



• Remember:

The most recent version of the slides can be downloaded at: <a href="http://wwwcg.in.tum.de/Tutorialsl">http://wwwcg.in.tum.de/Tutorialsl</a>

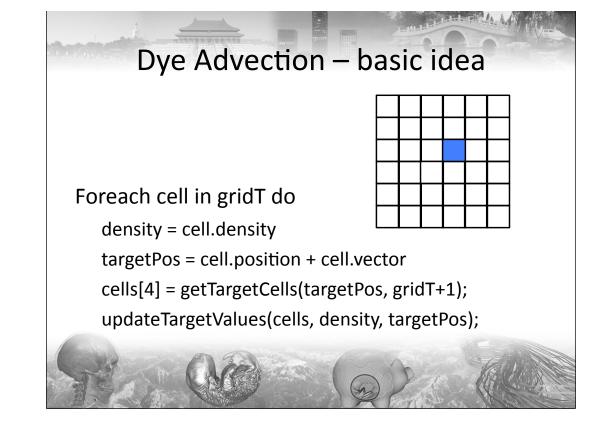


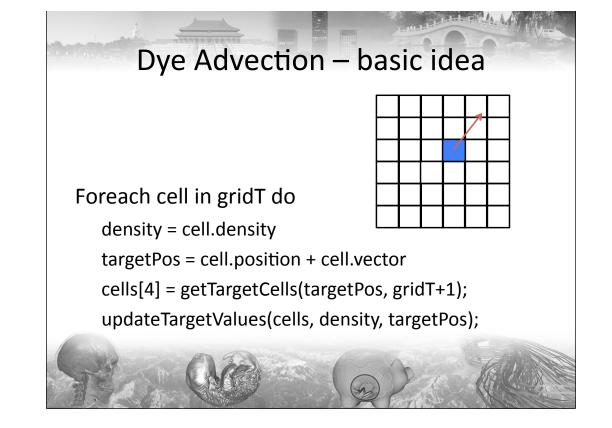


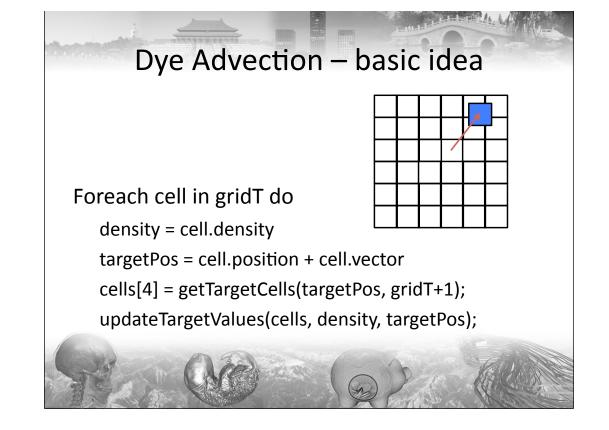
This talk will cover a set of approaches to interactively explore flow fields (given on regular grids, while the methods themselves also work for unstructured grids but for the sake of simplicity most of the implementations are given for regular grids)

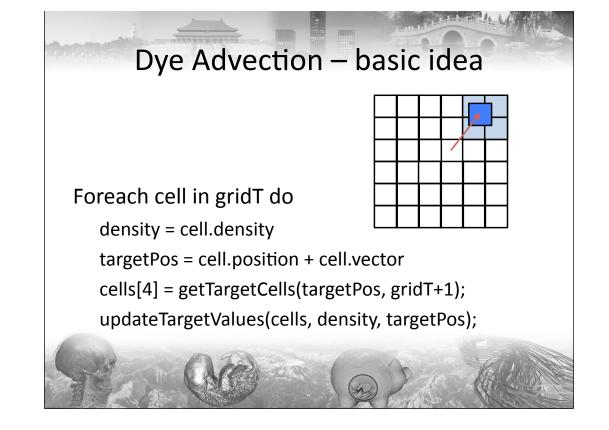


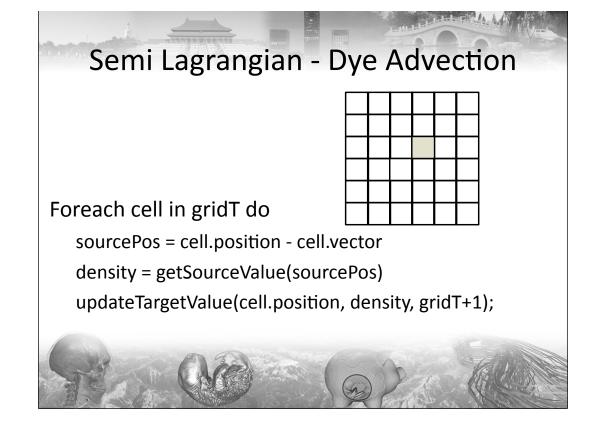
The first method in this talk is the dye advection, that simulates continuous smoke or dye in a flow field.

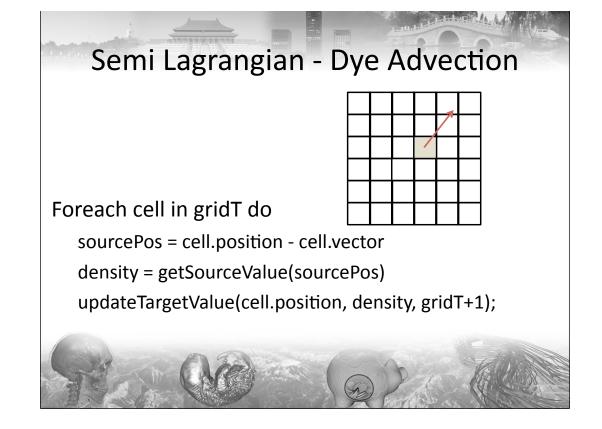


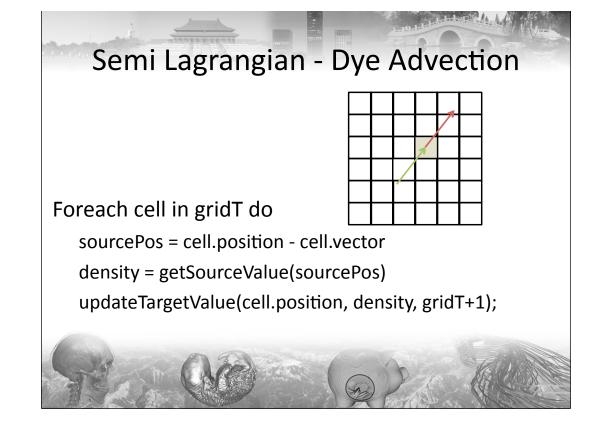


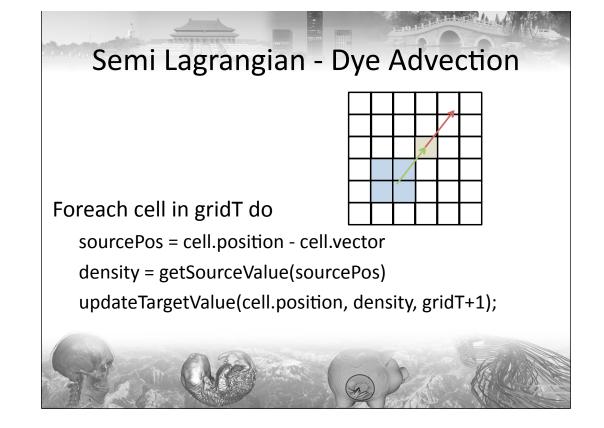


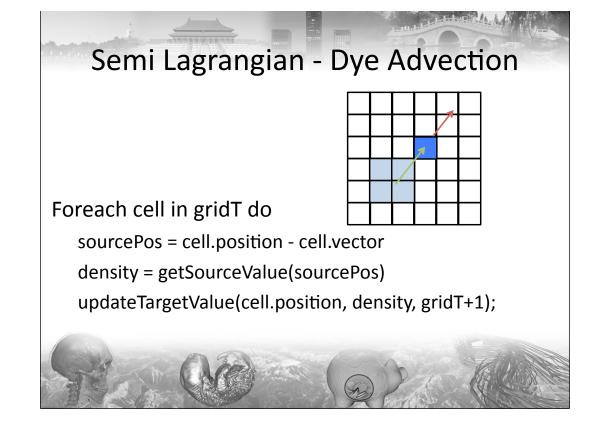


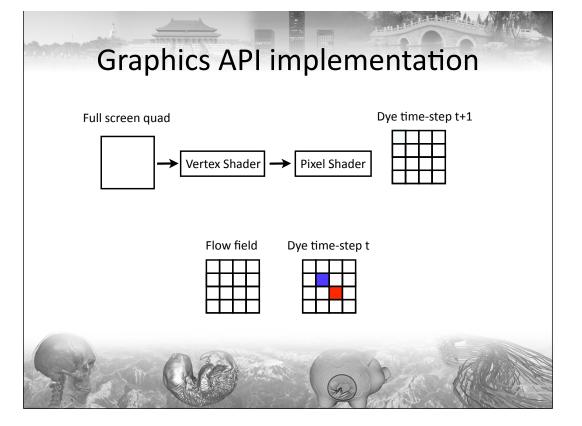


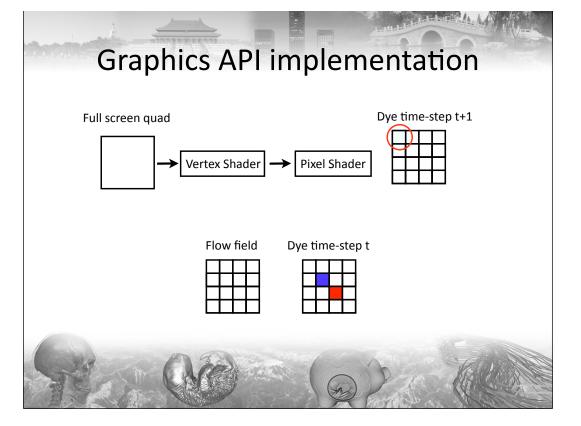


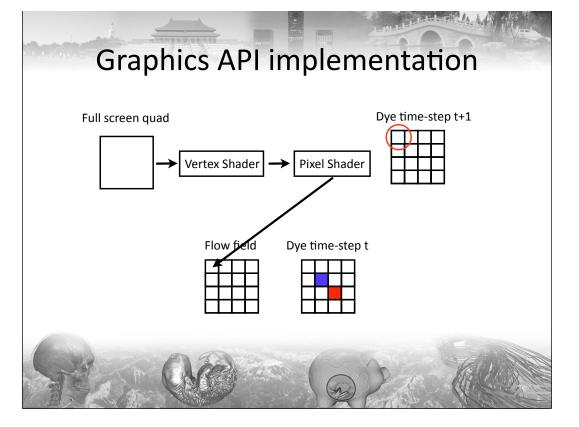


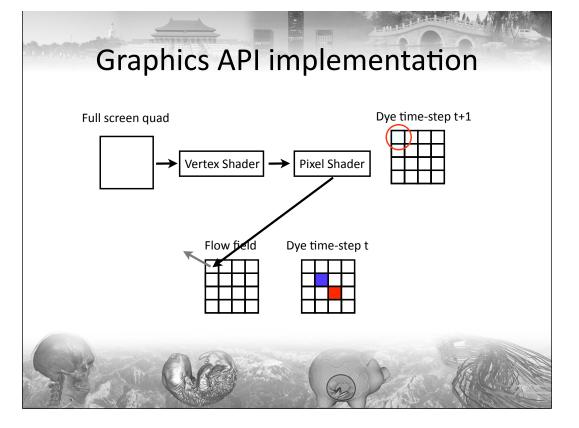


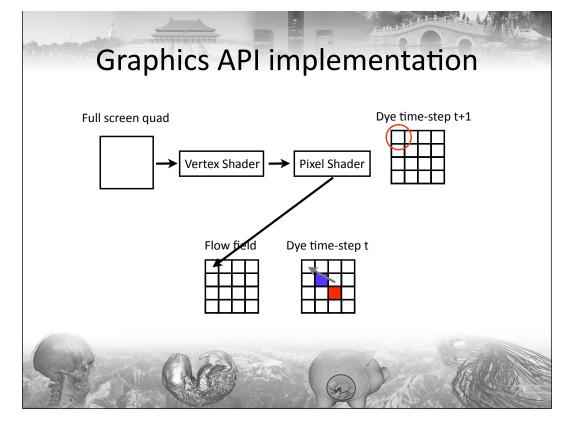


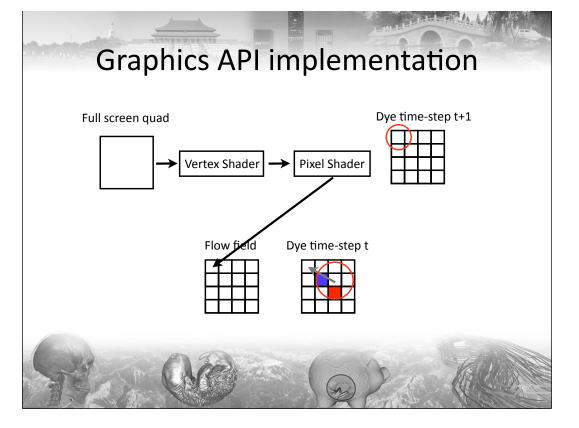


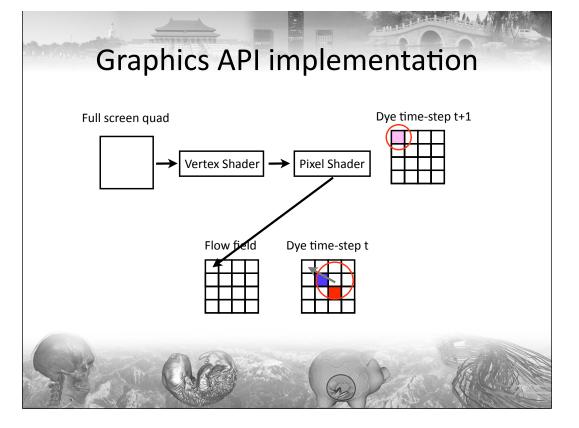


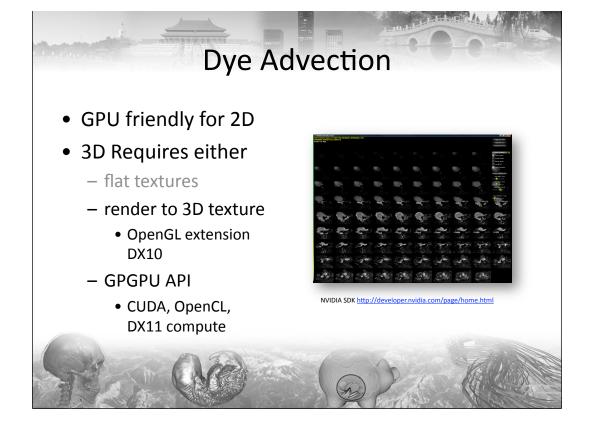




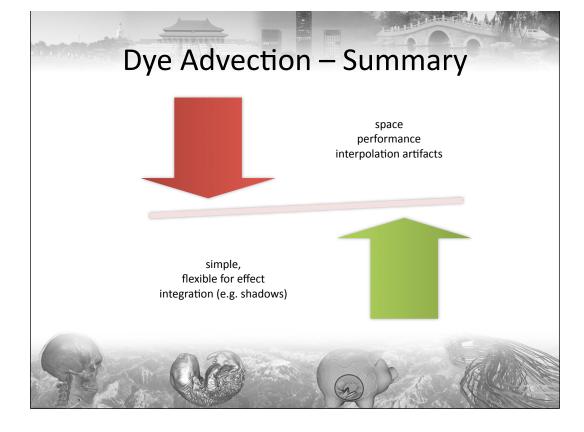




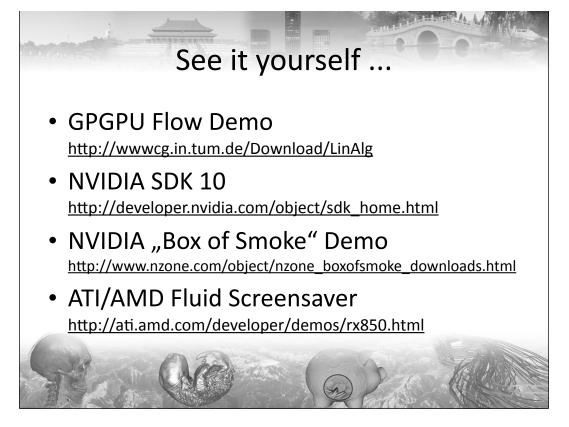




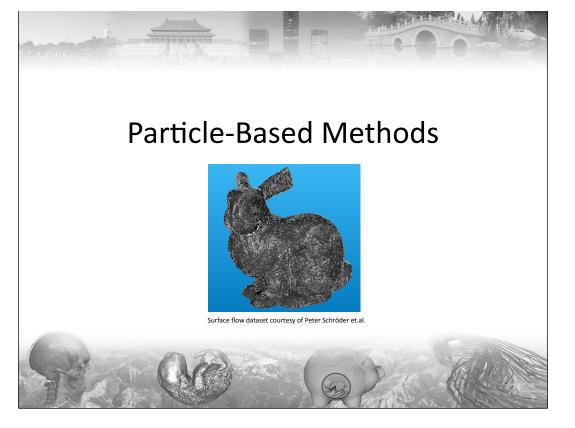
For a 2D grid the implementation of dye advection on the GPU is really straight forward, on a 3D lattice, however, the update of the volume becomes less easy to implement. To handle 3D grids three approaches can be used: - use a stack or an atlas of 2D grids (this limits the size of the volume to whatever fits into a 2D texture, and makes interpolation more complex) - use render to 3D texture if available on the target platform - use arrays in a GPGPU API such as CUDA, OpenCL, or DirectX11 compute shader API



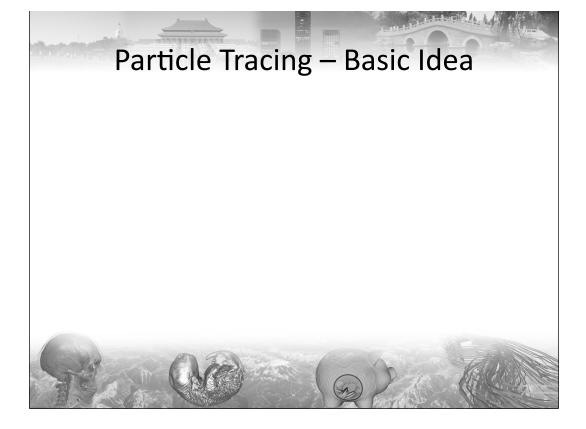
In a nutshell dye advection (at least for 2D) is the most simple approach (try it yourself, this method can be coded in minutes) and it allows for the integration of some "standart" effects, such as volumetric shadows, thus it works best in scenarios where eye candy is needed, e.g. games. On the downside this method requires a lot of space (i.e. a high resolution dye volume) and since in every frame this entire volume must be updated, the performance may be slow. To tackle this aften low resolution grids are used but in that case interpolation artefacts become visible during rendering.

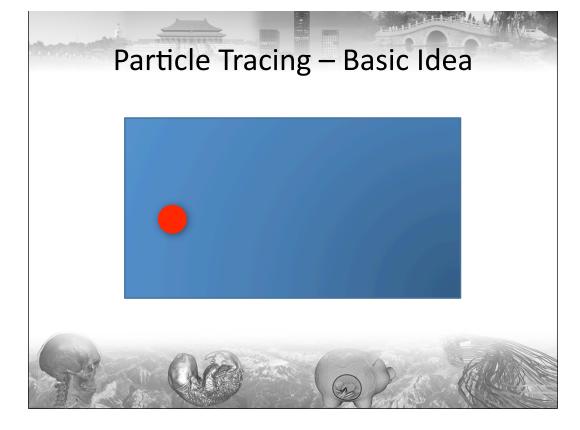


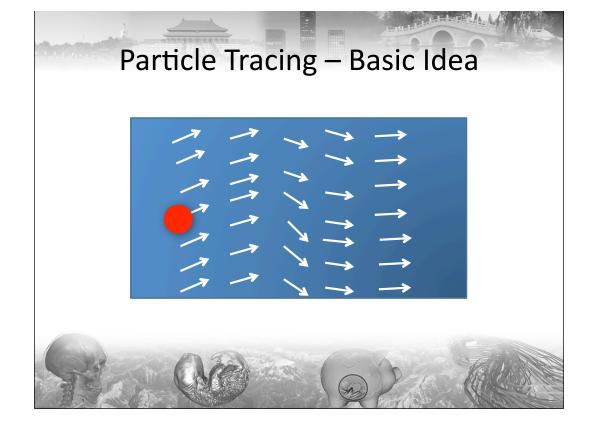
To see the dye advection technique in action, visit these sides, and download and try these demo programs.

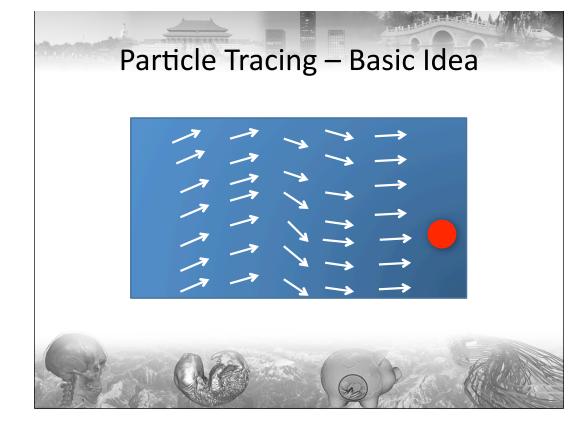


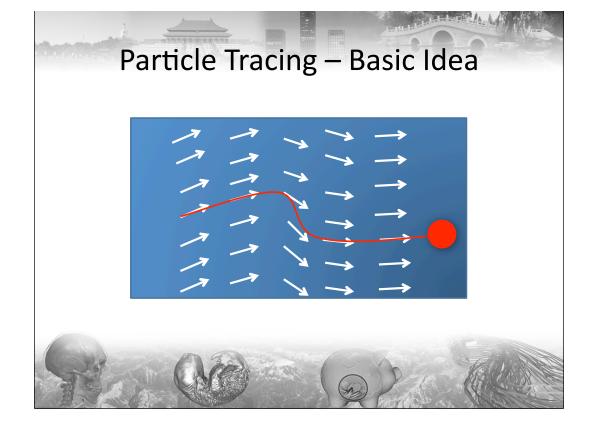
The next family of methods is based on an Eulerian approach, that takes discrete particle quantities in a continuos domain into account.

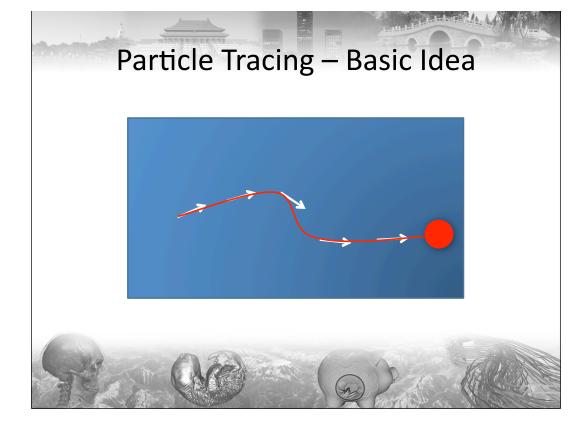


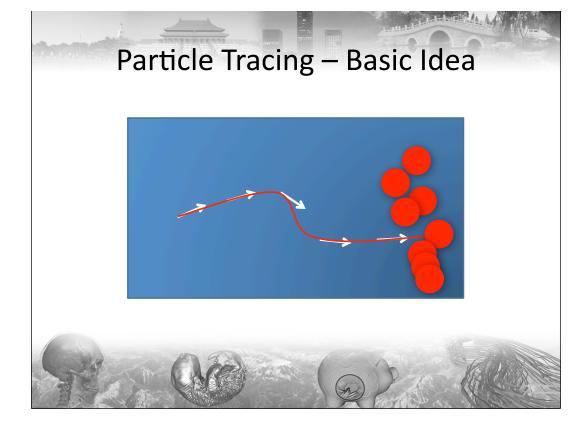


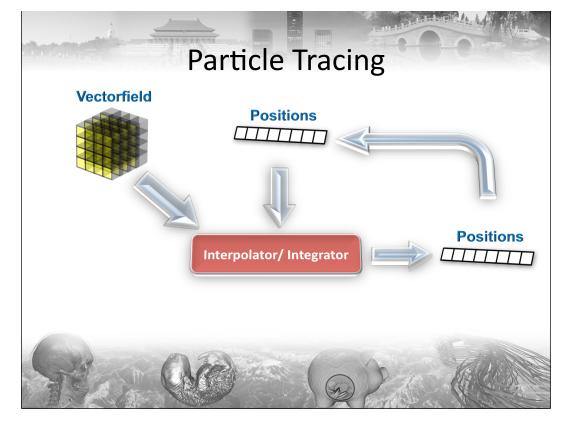




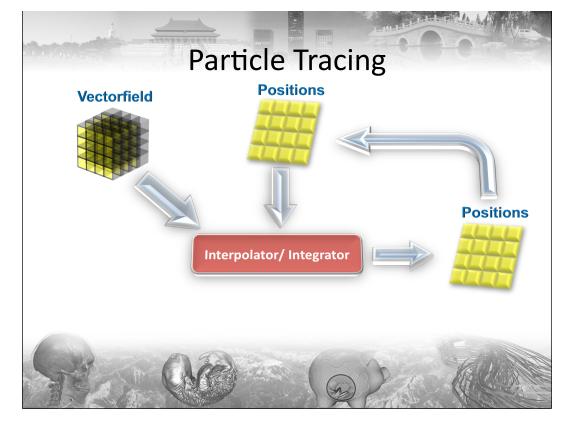




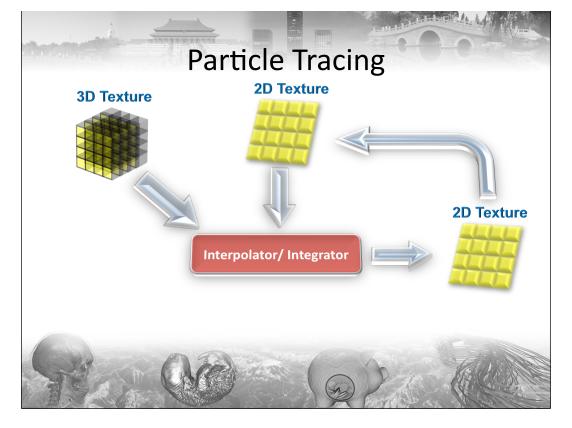




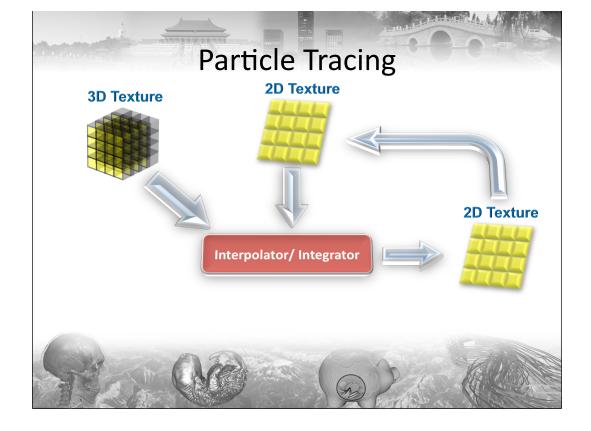
This slide and the next slide demonstrate how particle tracing is achieved on a graphics card. In essence the pixel shader is used to access the vector-field and update the position texture. Note that on newer DirectX 10 class GPUs this process can be done in the geometry shader to update the vertex positions directly, instead of first updating a position texture and then displacing vertices with this texture.

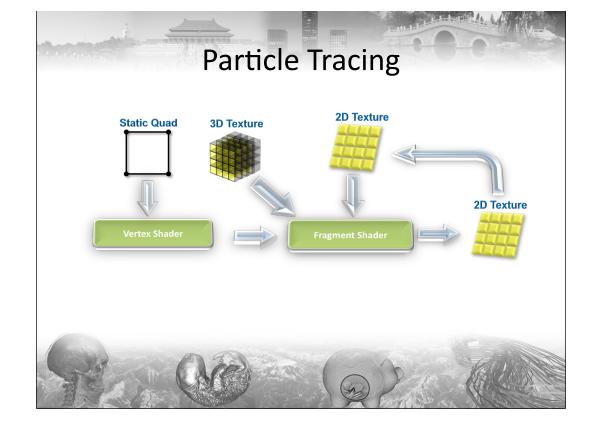


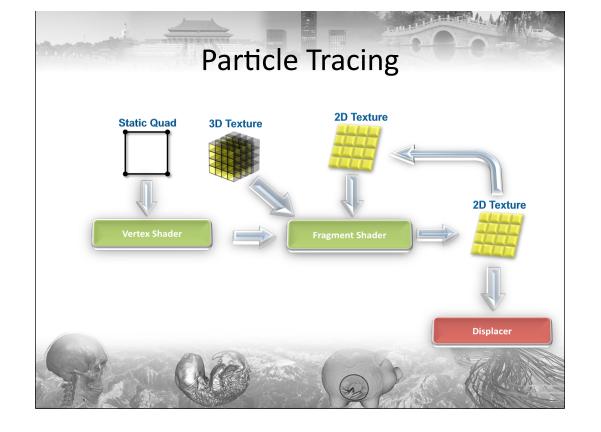
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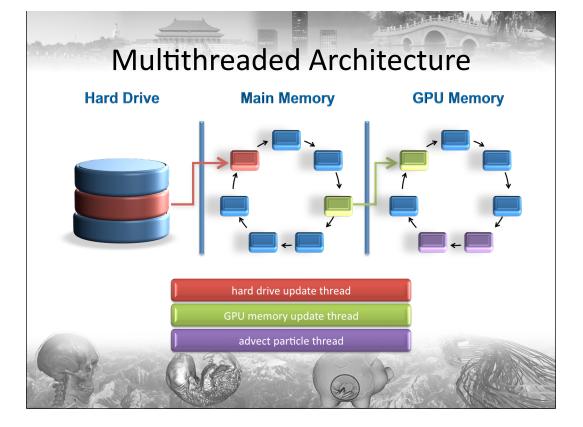


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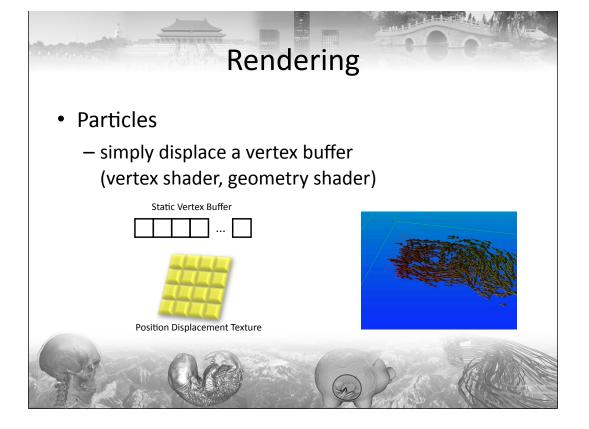








This is just the general theme for large out of core rendering/processing for much more details on this see the large-data talk of this tutorial later today.

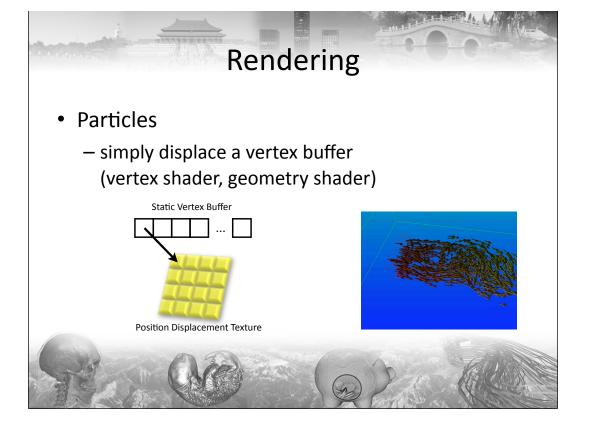


Most simple method, Idea:

Send a static vertex buffer into the pipeline / every element in the vertex shader fetches it's current position from the displacement texture / render displaced vertices as point sprites

If the graphics hardware is DirectX 10 class:

Instead of using the 2D textures in the previous step a vertex buffer can be used in the geometry shader directly in this case no explicit displacement is necessary

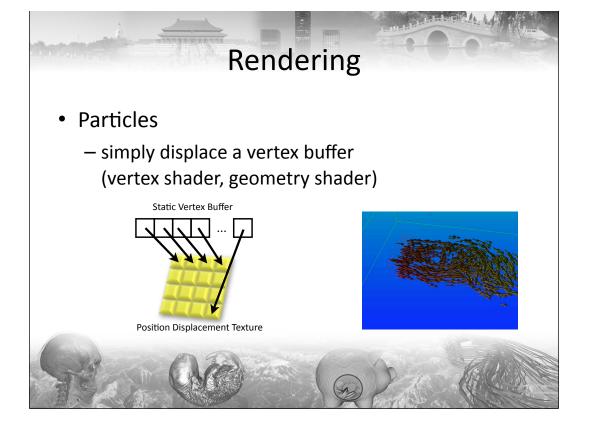


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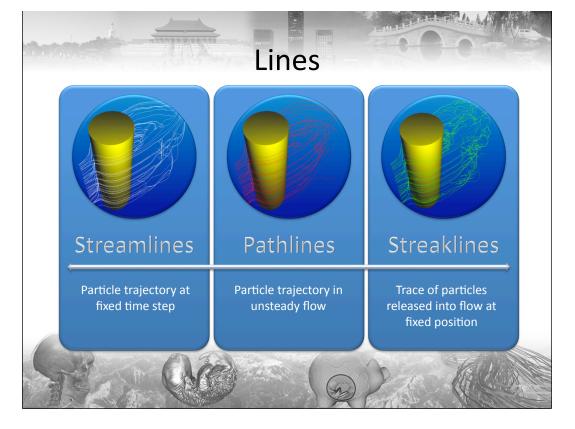


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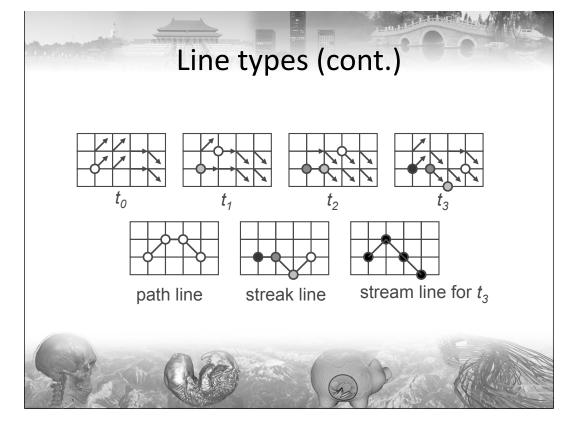


In an unsteady flow field there are three different possibilities to trace lines: Streamlines, where the entire line is recomputed for every time-step (a somehwat artificial method)

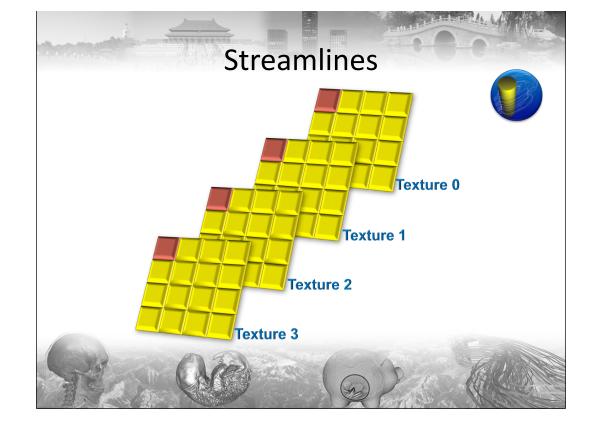
Pathlines, that use the time t during the advection to access the corresponding time-step in the flow field (correspond to the path taken by massless particles in the flow)

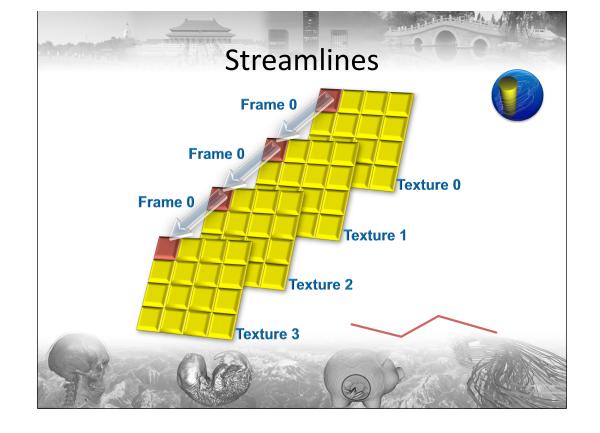
Streaklines, release a new particle every time-step in the flow and always advect all particles (corresponds to ink, advected in the flow)

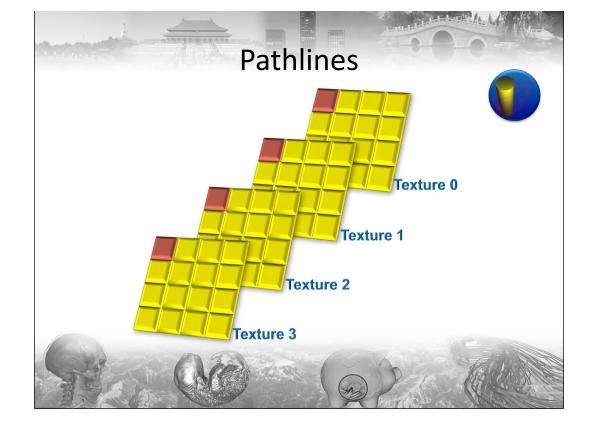
Note that in a steady flow field these three approaches are the same.

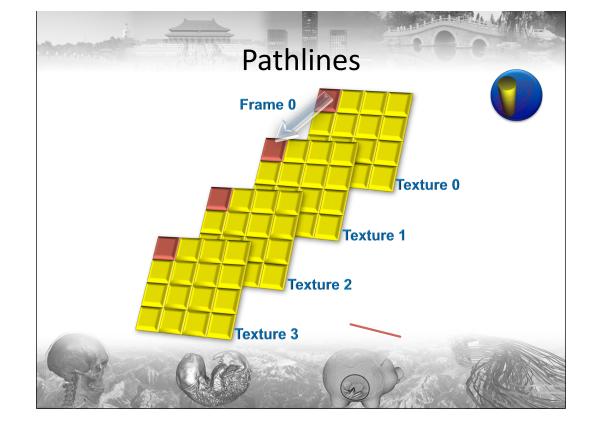


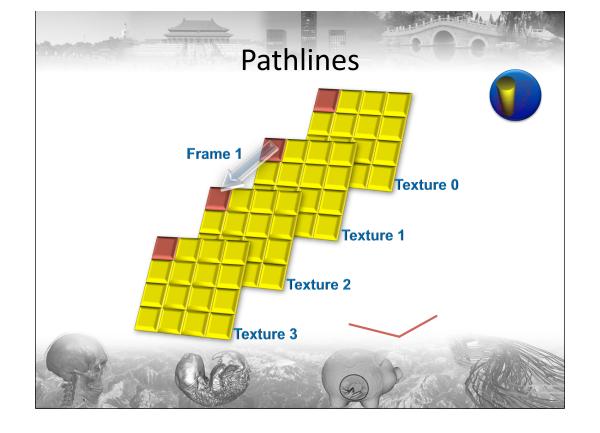
This slide shows the difference of the three methods for a sequence of four time steps in a time dependent flow.

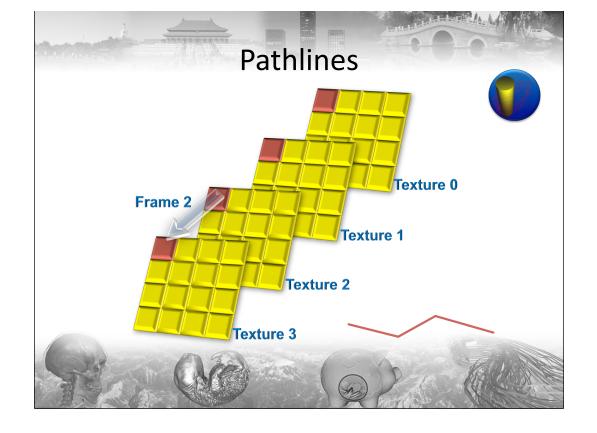


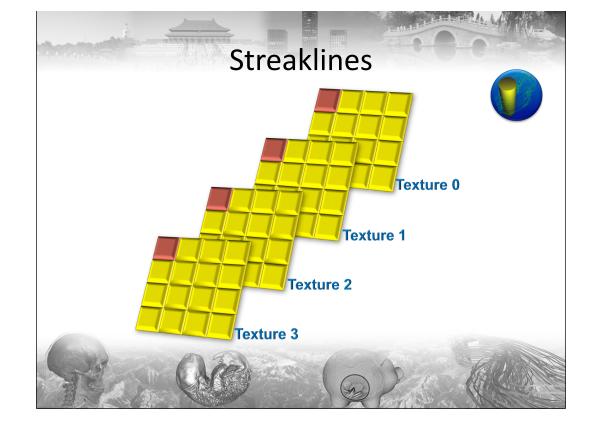


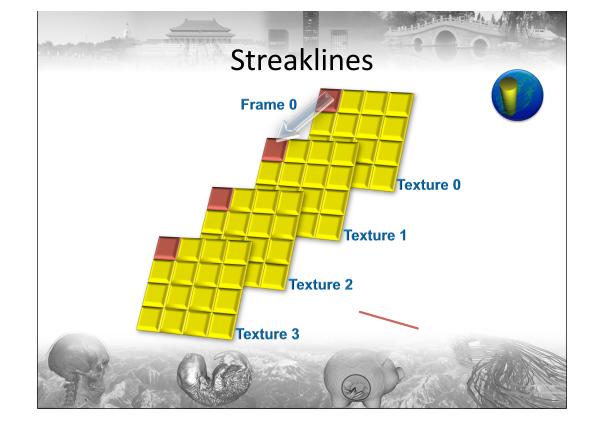


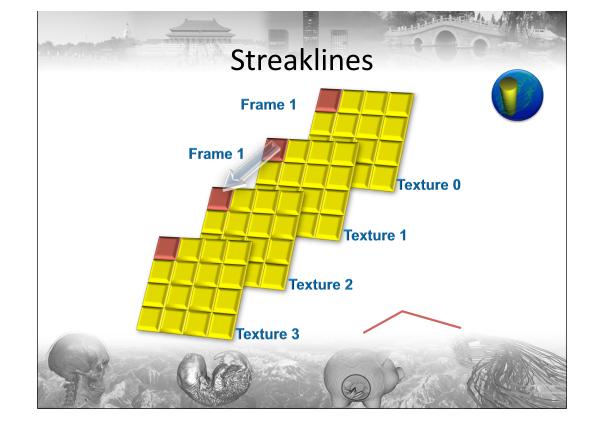


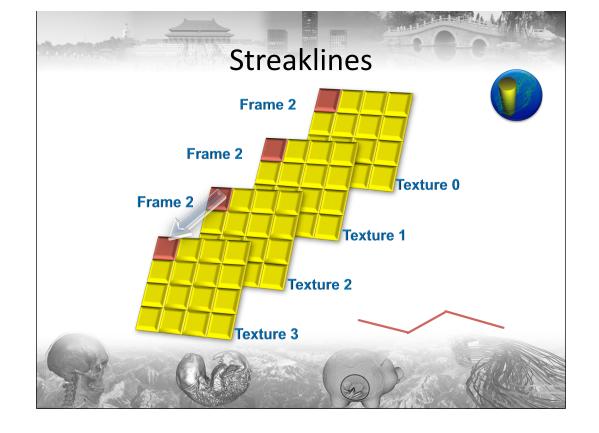


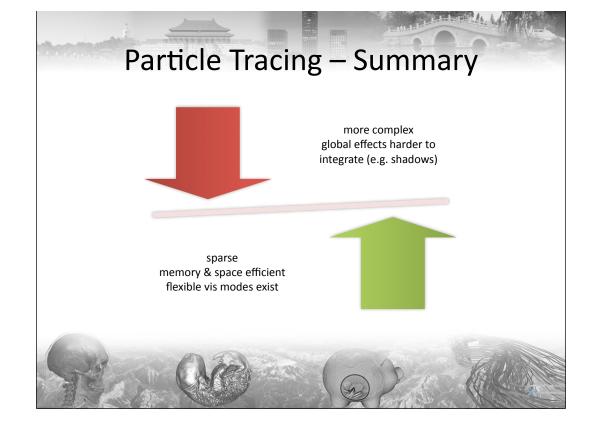


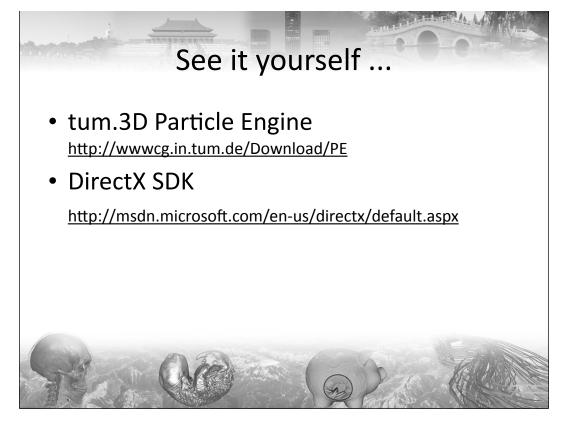


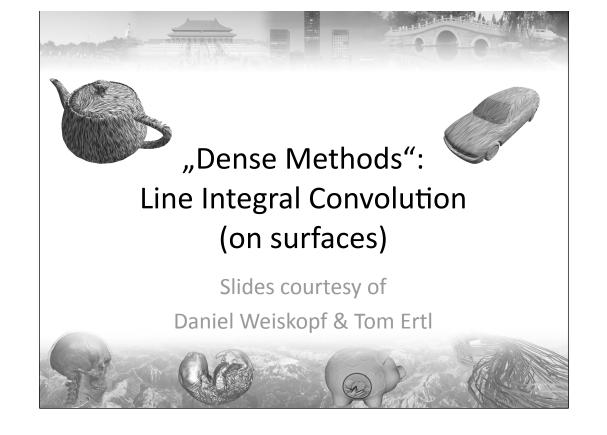


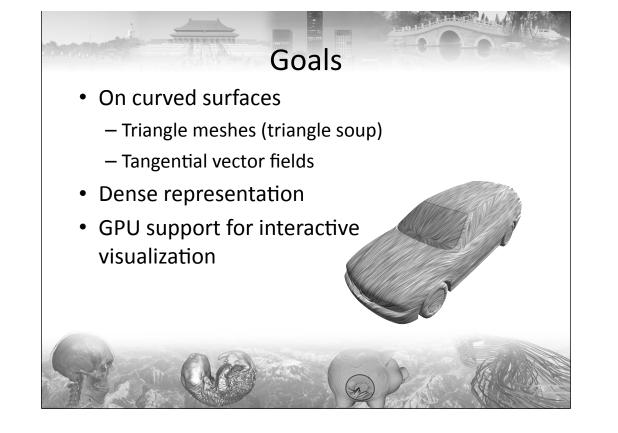


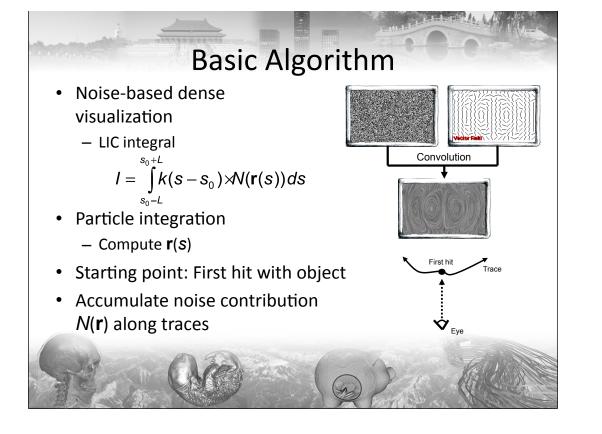


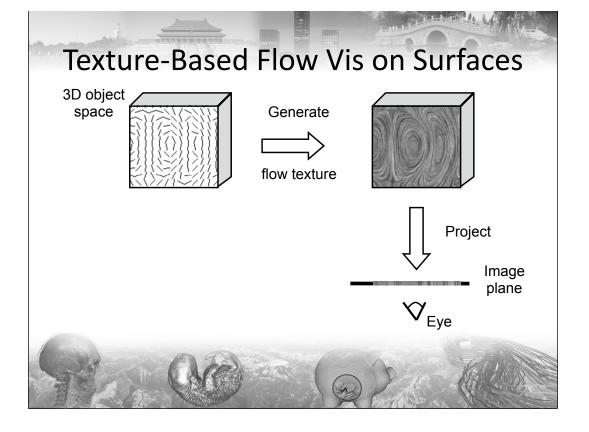


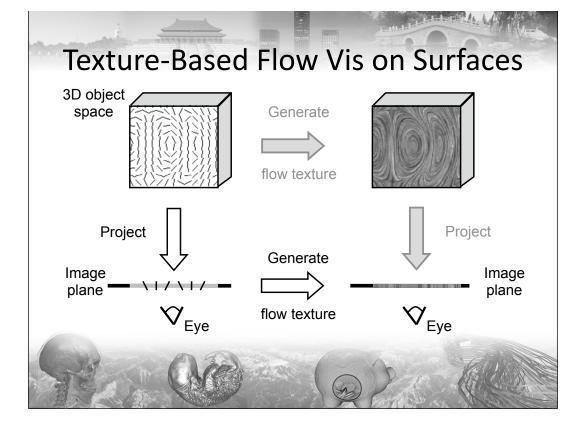












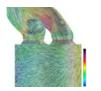
### Advection in Image-Space

- Advantages
  - + No mesh connectivity or parameterization required
  - + Uniform noise density in image space
  - + Simple mapping to GPU
  - Performance determined by viewport size, not mesh complexity



# Advection in Image-Space

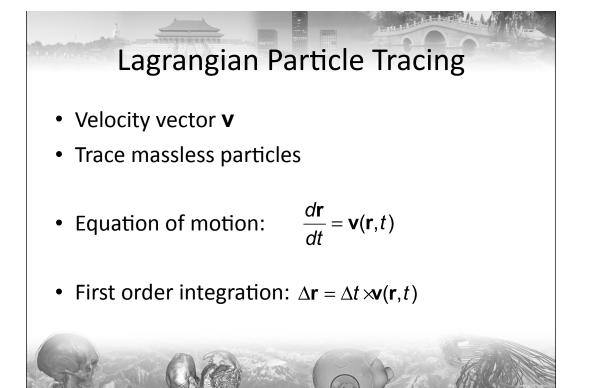
- Disadvantages
  - No or only limited frame-to-frame coherence
  - Blurring (numerical diffusion)
  - Only exponential filter
  - Silhouette lines are problematic inflow regions
  - Special detection of boundary lines needed to avoid crossboundary flow

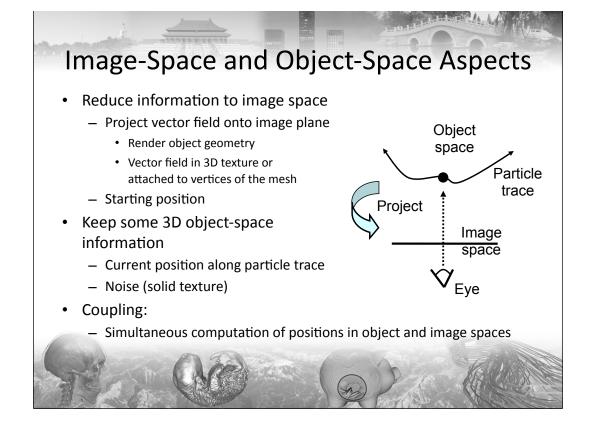


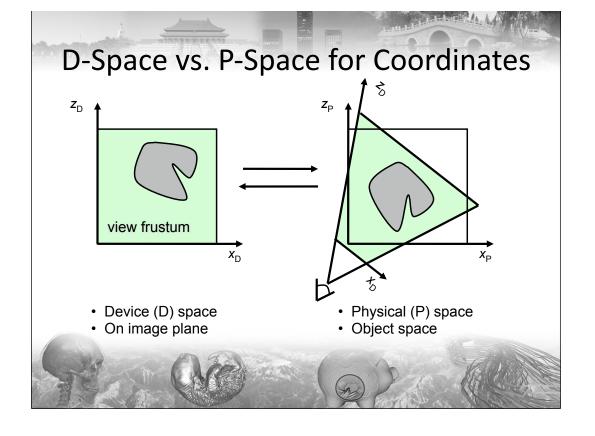


Courtesy of Bob Laramee









## **Visualization Process**

#### Initialization

Init 2D texture for projected velocities **v** 

Render mesh & make vectors tangential

Init 2D texture for P-space positions  ${\bf r}$ 

Render mesh

Init 2D accumulation texture I

#### Loop along particle trace

Transform current P-position **r** into D-space  $\mathbf{r}_{D}$ 

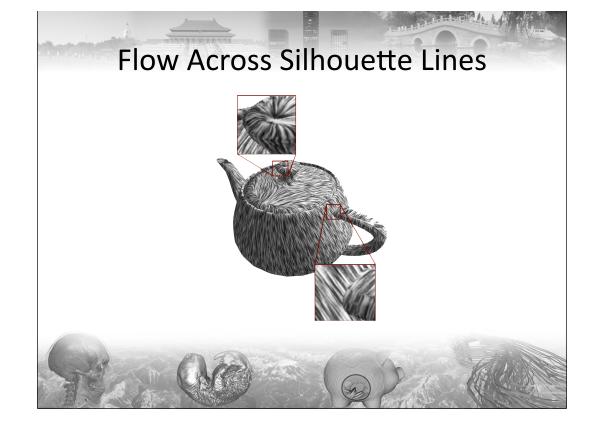
Get velocity from texture:  $\mathbf{v}(\mathbf{r}_{D})$ 

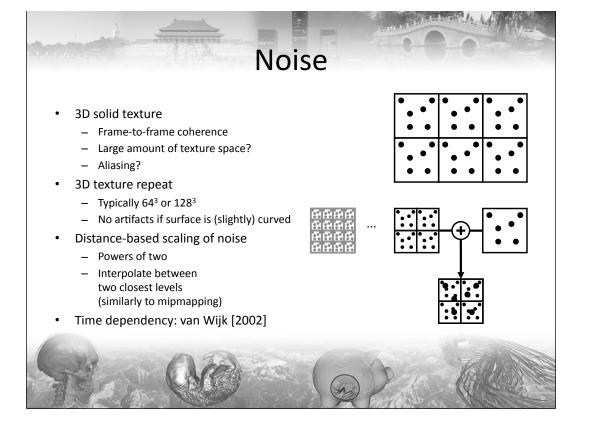
Euler integration  $\mathbf{r} := \mathbf{r} + \Delta t \mathbf{v}$ 

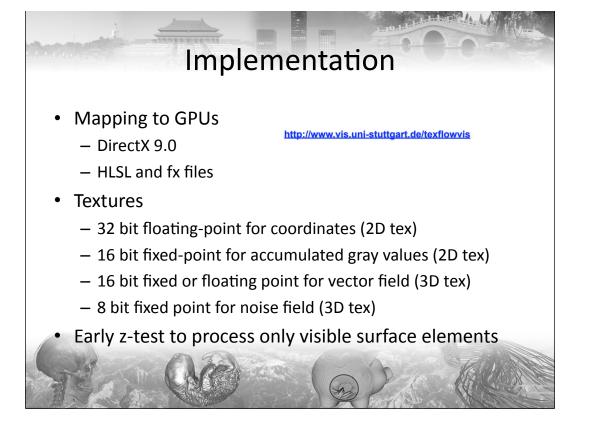
Accumulate noise in I

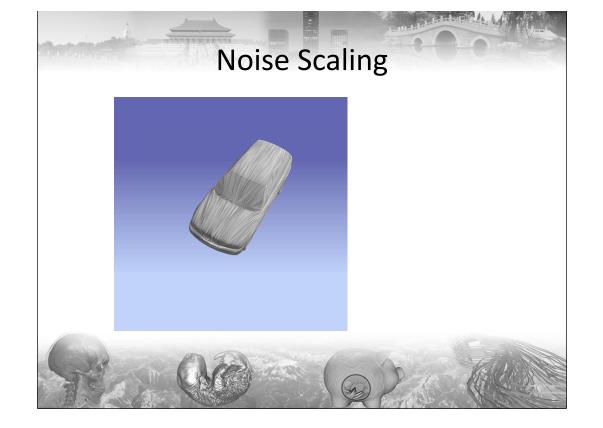
Endloop

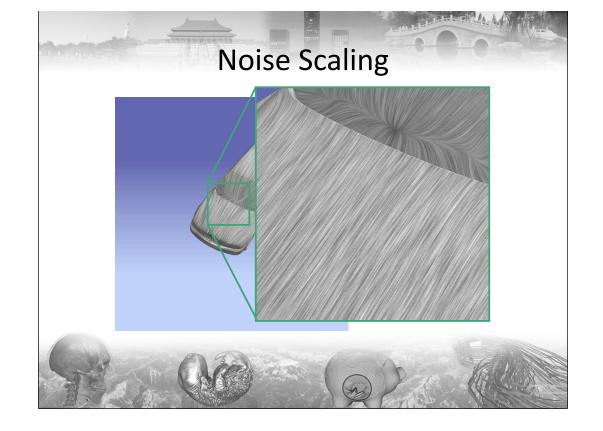


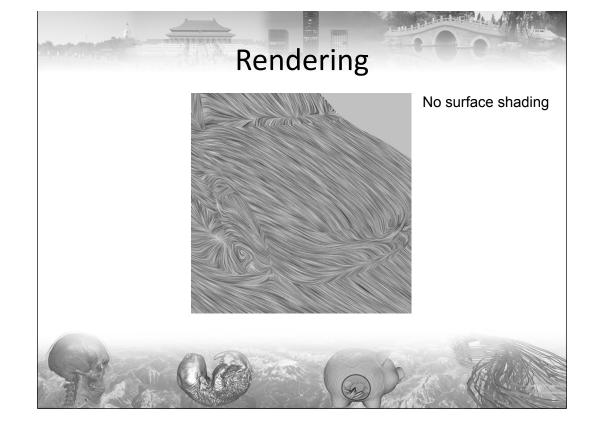




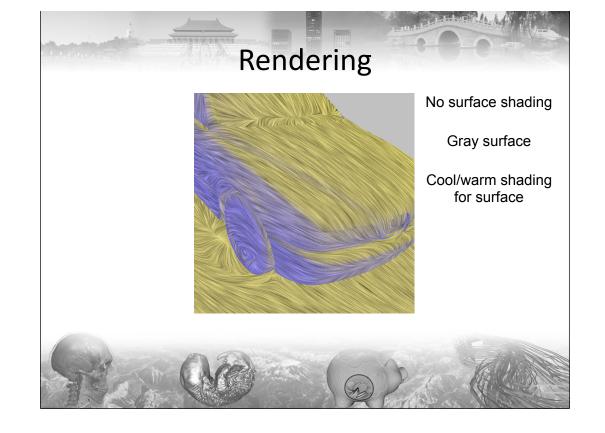


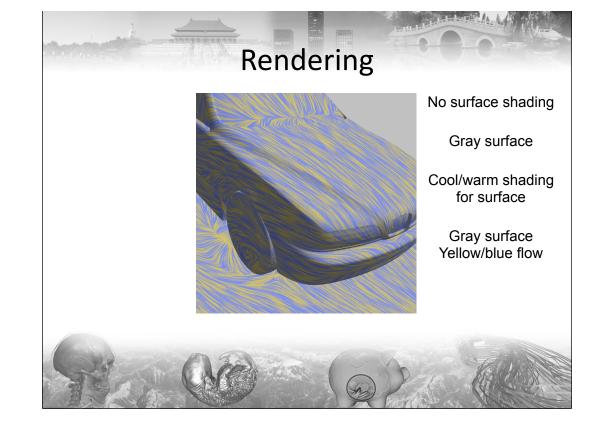


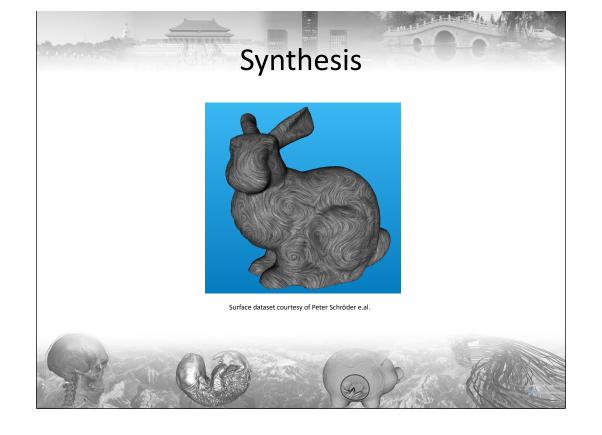


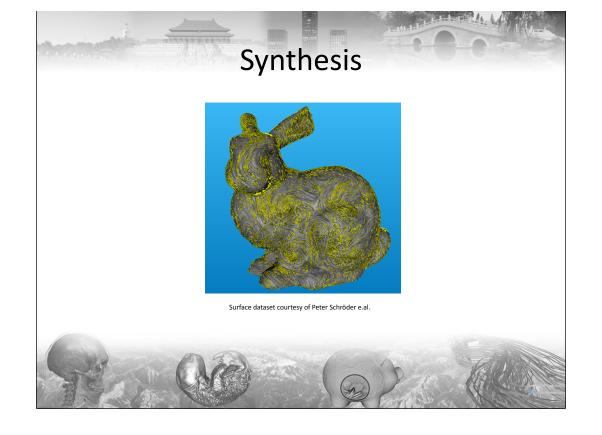


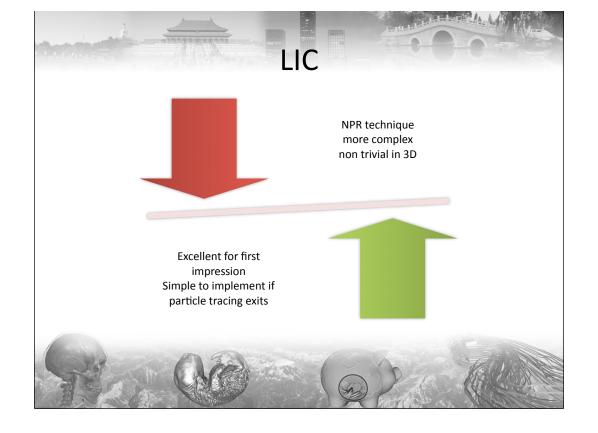


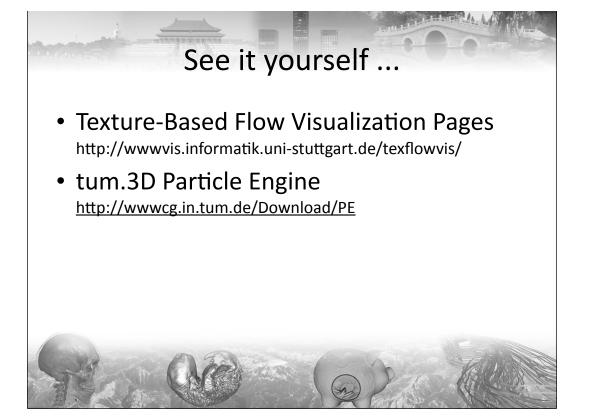














## **Topological Methods**

Slides courtesy of Gerik Scheuermann



