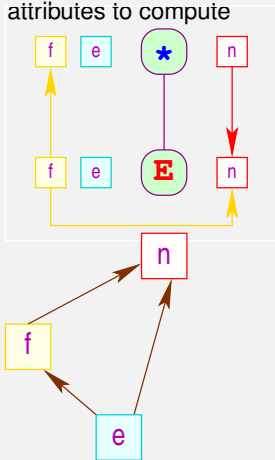




# From Dependencies to Evaluation Strategies

## Possible strategies:

- 1 let the *user* define the evaluation order
- 2 *automatic* strategy based on the dependencies:
  - use local dependencies to determine which attributes to compute
    - suppose we require  $n[1]$
    - computing  $n[1]$  requires  $f[1]$
    - $f[1]$  depends on an attribute in the child, so descend
  - compute attributes in passes
    - compute a dependency graph between attributes (no go if cyclic)
    - traverse AST once for each attribute; here three times, once for  $e$ ,  $f$ ,  $n$
    - compute one attribute in each pass
- 3 consider a *fixed* strategy and only allow an attribute system that can be evaluated using this strategy



# Linear Order from Dependency Partial Order

Possible *automatic* strategies:

## 1 demand-driven evaluation

- start with the evaluation of any required attribute
- if the equation for this attribute relies on as-of-yet unevaluated attributes, evaluate these recursively

## 2 evaluation in passes

for each pass, pre-compute a *global strategy* to visit the *nodes* together with a *local strategy* for evaluation *within each node* type

~> *minimize* the number of *visits* to each node



# Demand-Driven Evaluation

## Observations

- each node must contain a pointer to its parent
- *only required* attributes are evaluated
- the evaluation sequence depends – in general – on the actual syntax tree
- the algorithm must track which attributes it has already evaluated
- the algorithm may visit nodes more often than necessary
- ↪ the algorithm is *not local*

in principle:

- evaluation strategy is dynamic: difficult to debug
- usually all attributes in all nodes are required
- ↪ computation of all attributes is often cheaper
- ↪ perform evaluation in *passes*

# Evaluation in Passes

**Idea:** traverse the syntax tree several times; each time, evaluate all those equations  $a[i_a] = f(b[i_b], \dots, z[i_z])$  whose arguments  $b[i_b], \dots, z[i_z]$  are evaluated as-of-yet

## Strongly Acyclic Attribute Systems'

attributes have to be evaluated for each production  $p$  according to

$$D(p) \cup \mathcal{R}^*(X_1)[1] \cup \dots \cup \mathcal{R}^*(X_k)[k]$$

### Implementation

- determine a sequence of child visitations such that the most number of attributes are possible to evaluate
- in each pass at least one new attribute is evaluated
  - requires at most  $n$  passes for evaluating  $n$  attributes
  - find a strategy to evaluate more attributes

~> optimization problem

**Note:** evaluating attribute set  $\{a[0], \dots, z[0]\}$  for rule  $N \rightarrow \dots N \dots$  may evaluate a different attribute set of its children

~>  $2^k - 1$  evaluation functions for  $N$  (with  $k$  as the number of attributes)

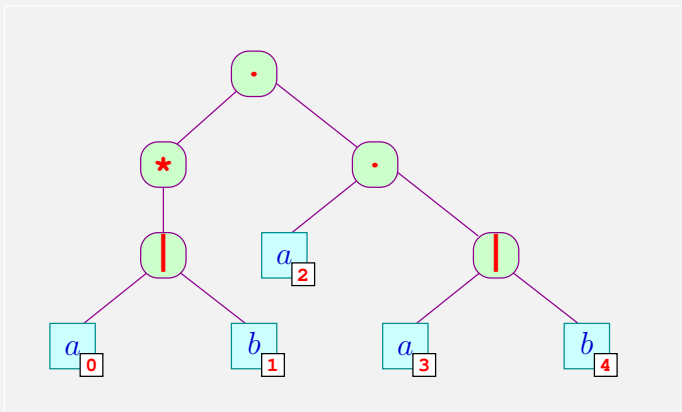
... in the example:

- empty and first can be computed together
- next must be computed in a separate pass

# Implementing State

**Problem:** In many cases some sort of state is required.

**Example:** numbering the leaves of a syntax tree



## Example: Implementing Numbering of Leafs

Idea:

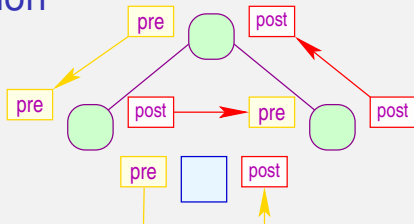
- use **helper** attributes **pre** and **post**
- in **pre** we pass the value for the first leaf down (inherited attribute)
- in **post** we pass the value of the last leaf up (synthetic attribute)

```
root:  pre[0] := 0  
       pre[1] := pre[0]  
       post[0] := post[1]
```

```
node:  pre[1] := pre[0]  
       pre[2] := post[1]  
       post[0] := post[2]
```

```
leaf:  post[0] := pre[0] + 1
```

# L-Attribution



- the attribute system is apparently strongly acyclic
- each node computes
  - the inherited attributes before descending into a child node (corresponding to a pre-order traversal)
  - the synthetic attributes after returning from a child node (corresponding to post-order traversal)

## Definition L-Attributed Grammars

An attribute system is *L*-attributed, if for all productions  $S \rightarrow S_1 \dots S_n$  every inherited attribute of  $S_j$  where  $1 \leq j \leq n$  only depends on

- 1 the attributes of  $S_1, S_2, \dots, S_{j-1}$  and
- 2 the inherited attributes of  $S$ .



# L-Attribution

## Background:

- the attributes of an  $L$ -attributed grammar can be evaluated during parsing
- important if no syntax tree is required or if error messages should be emitted while parsing
- example: pocket calculator

$L$ -attributed grammars have a fixed evaluation strategy:  
a single *depth-first* traversal

- in general: partition all attributes into  $\mathcal{A} = A_1 \cup \dots \cup A_n$  such that for all attributes in  $A_i$  the attribute system is  $L$ -attributed
- perform a *depth-first* traversal for each attribute set  $A_i$

$\leadsto$  craft attribute system in a way that they can be partitioned into few  $L$ -attributed sets

# Practical Applications

- symbol tables, type checking/inference, and simple code generation can all be specified using  $L$ -attributed grammars
- most applications *annotate* syntax trees with additional information
- the nodes in a syntax tree often have different *types* that depend on the non-terminal that the node represents
- the different types of non-terminals are characterised by the set of attributes with which they are decorated

**Example:** a statement may have two attributes containing valid identifiers: one ingoing (inherited) set and one outgoing (synthesised) set; in contrast, an expression only has an ingoing set

## Implementation of Attribute Systems via a *Visitor*

- class with a method for every non-terminal in the grammar

```
public abstract class Regex {  
    public abstract void accept(Visitor v);  
}
```

- attribute-evaluation works via *pre-order / post-order callbacks*

```
public interface Visitor {  
    default void pre(OrEx re) {}  
    default void pre(AndEx re) {}  
    ...  
    default void post(OrEx re) {}  
    default void post(AndEx re) {}  
}
```

- we pre-define a depth-first traversal of the syntax tree

```
public class OrEx extends Regex {  
    Regex l, r;  
    public void accept(Visitor v) {  
        v.pre(this); l.accept(v); v.inter(this);  
        r.accept(v); v.post(this);  
    }  
}
```

## Example: Leaf Numbering

```
public abstract class AbstractVisitor
    implements Visitor {
    public void pre(OrEx re) { pr(re); }
    public void pre(AndEx re) { pr(re); }
    ...
    public void post(OrEx re) { po(re); }
    public void post(AndEx re) { po(re); }
    abstract void po(BinEx re);
    abstract void in(BinEx re);
    abstract void pr(BinEx re);
}

public class LeafNum extends AbstractVisitor {
    public LeafNum(Regex r) { n.put(r, 0); r.accept(this); }
    public Map<Regex, Integer> n = new HashMap<>();
    public void pr(Const r) { n.put(r, n.get(r)+1); }
    public void pr(BinEx r) { n.put(r.l, n.get(r)); }
    public void in(BinEx r) { n.put(r.r, n.get(r.l)); }
    public void po(BinEx r) { n.put(r, n.get(r.r)); }
}
```

## Chapter 2: Decl-Use Analysis

# Symbol Tables

Consider the following Java code:

```
void foo() {  
    int A;  
    while(true) {  
        double A;  
        A = 0.5;  
        write(A);  
        break;  
    }  
    A = 2;  
    bar();  
    write(A);  
}
```

- within the body of the loop, the definition of `A` is shadowed by the *local definition*
- each *declaration* of a variable `v` requires allocating memory for `v`
- accessing `v` requires finding the declaration the access is *bound* to
- a binding is not *visible* when a local declaration of the same name is in scope

# Scope of Identifiers

```
void foo() {  
    int A;  
    while (true) {  
        double A;  
        A = 0.5;  
        write(A);  
        break;  
    }  
    A = 2;  
    bar();  
    write(A);  
}
```

scope of `int A`

scope of

`double A`

administration of identifiers can be quite complicated...

# Resolving Identifiers

**Observation:** each identifier in the AST must be translated into a memory access

**Problem:** for each identifier, find out what memory needs to be accessed by providing *rapid* access to its *declaration*

**Idea:**

- 1 *rapid* access: replace every identifier by a *unique* integer
  - integers as keys: comparisons of integers is faster
- 2 link each usage of a variable to the *declaration* of that variable
  - for languages without explicit declarations, create declarations when a variable is first encountered



# Rapid Access: Replace Strings with Integers

## Idea for Algorithm:

**Input:** a sequence of strings

- Output:**
- 1 sequence of numbers
  - 2 table that allows to retrieve the string that corresponds to a number

Apply this algorithm on each identifier during *scanning*.

## Implementation approach:

- count the number of new-found identifiers in **int** `count`
- maintain a *hashtable*  $S : \text{String} \rightarrow \text{int}$  to remember numbers for known identifiers

We thus define the function:

```
int indexForIdentifier(String w) {  
    if ( $S(w) \equiv \text{undefined}$ ) {  
         $S = S \oplus \{w \mapsto \text{count}\}$ ;  
        return count++;  
    } else return  $S(w)$ ;  
}
```

# Implementation: Hashtables for Strings

- 1 allocate an array  $M$  of sufficient size  $m$
- 2 choose a *hash function*  $H : \text{String} \rightarrow [0, m - 1]$  with:
  - $H(w)$  is *cheap* to compute
  - $H$  distributes the occurring words *equally* over  $[0, m - 1]$

Possible generic choices for sequence types ( $\vec{x} = \langle x_0, \dots, x_{r-1} \rangle$ ):

$$H_0(\vec{x}) = (x_0 + x_{r-1}) \% m$$

$$H_1(\vec{x}) = (\sum_{i=0}^{r-1} x_i \cdot p^i) \% m$$

$$H_1(\vec{x}) = (x_0 + p \cdot (x_1 + p \cdot (\dots + p \cdot x_{r-1} \dots))) \% m$$

for some prime number  $p$  (e.g. 31)

**x** The hash value of  $w$  *may not be unique!*

→ Append  $(w, i)$  to a linked list located at  $M[H(w)]$

- Finding the index for  $w$ , we compare  $w$  with all  $x$  for which

$$H(w) = H(x)$$

✓ access on average:

insert:  $\mathcal{O}(1)$

lookup:  $\mathcal{O}(1)$



# Refer Uses to Declarations: Symbol Tables

Check for the correct usage of variables:

- Traverse the syntax tree in a suitable sequence, such that
  - each declaration is visited **before** its use
  - the currently visible declaration is the last one visited
- $\rightsquigarrow$  perfect for an L-attributed grammar
  - equation system for basic block must add and remove identifiers
- for each identifier, we manage a **stack** of declarations
  - 1 if we visit a **declaration**, we push it onto the stack of its identifier
  - 2 upon leaving the **scope**, we remove it from the stack
- if we visit a **usage** of an identifier, we pick the top-most declaration from its stack
- if the stack of the identifier is empty, we have found an undeclared identifier

## Example: A Table of Stacks

```
1 // Abstract locations in comments
2 {
3   int a, b; // V, W
4   b = 5;
5   if (b>3) {
6     int a, c; // X, Y
7     a = 3;
8     c = a + 1;
9     b = c;
10  } else {
11    int c; // Z
12    c = a + 1;
13    b = c;
14  }
15  b = a + b;
16 }
```

0	a
1	b
2	c

V
W

0	a
1	b
2	c

X	V
	W
	Y

0	a
1	b
2	c

V
W
Z

0	a
1	b
2	c

V
W

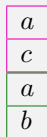


## Alternative Implementations for Symbol Tables

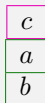
- when using a list to store the symbol table, storing a marker indicating the old head of the list is sufficient



in front of if-statement



then-branch



else-branch

- instead of lists of symbols, it is possible to use a list of hash tables  $\leadsto$  more efficient in large, shallow programs
- an even more elegant solution: *persistent trees* (updates return fresh trees with references to the old tree where possible)
  - $\leadsto$  a persistent tree  $t$  can be passed down into a basic block where new elements may be added, yielding a  $t'$ ; after examining the basic block, the analysis proceeds with the unchanged old  $t$

# Type Definitions in C

A type definition is a *synonym* for a type expression.  
In C they are introduced using the **typedef** keyword.  
Type definitions are useful

- as abbreviation:

```
typedef struct { int x; int y; } point_t;
```

- to construct *recursive* types:

Possible declaration in C:

```
struct list {  
    int info;  
    struct list* next;  
}  
struct list* head;
```

more readable:

```
typedef struct list list_t;  
struct list {  
    int info;  
    list_t* next;  
}  
list_t* head;
```



# Type Definitions in C

The C grammar distinguishes `typedef-name` and `identifier`. Consider the following declarations:

```
typedef struct { int x,y } point_t;
point_t origin;
```

Relevant C grammar:

declaration	→	(declaration-specifier) <sup>+</sup> declarator ;
declaration-specifier	→	static   volatile ... typedef   void   char   char ... typename
declarator	→	identifier   ...

## *Problem:*

- parser adds `point_t` to the table of types when the **declaration** is reduced
- parser state has at least one look-ahead token
- the scanner has already read `point_t` in line two as **identifier**

# Type Definitions in C: Solutions

Relevant C grammar:

```
declaration      → (declaration-specifier)+ declarator ;
declaration-specifier → static | volatile ... typedef
                   | void | char | char ... typename
declarator       → identifier | ...
```

Solution is difficult:

- try to fix the look-ahead inside the parser

- add a rule to the grammar:

```
typename → identifier
```

S/R- & R/R- Conflicts!!

- register type name earlier
  - separate rule for `typedef` production
  - call alternative `declarator` production that registers `identifier` as type name

## Chapter 3: Type Checking

# Goal of Type Checking

In most mainstream (imperative / object oriented / functional) programming languages, variables and functions have a fixed **type**.  
for example: `int`, `void*`, `struct { int x; int y; }`.

Types are useful to

- manage **memory**
- to avoid certain **run-time errors**

In imperative and object-oriented programming languages a declaration has to specify a type. The compiler then checks for a type correct use of the declared entity.

# Type Expressions

Types are given using type-*expressions*.

The set of type expressions  $T$  contains:

- 1 base types: **int**, **char**, **float**, **void**, ...
- 2 type constructors that can be applied to other types

example for type constructors in C:

- structures: **struct** {  $t_1$   $a_1$ ; ...  $t_k$   $a_k$ ; }
- pointers:  $t$  \*
- arrays:  $t$  [ ]
  - the size of an array can be specified
  - the variable to be declared is written between  $t$  and  $[n]$
- functions:  $t(t_1, \dots, t_k)$ 
  - the variable to be declared is written between  $t$  and  $(t_1, \dots, t_k)$
  - in ML function types are written as:  $t_1 * \dots * t_k \rightarrow t$

# Type Checking

## Problem:

**Given:** A set of type declarations  $\Gamma = \{t_1 x_1; \dots t_m x_m; \}$

**Check:** Can an expression  $e$  be given the type  $t$ ?

## Example:

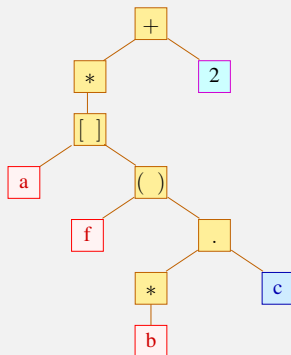
```
struct list { int info; struct list* next; };  
int f(struct list* l) { return l; };  
struct { struct list* c; }* b;  
int* a[11];
```

Consider the expression:

```
*a[f(b->c)]+2;
```

# Type Checking using the Syntax Tree

Check the expression  $*a [ f (b \rightarrow c) ] + 2$ :



## Idea:

- traverse the syntax tree **bottom-up**
- for each identifier, we lookup its type in  $\Gamma$
- constants such as 2 or 0.5 have a fixed type
- the types of the inner nodes of the tree are deduced using *typing rules*

# Type Systems

Formally: consider *judgements* of the form:

$$\Gamma \vdash e : t$$

// (in the type environment  $\Gamma$  the expression  $e$  has type  $t$ )

Axioms:

$$\begin{array}{ll} \text{Const: } \Gamma \vdash c : t_c & (t_c \text{ type of constant } c) \\ \text{Var: } \Gamma \vdash x : \Gamma(x) & (x \text{ Variable}) \end{array}$$

Rules:

$$\text{Ref: } \frac{\Gamma \vdash e : t}{\Gamma \vdash \&e : t^*}$$

$$\text{Deref: } \frac{\Gamma \vdash e : t^*}{\Gamma \vdash *e : t}$$



# Type Systems for C-like Languages

More rules for typing an expression:

$$\text{Array: } \frac{\Gamma \vdash e_1 : t^* \quad \Gamma \vdash e_2 : \mathbf{int}}{\Gamma \vdash e_1[e_2] : t}$$

$$\text{Array: } \frac{\Gamma \vdash e_1 : t[] \quad \Gamma \vdash e_2 : \mathbf{int}}{\Gamma \vdash e_1[e_2] : t}$$

$$\text{Struct: } \frac{\Gamma \vdash e : \mathbf{struct} \{t_1 a_1; \dots t_m a_m;\}}{\Gamma \vdash e.a_i : t_i}$$

$$\text{App: } \frac{\Gamma \vdash e : t(t_1, \dots, t_m) \quad \Gamma \vdash e_1 : t_1 \dots \Gamma \vdash e_m : t_m}{\Gamma \vdash e(e_1, \dots, e_m) : t}$$

$$\text{Op } \square: \frac{\Gamma \vdash e_1 : t \quad \Gamma \vdash e_2 : t}{\Gamma \vdash e_1 \square e_2 : t}$$

$$\text{Explicit Cast: } \frac{\Gamma \vdash e : t_1 \quad t_1 \text{ can be converted to } t_2}{\Gamma \vdash (t_2) e : t_2}$$

# Example: Type Checking

Given expression `*a[f(b->c)]+2` and

$\Gamma = \{$

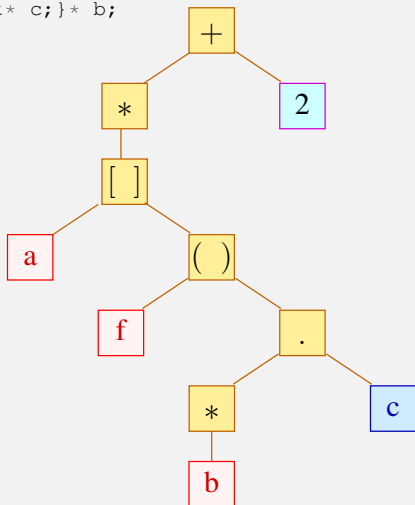
```
struct list { int info; struct list* next; };
```

```
int f(struct list* l);
```

```
struct { struct list* c;}* b;
```

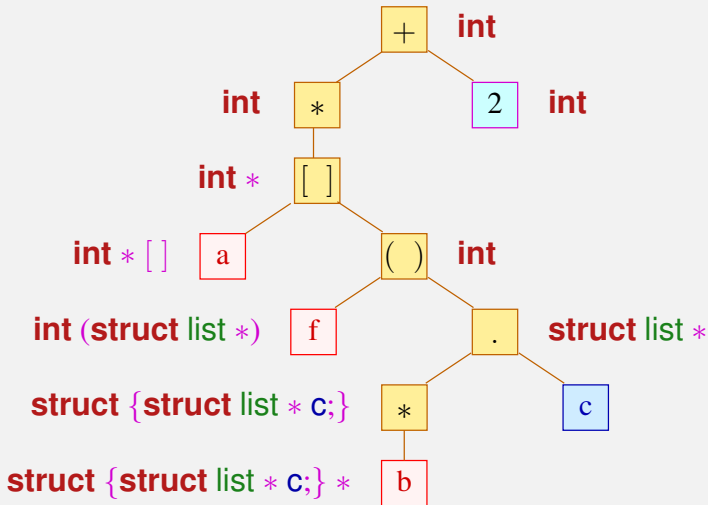
```
int* a[l1];
```

$\}$



# Example: Type Checking

Given expression `*a [ f (b->c) ] +2:`



## Example: Type Checking – More formally:

Given expression  $*a[f(b \rightarrow c)] + 2$ :

$$\begin{array}{c}
 \text{VAR} \frac{}{\Gamma \vdash b : \text{struct}\{\text{struct list } *c;\} *} \\
 \text{DEREF} \frac{}{\Gamma \vdash *b : \text{struct}\{\text{struct list } *c;\}} \\
 \text{STRUCT} \frac{}{\Gamma \vdash (*b).c : \text{struct list} *} \\
 \\
 \text{VAR} \frac{}{\Gamma \vdash a : \text{int} * []} \quad \text{APP} \frac{\text{VAR} \frac{}{\Gamma \vdash f : \text{struct}\{\text{struct list } *c;\} *} \quad \Gamma \vdash (*b).c : \text{struct list} *}{\Gamma \vdash f(b \rightarrow c) : \text{int} \checkmark}}{\Gamma \vdash a[f(b \rightarrow c)] : \text{int} *} \\
 \text{ARRAY} \frac{}{} \\
 \\
 \text{DEREF} \frac{\Gamma \vdash a[f(b \rightarrow c)] : \text{int} *}{\Gamma \vdash *a[f(b \rightarrow c)] : \text{tint}} \quad \text{CONST} \frac{}{\Gamma \vdash 2 : \text{tint} \checkmark} \\
 \text{OP} \frac{}{\Gamma \vdash *a[f(b \rightarrow c)] + 2 : \text{tint}}
 \end{array}$$

# Equality of Types

## Summary of Type Checking

- Choosing which rule to apply at an AST node is determined by the type of the child nodes
- determining the rule requires a check for  $\rightsquigarrow$  *equality* of types

*type equality* in C:

- **struct** A {} and **struct** B {} are considered to be different
  - $\rightsquigarrow$  the compiler could re-order the fields of A and B independently (*not* allowed in C)
  - to extend an record A with more fields, it has to be embedded into another record:

```
struct B {  
    struct A;  
    int field_of_B;  
} extension_of_A;
```

- after issuing **typedef int C**; the types C and **int** are **the same**

# Structural Type Equality

Alternative interpretation of type equality (*does not hold in C*):

*semantically*, two types  $t_1, t_2$  can be considered as *equal* if they accept the same set of access paths.

Example:

```
struct list {  
    int info;  
    struct list* next;  
}
```

```
struct list1 {  
    int info;  
    struct {  
        int info;  
        struct list1* next;  
    }* next;  
}
```

Consider declarations `struct list* l` and `struct list1* l`.  
Both allow

```
l->info  l->next->info
```

but the two declarations of `l` have unequal types in C.

# Algorithm for Testing Structural Equality

## Idea:

- track a set of equivalence queries of type expressions
- if two types are **syntactically** equal, we stop and report success
- otherwise, reduce the equivalence query to a several equivalence queries on (hopefully) **simpler** type expressions

Suppose that recursive types were introduced using type definitions:

```
typedef A t
```

(we omit the  $\Gamma$ ). Then define the following rules:

# Rules for Well-Typedness



typedef  $s$   $A$

**struct**  $\{s_1 a_1; \dots s_m a_m;\}$  **struct**  $\{t_1 a_1; \dots t_m a_m;\}$

$a_1$



...

$a_m$





## Example:

```
typedef struct {int info; A * next;} A
typedef struct {int info; struct {int info; B * next;} * next;} B
```

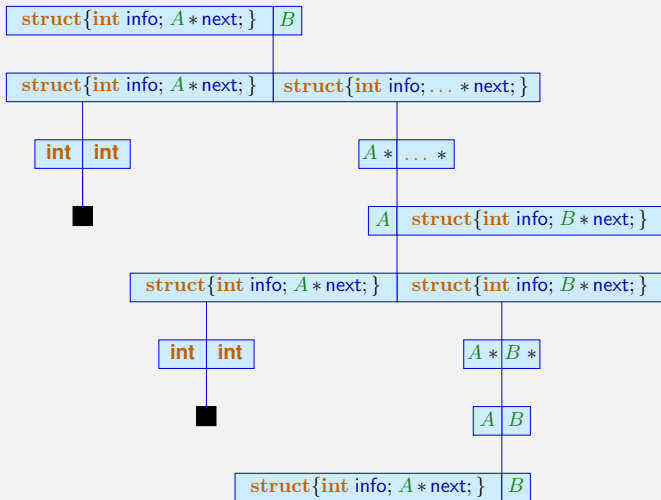
We ask, for instance, if the following equality holds:

$$\text{struct \{int info; A * next;\}} = B$$

We construct the following deduction tree:

# Proof for the Example:

```
typedef struct {int info; A * next;} A  
typedef struct {int info; struct {int info; B * next;} * next;} B
```



# Implementation

We implement a function that implements the equivalence query for two types by applying the deduction rules:

- if no deduction rule applies, then the two types are *not equal*
- if the deduction rule for expanding a type definition applies, the function is called recursively with a *potentially larger* type
- in case an equivalence query appears a second time, the types are *equal by definition*

## Termination

- the set  $D$  of all declared types is finite
- there are no more than  $|D|^2$  different equivalence queries
- repeated queries for the same inputs are automatically satisfied

~> termination is ensured

# Subtypes

On the arithmetic basic types `char`, `int`, `long`, etc. there exists a rich *subtype* hierarchy

## Subtypes

$t_1 \leq t_2$ , means that the values of type  $t_1$

- 1 form a **subset** of the values of type  $t_2$ ;
- 2 can be converted into a value of type  $t_2$ ;
- 3 fulfill the requirements of type  $t_2$ ;
- 4 are assignable to variables of type  $t_2$ .

### Example:

assign smaller type (fewer values) to larger type (more values)

```
 $t_1$   int x;  
 $t_2$   double y;  
y = x;
```

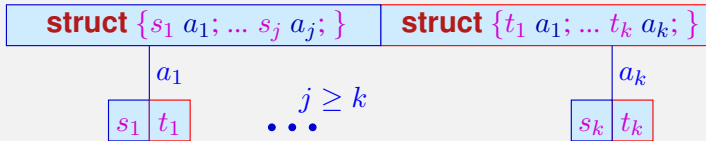
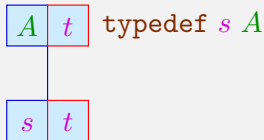
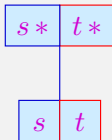
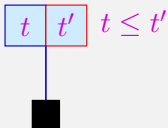
## Example: Subtyping

Extending the subtype relationship to more complex types, observe:

```
string extractInfo( struct { string info; } x) {  
    return x.info;  
}
```

- we want `extractInfo` to be applicable to all argument structures that return a `string` typed field for accessor `info`
- the idea of subtyping on values is related to subclasses
- we use deduction rules to describe when  $t_1 \leq t_2$  should hold...

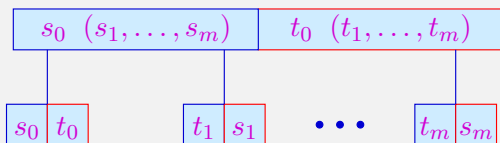
# Rules for Well-Typedness of Subtyping



```

struct {int u, int v} x;
struct {int u} y;
y = x;
    
```

# Rules and Examples for Subtyping



## Examples:

`struct {int a; int b;}`  $\leq$  `struct {float a;}`  
`int (int)`  $\not\leq$  `float (float)`  
`int (float)`  $\leq$  `float (int)`

## Definition

Given two function types in subtype relation

$s_0(s_1, \dots, s_n) \leq t_0(t_1, \dots, t_n)$  then we have

- **co-variance** of the return type  $s_0 \leq t_0$  and
- **contra-variance** of the arguments  $s_i \geq t_i$  für  $1 < i \leq n$

# Subtypes: Application of Rules (I)

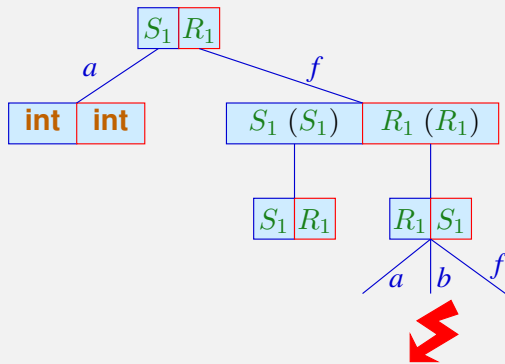
Check if  $S_1 \leq R_1$ :

$R_1 = \text{struct } \{\text{int } a; R_1(R_1) f;\}$

$S_1 = \text{struct } \{\text{int } a; \text{int } b; S_1(S_1) f;\}$

$R_2 = \text{struct } \{\text{int } a; R_2(S_2) f;\}$

$S_2 = \text{struct } \{\text{int } a; \text{int } b; S_2(R_2) f;\}$





# Subtypes: Application of Rules (II)

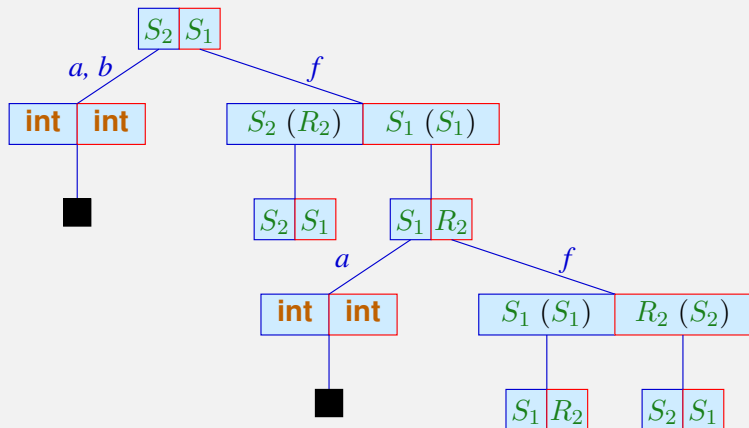
Check if  $S_2 \leq S_1$ :

$R_1 = \text{struct } \{\text{int } a; R_1(R_1) f;\}$

$S_1 = \text{struct } \{\text{int } a; \text{int } b; S_1(S_1) f;\}$

$R_2 = \text{struct } \{\text{int } a; R_2(S_2) f;\}$

$S_2 = \text{struct } \{\text{int } a; \text{int } b; S_2(R_2) f;\}$



# Subtypes: Application of Rules (III)

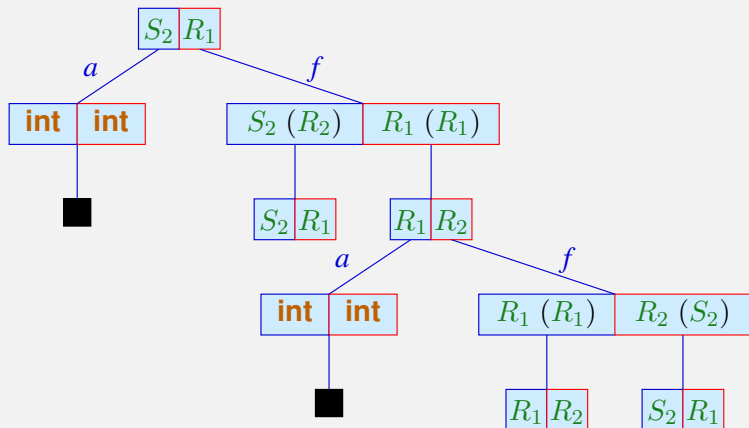
Check if  $S_2 \leq R_1$ :

$R_1 = \text{struct } \{\text{int } a; R_1(R_1) f;\}$

$S_1 = \text{struct } \{\text{int } a; \text{int } b; S_1(S_1) f;\}$

$R_2 = \text{struct } \{\text{int } a; R_2(S_2) f;\}$

$S_2 = \text{struct } \{\text{int } a; \text{int } b; S_2(R_2) f;\}$



# Discussion

- for presentational purposes, proof trees are often abbreviated by omitting deductions within the tree
- structural sub-types are very powerful and can be quite intricate to understand
- **Java** generalizes structs to **objects/classes** where a sub-class  $A$  inheriting from base class  $O$  is a subtype  $A \leq O$
- subtype relations between classes must be **explicitly declared**

Topic:

Code Synthesis

# Generating Code: Overview

We inductively generate instructions from the AST:

- there is a rule stating how to generate code for each non-terminal of the grammar
- the code is merely another attribute in the syntax tree
- code generation makes use of the already computed attributes

In order to specify the code generation, we require

- a semantics of the language we are compiling (here: C standard)
- a semantics of the machine instructions

~> we commence by specifying machine instruction semantics

# Chapter 1: The Register C-Machine

# The Register C-Machine (R-CMa)

We generate Code for the Register C-Machine.

The Register C-Machine is a virtual machine (VM).

- there exists no processor that can execute its instructions
- ... but we can build an interpreter for it
- we provide a visualization environment for the R-CMa
- the R-CMa has no **double**, **float**, **char**, **short** or **long** types
- the R-CMa has no instructions to communicate with the operating system
- the R-CMa has an unlimited supply of registers

The R-CMa is more realistic than it may seem:

- the mentioned restrictions can easily be lifted
- the *Dalvik VM* or the *LLVM* are similar to the R-CMa
- an interpreter of R-CMa can run on any platform

# Virtual Machines

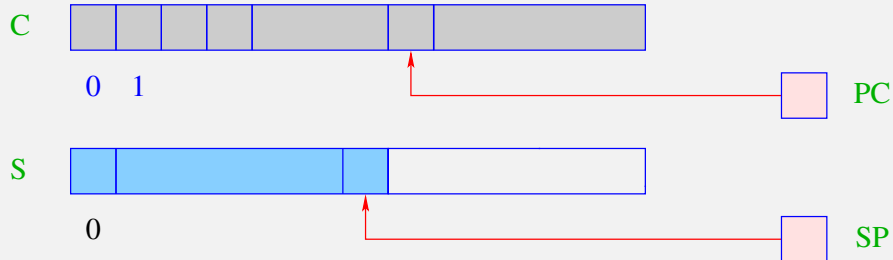
A virtual machine has the following ingredients:

- any virtual machine provides a set of **instructions**
- instructions are executed on virtual hardware
- the virtual hardware is a collection of data structures that is accessed and modified by the VM instructions
- ... and also by other components of the **run-time system**, namely functions that go beyond the instruction semantics
- the **interpreter** is part of the run-time system



# Components of a Virtual Machine

Consider **Java** as an example:



A virtual machine such as the **Dalvik VM** has the following structure:

- **S**: the data store – a memory region in which cells can be stored in LIFO order  $\rightsquigarrow$  **stack**.
- **SP**: ( $\hat{=}$  **stack pointer**) pointer to the last used cell in **S**
- beyond **S** follows the memory containing the heap
- **C** is the memory storing **code**
  - each cell of **C** holds exactly one virtual instruction
  - **C** can only be **read**
- **PC** ( $\hat{=}$  **program counter**) address of the instruction that is to be executed next
- **PC** contains 0 initially

# Executing a Program

- the machine loads an instruction from `C[PC]` into the `instruction register IR` in order to execute it
- before evaluating the instruction, the `PC` is incremented by one

```
while (true) {  
    IR = C[PC]; PC++;  
    execute (IR);  
}
```

- note: the `PC` must be incremented `before` the execution, since an instruction may modify the `PC`
- the loop is exited by evaluating a `halt` instruction that returns directly to the operating system

## Chapter 2: Generating Code for the Register C-Machine

# Simple Expressions and Assignments in R-CMa

**Task:** evaluate the expression  $(1 + 7) * 3$   
that is, generate an instruction sequence that

- computes the value of the expression and
- keeps its value accessible in a reproducible way

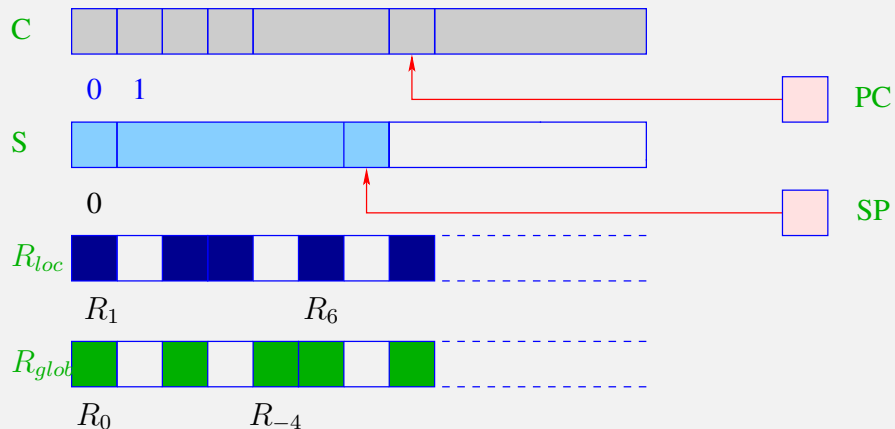
**Idea:**

- first compute the value of the sub-expressions
- store the intermediate result in a temporary register
- apply the operator
- loop

# Principles of the R-CMa

The **R-CMa** is composed of a stack, heap and a code segment, just like the **JVM**; it additionally has register sets:

- *local* registers are  $R_1, R_2, \dots, R_i, \dots$
- *global* registers are  $R_0, R_{-1}, \dots, R_j, \dots$



# The Register Sets of the R-CMa

The two register sets have the following purpose:

- 1 the *local* registers  $R_i$ 
  - save temporary results
  - store the contents of local variables of a function
  - can efficiently be stored and restored from the stack
- 2 the *global* registers  $R_i$ 
  - save the parameters of a function
  - store the result of a function

Note:

for now, we only use registers to store temporary computations

Idea for the translation: use a register counter  $i$ :

- registers  $R_j$  with  $j < i$  are *in use*
- registers  $R_j$  with  $j \geq i$  are *available*

# Translation of Simple Expressions

Using variables stored in registers; loading constants:

instruction	semantics	intuition
loadc $R_i$ $c$	$R_i = c$	load constant
move $R_i$ $R_j$	$R_i = R_j$	copy $R_j$ to $R_i$

We define the following translation schema (with  $\rho$   $x = a$ ):

$$\begin{aligned}\text{code}_{\mathbf{R}}^i c \rho &= \text{loadc } R_i c \\ \text{code}_{\mathbf{R}}^i x \rho &= \text{move } R_i R_a \\ \text{code}_{\mathbf{R}}^i x = e \rho &= \text{code}_{\mathbf{R}}^i e \rho \\ &\quad \text{move } R_a R_i\end{aligned}$$

# Translation of Expressions

Let  $op = \{add, sub, div, mul, mod, le, gr, eq, leq, geq, and, or\}$ .  
The R-CMa provides an instruction for each operator  $op$ .

$$op \ R_i \ R_j \ R_k$$

where  $R_i$  is the target register,  $R_j$  the first and  $R_k$  the second argument.

Correspondingly, we generate code as follows:

$$\begin{aligned} \text{code}_{\mathbb{R}}^i \ e_1 \ op \ e_2 \ \rho &= \text{code}_{\mathbb{R}}^i \ e_1 \ \rho \\ &\quad \text{code}_{\mathbb{R}}^{i+1} \ e_2 \ \rho \\ &\quad op \ R_i \ R_i \ R_{i+1} \end{aligned}$$

**Example:** Translate  $3 * 4$  with  $i = 4$ :

$$\begin{aligned} \text{code}_{\mathbb{R}}^4 \ 3 * 4 \ \rho &= \text{code}_{\mathbb{R}}^4 \ 3 \ \rho \\ &\quad \text{code}_{\mathbb{R}}^5 \ 4 \ \rho \\ \text{code}_{\mathbb{R}}^4 \ 3 * 4 \ \rho &= \text{loadc } R_4 \ 3 \\ &\quad \text{loadc } R_5 \ 4 \\ &\quad \text{mul } R_4 \ R_4 \ R_5 \end{aligned}$$



## Managing Temporary Registers

Observe that temporary registers are re-used: translate  $3 * 4 + 3 * 4$  with  $t = 4$ :

$$\text{code}_{\text{R}}^4 \quad 3 * 4 + 3 * 4 \quad \rho = \begin{array}{l} \text{code}_{\text{R}}^4 \quad 3 * 4 \quad \rho \\ \text{code}_{\text{R}}^5 \quad 3 * 4 \quad \rho \\ \text{add } R_4 \quad R_4 \quad R_5 \end{array}$$

where

$$\text{code}_{\text{R}}^i \quad 3 * 4 \quad \rho = \begin{array}{l} \text{loadc } R_i \quad 3 \\ \text{loadc } R_{i+1} \quad 4 \\ \text{mul } R_i \quad R_i \quad R_{i+1} \end{array}$$

we obtain

$$\text{code}_{\text{R}}^4 \quad 3 * 4 + 3 * 4 \quad \rho = \begin{array}{l} \text{loadc } R_4 \quad 3 \\ \text{loadc } R_5 \quad 4 \\ \text{mul } R_4 \quad R_4 \quad R_5 \\ \text{loadc } R_5 \quad 3 \\ \text{loadc } R_6 \quad 4 \\ \text{mul } R_5 \quad R_5 \quad R_6 \\ \text{add } R_4 \quad R_4 \quad R_5 \end{array}$$

# Semantics of Operators

The operators have the following semantics:

add $R_i R_j R_k$	$R_i = R_j + R_k$
sub $R_i R_j R_k$	$R_i = R_j - R_k$
div $R_i R_j R_k$	$R_i = R_j / R_k$
mul $R_i R_j R_k$	$R_i = R_j * R_k$
mod $R_i R_j R_k$	$R_i = \text{signum}(R_k) \cdot k$ with $ R_j  = n \cdot  R_k  + k \wedge n \geq 0, 0 \leq k <  R_k $
le $R_i R_j R_k$	$R_i = \text{if } R_j < R_k \text{ then } 1 \text{ else } 0$
gr $R_i R_j R_k$	$R_i = \text{if } R_j > R_k \text{ then } 1 \text{ else } 0$
eq $R_i R_j R_k$	$R_i = \text{if } R_j = R_k \text{ then } 1 \text{ else } 0$
leq $R_i R_j R_k$	$R_i = \text{if } R_j \leq R_k \text{ then } 1 \text{ else } 0$
geq $R_i R_j R_k$	$R_i = \text{if } R_j \geq R_k \text{ then } 1 \text{ else } 0$
and $R_i R_j R_k$	$R_i = R_j \ \& \ R_k$ // bit-wise and
or $R_i R_j R_k$	$R_i = R_j \   \ R_k$ // bit-wise or

**Note:** all registers and memory cells contain operands in  $\mathbb{Z}$

# Translation of Unary Operators

Unary operators  $op = \{neg, not\}$  take only two registers:

$$\text{code}_R^i \text{ op } e \ \rho = \begin{array}{l} \text{code}_R^i \ e \ \rho \\ \text{op } R_i \ R_i \end{array}$$

**Note:** We use the same register.

**Example:** Translate  $-4$  into  $R_5$ :

$$\begin{array}{l} \text{code}_R^5 \ -4 \ \rho = \text{code}_R^5 \ 4 \ \rho \\ \text{code}_R^5 \ -4 \ \rho = \text{loadc } R_5 \ 4 \\ \qquad \qquad \qquad \text{neg } R_5 \ R_5 \end{array}$$

The operators have the following semantics:

$$\begin{array}{ll} \text{not } R_i \ R_j & R_i \leftarrow \text{if } R_j = 0 \text{ then } 1 \text{ else } 0 \\ \text{neg } R_i \ R_j & R_i \leftarrow -R_j \end{array}$$

# Applying Translation Schema for Expressions

Suppose the following function is given:

```
void f(void) {  
    int x, y, z;  
    x = y+z*3;  
}
```

- Let  $\rho = \{x \mapsto 1, y \mapsto 2, z \mapsto 3\}$  be the address environment.
- Let  $R_4$  be the first free register, that is,  $i = 4$ .

$$\text{code}^4_{x=y+z*3} \rho = \text{code}^4_{y+z*3} \rho$$

`move  $R_1$   $R_4$`

$$\text{code}^4_{y+z*3} \rho = \text{code}^5_{z*3} \rho$$

`move  $R_4$   $R_2$`   
`add  $R_4$   $R_4$   $R_5$`

$$\text{code}^5_{z*3} \rho = \text{code}^6_3 \rho$$

`move  $R_5$   $R_3$`   
`mul  $R_5$   $R_5$   $R_6$`

$$\text{code}^6_3 \rho = \text{loadc } R_6 \ 3$$

$\leadsto$  the assignment  $x=y+z*3$  is translated as

`move  $R_4$   $R_2$ ; move  $R_5$   $R_3$ ; loadc  $R_6$  3; mul  $R_5$   $R_5$   $R_6$ ; add  $R_4$   $R_4$   $R_5$ ; move  $R_1$   $R_4$`

## Chapter 3: Statements and Control Structures

# About Statements and Expressions

General idea for translation:

$\text{code}_R^i s \rho$  : generate code for statement  $s$

$\text{code}_R^i e \rho$  : generate code for expression  $e$  into  $R_i$

Throughout:  $i, i+1, \dots$  are free (unused) registers

For an *expression*  $x = e$  with  $\rho x = a$  we defined:

$$\text{code}_R^i x = e \rho = \text{code}_R^i e \rho \\ \text{move } R_a R_i$$

However,  $x = e$ ; is also an *expression statement*:

- Define:

$$\text{code}_R^i e_1 = e_2; \rho = \text{code}_R^i e_1 = e_2 \rho$$

The temporary register  $R_i$  is ignored here. More general:

$$\text{code}_R^i e; \rho = \text{code}_R^i e \rho$$

- **Observation:** the assignment to  $e_1$  is a side effect of the evaluating the expression  $e_1 = e_2$ .

# Translation of Statement Sequences

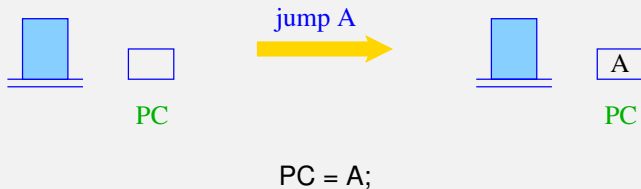
The code for a sequence of statements is the concatenation of the instructions for each statement in that sequence:

$$\begin{aligned} \text{code}^i (s \text{ } ss) \rho &= \text{code}^i s \rho \\ &\quad \text{code}^i ss \rho \\ \text{code}^i \varepsilon \rho &= // \textit{empty sequence of instructions} \end{aligned}$$

Note here:  $s$  is a statement,  $ss$  is a sequence of statements

# Jumps

In order to diverge from the linear sequence of execution, we need *jumps*:





# Conditional Jumps

A conditional jump branches depending on the value in  $R_i$ :



if ( $R_i == 0$ ) PC = A;

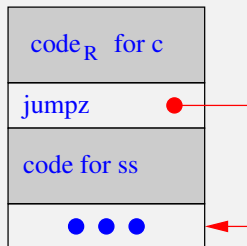
# Simple Conditional

We first consider  $s \equiv \mathbf{if} (c) \ ss$ .

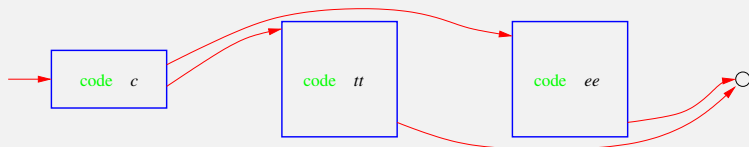
...and present a translation without basic blocks.

Idea:

- emit the code of  $c$  and  $ss$  in sequence
- insert a jump instruction in-between, so that correct control flow is ensured

$$\begin{aligned} \text{code}^i \ s \ \rho &= \text{code}_R^i \ c \ \rho \\ &\quad \text{jumpz } R_i \ A \\ &\quad \text{code}^i \ ss \ \rho \\ A : &\quad \dots \end{aligned}$$


# General Conditional



Translation of **if** (*c*) *tt* **else** *ee*.

$\text{code}^i \text{ if}(c) \text{ } tt \text{ else } ee \rho =$

$\text{code}_R^i c \rho$

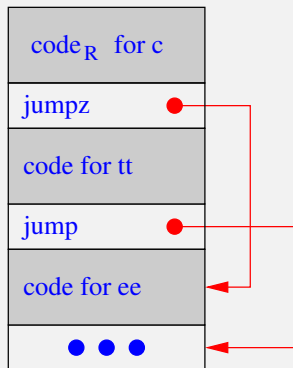
$\text{jumpz } R_i A$

$\text{code}^i tt \rho$

$\text{jump } B$

$A: \text{code}^i ee \rho$

$B:$



# Example for if-statement

Let  $\rho = \{x \mapsto 4, y \mapsto 7\}$  and let  $s$  be the statement

```
if (x>y) {           /* (i) */
  x = x - y;         /* (ii) */
} else {
  y = y - x;         /* (iii) */
}
```

Then `codei s`  $\rho$  yields:

(i)

```
move Ri R4
move Ri+1 R7
gr Ri Ri Ri+1
jumpz Ri A
```

(ii)

```
move Ri R4
move Ri+1 R7
sub Ri Ri Ri+1
move R4 Ri
jump B
```

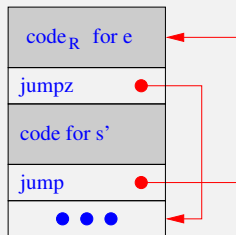
(iii)

```
A : move Ri R7
     move Ri+1 R4
     sub Ri Ri Ri+1
     move R7 Ri
B :
```

# Iterating Statements

We only consider the loop  $s \equiv \mathbf{while} (e) s'$ . For this statement we define:

$code^i \mathbf{while}(e) s \rho = A :$   $code^i_R e \rho$   
 $jumpz R_i B$   
 $code^i s \rho$   
 $jump A$   
  
 $B :$



## Example: Translation of Loops

Let  $\rho = \{a \mapsto 7, b \mapsto 8, c \mapsto 9\}$  and let  $s$  be the statement:

```
while (a>0) {      /* (i) */
    c = c + 1;      /* (ii) */
    a = a - b;      /* (iii) */
}
```

Then  $\text{code}^i s \rho$  evaluates to:

(i)	(ii)	(iii)
A : move $R_i R_7$	move $R_i R_9$	move $R_i R_7$
loadc $R_{i+1} 0$	loadc $R_{i+1} 1$	move $R_{i+1} R_8$
gr $R_i R_i R_{i+1}$	add $R_i R_i R_{i+1}$	sub $R_i R_i R_{i+1}$
jumpz $R_i B$	move $R_9 R_i$	move $R_7 R_i$
		jump A
		B :

# for-Loops

The **for**-loop  $s \equiv \mathbf{for} (e_1; e_2; e_3) s'$  is equivalent to the statement sequence  $e_1; \mathbf{while} (e_2) \{s' e_3; \}$  – as long as  $s'$  does not contain a **continue** statement.

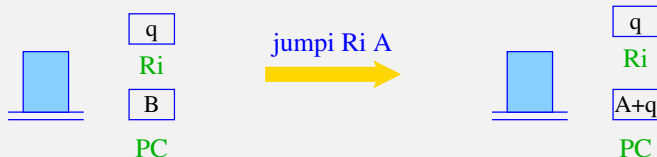
Thus, we translate:

$$\begin{aligned} \text{code}^i \text{ for}(e_1; e_2; e_3) s \rho &= \text{code}_R^i e_1 \rho \\ A : & \text{code}_R^i e_2 \rho \\ & \text{jumpz } R_i B \\ & \text{code}^i s \rho \\ & \text{code}_R^i e_3 \rho \\ & \text{jump } A \\ B : & \end{aligned}$$

# The switch-Statement

## Idea:

- Suppose choosing from multiple options in *constant time* if possible
- use a *jump table* that, at the  $i$ th position, holds a jump to the  $i$ th alternative
- in order to realize this idea, we need an *indirect jump* instruction



$$PC = A + R_i;$$



## Consecutive Alternatives

Let **switch**  $s$  be given with  $k$  consecutive **case** alternatives:

```
switch (e) {  
  case 0:  $s_0$ ; break;  
    
   $\vdots$   
  case  $k-1$ :  $s_{k-1}$ ; break;  
  default:  $s_k$ ; break;  
}
```

Define  $\text{code}^i s \rho$  as follows:

$\text{code}^i s \rho$	=	$\text{code}_R^i e \rho$	
		$\text{check}^i 0 k B$	$B$ : <b>jump</b> $A_0$
$A_0$ :	$\text{code}^i s_0 \rho$	<b>jump</b> $C$	$\vdots$ $\vdots$
$\vdots$	$\vdots$		<b>jump</b> $A_k$
$A_k$ :	$\text{code}^i s_k \rho$	<b>jump</b> $C$	$C$ :

$\text{check}^i l u B$  checks if  $l \leq R_i < u$  holds and jumps accordingly.

## Translation of the $check^i$ Macro

The macro  $check^i l u B$  checks if  $l \leq R_i < u$ . Let  $k = u - l$ .

- if  $l \leq R_i < u$  it jumps to  $B + R_i - l$
- if  $R_i < l$  or  $R_i \geq u$  it jumps to  $A_k$

we define:

```
 $check^i l u B$  = loadc  $R_{i+1} l$   
                  geq  $R_{i+2} R_i R_{i+1}$       B : jump  $A_0$   
                  jumpz  $R_{i+2} E$   
                  sub  $R_i R_i R_{i+1}$           :      :  
                  loadc  $R_{i+1} u$            :      :  
                  geq  $R_{i+2} R_i R_{i+1}$       :      : jump  $A_k$   
                  jumpz  $R_{i+2} D$           C :  
E : loadc  $R_i u - l$   
D : jumpi  $R_i B$ 
```

**Note:** a jump  $jumpi R_i B$  with  $R_i = u$  winds up at  $B + u$ , the default case

# Improvements for Jump Tables

This translation is only suitable for *certain* `switch`-statement.

- In case the table starts with 0 instead of  $u$  we don't need to subtract it from  $e$  before we use it as index
- if the value of  $e$  is **guaranteed** to be in the interval  $[l, u]$ , we can omit *check*

# General translation of switch-Statements

In general, the values of the various cases may be far apart:

- generate an **if**-ladder, that is, a sequence of **if**-statements
- for  $n$  cases, an **if**-cascade (tree of conditionals) can be generated  $\rightsquigarrow O(\log n)$  tests
- if the sequence of numbers has small gaps ( $\leq 3$ ), a jump table may be smaller and faster
- one could generate several jump tables, one for each sets of consecutive cases
- an **if** cascade can be re-arranged by using information from *profiling*, so that paths executed more frequently require fewer tests

# Chapter 4: Functions

# Ingredients of a Function

The definition of a function consists of

- a **name** with which it can be called;
- a specification of its **formal parameters**;
- possibly a **result type**;
- a sequence of **statements**.

In C we have:

$\text{code}_R^i f \rho = \text{loadc } R_i \_f$  with  $\_f$  starting address of  $f$

Observe:

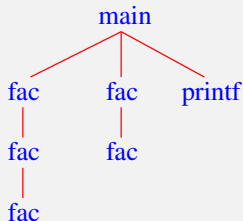
- function names must have an address assigned to them
- since the size of functions is unknown before they are translated, the addresses of forward-declared functions must be inserted later

# Memory Management in Functions

```
int fac(int x) {  
    if (x<=0) return 1;  
    else return x*fac(x-1);  
}  
  
int main(void) {  
    int n;  
    n = fac(2) + fac(1);  
    printf("%d", n);  
}
```

At run-time several **instances** may be active, that is, the function has been called but has not yet returned.

The recursion tree in the example:



# Memory Management in Function Variables

The **formal parameters** and the **local variables** of the various **instances** of a function must be kept separate

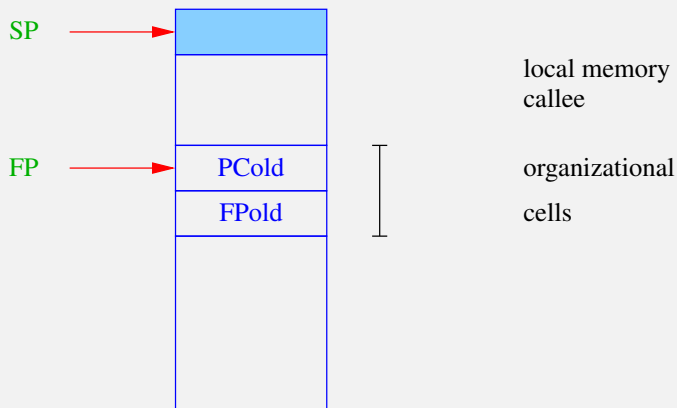
## Idea for implementing functions:

- set up a region of memory each time it is called
- in sequential programs this memory region can be allocated on the stack
- thus, each instance of a function has its own region on the stack
- these regions are called **stack frames**



# Organization of a Stack Frame

- **stack** representation: grows upwards
- **SP** points to the last used stack cell



- **FP**  $\hat{=}$  **frame pointer**: points to the last **organizational cell**
- used to recover the previously active stack frame

# Split of Obligations

## Definition

Let  $f$  be the current function that calls a function  $g$ .

- $f$  is dubbed *caller*
- $g$  is dubbed *callee*

The code for managing function calls has to be split between caller and callee.

This split cannot be done arbitrarily since some information is only known in that caller or only in the callee.

## Observation:

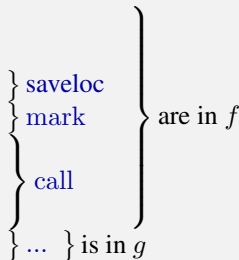
The space requirement for parameters is only known by the caller:

Example: `printf`

# Principle of Function Call and Return

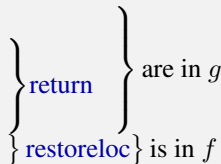
actions taken on **entering**  $g$ :

1. compute the start address of  $g$
2. compute actual parameters in globals
3. backup of **caller**-save registers
4. backup of **FP**
5. set the new **FP**
6. back up of **PC** and  
jump to the beginning of  $g$
7. copy actual params to locals



actions taken on **leaving**  $g$ :

1. compute the result into  $R_0$
2. restore **FP**, **SP**
3. return to the call site in  $f$ ,  
that is, restore **PC**
4. restore the **caller**-save registers



# Managing Registers during Function Calls

The two register sets (global and local) are used as follows:

- automatic variables live in *local* registers  $R_i$
- intermediate results also live in *local* registers  $R_i$
- parameters live in *global* registers  $R_i$  (with  $i \leq 0$ )
- global variables: let's suppose there are none

convention:

- the  $i$ th argument of a function is passed in register  $R_{-i}$
- the result of a function is stored in  $R_0$
- local registers are saved before calling a function

## Definition

Let  $f$  be a function that calls  $g$ . A register  $R_i$  is called

- *caller-saved* if  $f$  backs up  $R_i$  and  $g$  may overwrite it
- *callee-saved* if  $f$  does not back up  $R_i$ , and  $g$  must restore it before returning

# Translation of Function Calls

A function call  $g(e_1, \dots, e_n)$  is translated as follows:

```
codeRi g(e1, ... en) ρ = codeRi g ρ
                             codeRi+1 e1 ρ
                             ⋮
                             codeRi+n en ρ
                             move R-1 Ri+1
                             ⋮
                             move R-n Ri+n
                             saveloc R1 Ri-1
                             mark
                             call Ri
                             restoreloc R1 Ri-1
                             move Ri R0
```

New instructions:

- **saveloc**  $R_i R_j$  pushes the registers  $R_i, R_{i+1} \dots R_j$  onto the stack
- **mark** backs up the organizational cells
- **call**  $R_i$  calls the function at the address in  $R_i$
- **restoreloc**  $R_i R_j$  pops  $R_j, R_{j-1}, \dots R_i$  off the stack

# Rescuing the FP

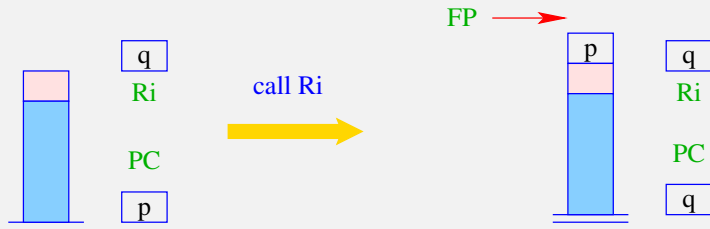
The instruction `mark` allocates stack space for the return value and the organizational cells and backs up `FP`.



```
S[SP+1] = FP;  
SP = SP + 1;
```

# Calling a Function

The instruction `call Ri` rescues the value of `PC+1` onto the stack and sets `FP` and `PC`.



```
SP = SP+1;  
S[SP] = PC;  
FP = SP;  
PC = Ri;
```

## Result of a Function

The global register set is also used to communicate the result value of a function:

$$\text{code}^i \text{ return } e \ \rho = \begin{array}{l} \text{code}_R^i \ e \ \rho \\ \text{move } R_0 \ R_i \\ \text{return} \end{array}$$

alternative without result value:

$$\text{code}^i \text{ return } \rho = \text{return}$$

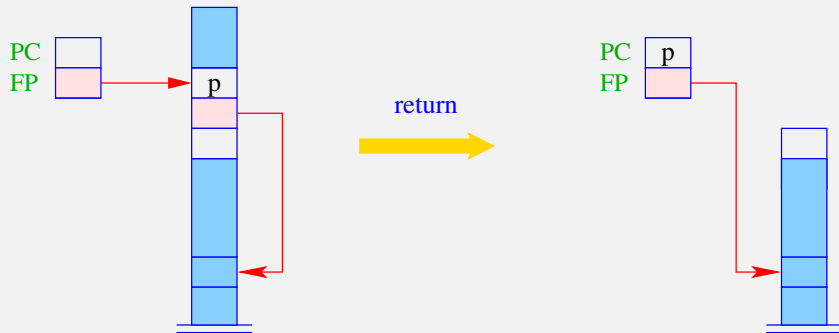
*global* registers are otherwise not used inside a function body:

- advantage: at any point in the body another function can be called without backing up *global* registers
- disadvantage: on entering a function, all *global* registers must be saved



## Return from a Function

The instruction `return` relinquishes control of the current stack frame, that is, it restores `PC` and `FP`.



```
PC = S[FP];  
SP = FP-2;  
FP = S[SP+1];
```

# Translation of Functions

The translation of a function is thus defined as follows:

$$\begin{aligned} \text{code}^l t_r f(\text{args})\{\text{decls } ss\} \rho &= \text{move } R_{l+1} R_{-1} \\ &\quad \vdots \\ &\quad \text{move } R_{l+n} R_{-n} \\ \text{code}^{l+n+1} ss \rho' & \\ \text{return} & \end{aligned}$$

Assumptions:

- the function has  $n$  parameters
- the local variables are stored in registers  $R_1, \dots, R_l$
- the parameters of the function are in  $R_{-1}, \dots, R_{-n}$
- $\rho'$  is obtained by extending  $\rho$  with the bindings in  $\text{decls}$  and the function parameters  $\text{args}$
- **return** is not always necessary

Are the **move** instructions always necessary?

# Translation of Whole Programs

A program  $P = F_1; \dots F_n$  must have a single `main` function.

```
code1 P ρ    =   loadc R1 _main
                  mark
                  call R1
                  halt
    _f1 : code1 F1 ρ ⊕ ρf1
              ⋮
    _fn : code1 Fn ρ ⊕ ρfn
```

Assumptions:

- $\rho = \emptyset$  assuming that we have no global variables
- $\rho_{f_i}$  contain the addresses the local variables
- $\rho_1 \oplus \rho_2 = \lambda x . \begin{cases} \rho_2(x) & \text{if } x \in \text{dom}(\rho_2) \\ \rho_1(x) & \text{otherwise} \end{cases}$

# Translation of the `fac`-function

Consider:

```
int fac(int x) {  
    if (x<=0) then  
        return 1;  
    else  
        return x*fac(x-1);  
}
```

```
_fac:  move R1 R-1  save param.  
i = 2  move R2 R1   if (x<=0)  
       loadc R3 0  
       leq R2 R2 R3  
       jumpz R2 _A  to else  
       loadc R2 1  return 1  
       move R0 R2  
       return  
       jump _B     code is dead
```

```
_A:  move R2 R1      x*fac(x-1)  
     i = 3  move R3 R1      x-1  
     i = 4  loadc R4 1  
           sub R3 R3 R4  
     i = 3  move R-1 R3     fac(x-1)  
           loadc R3 _fac  
           saveloc R1 R2  
           mark  
           call R3  
           restoreloc R1 R2  
           move R3 R0  
           mul R2 R2 R3  
           move R0 R2      return x*...  
           return  
B:  return
```