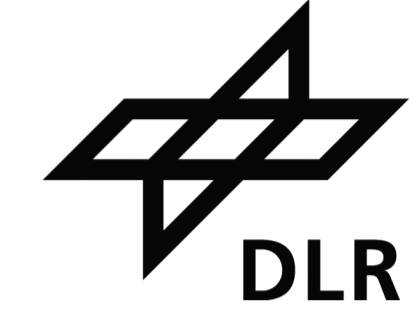
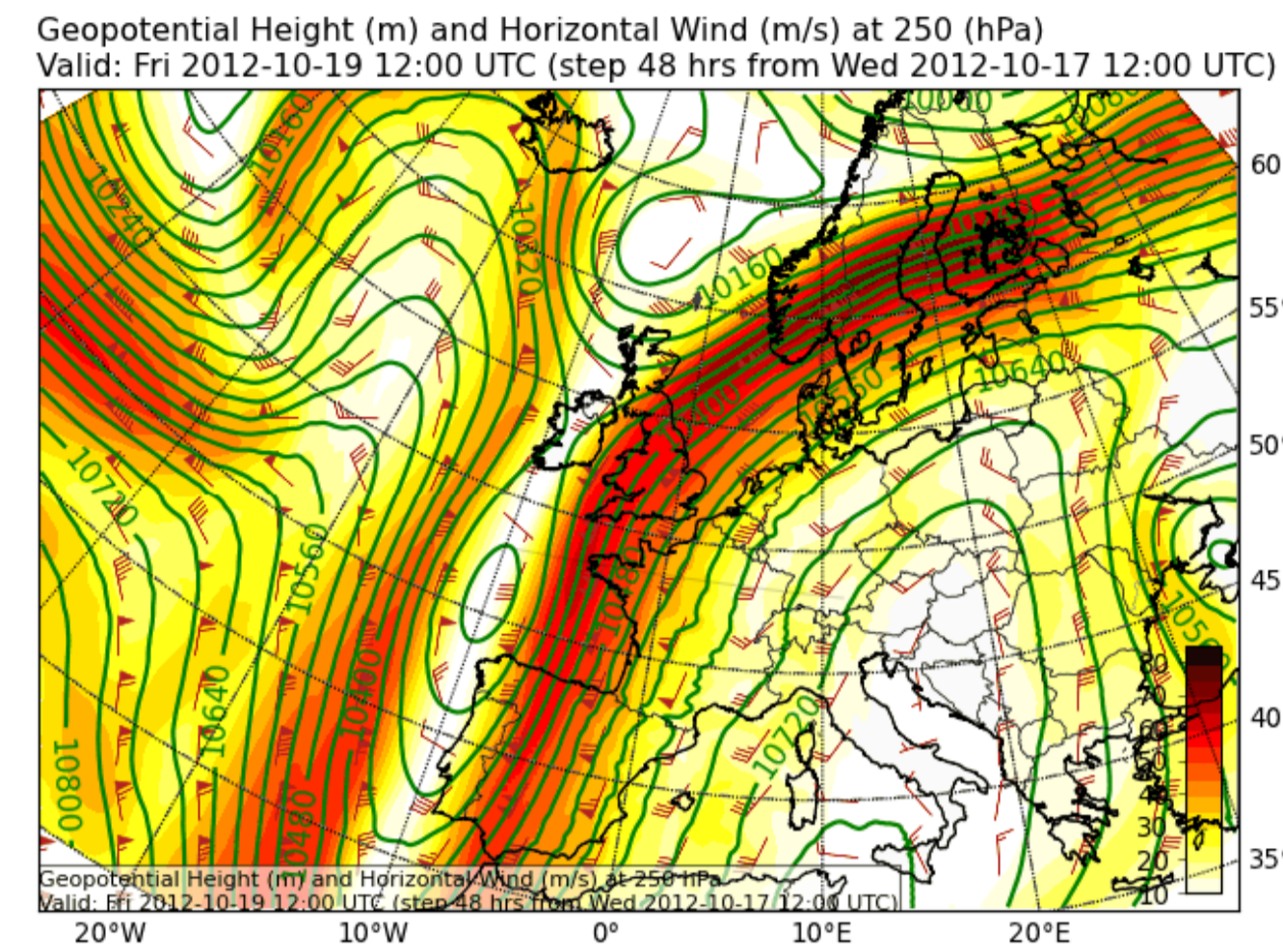
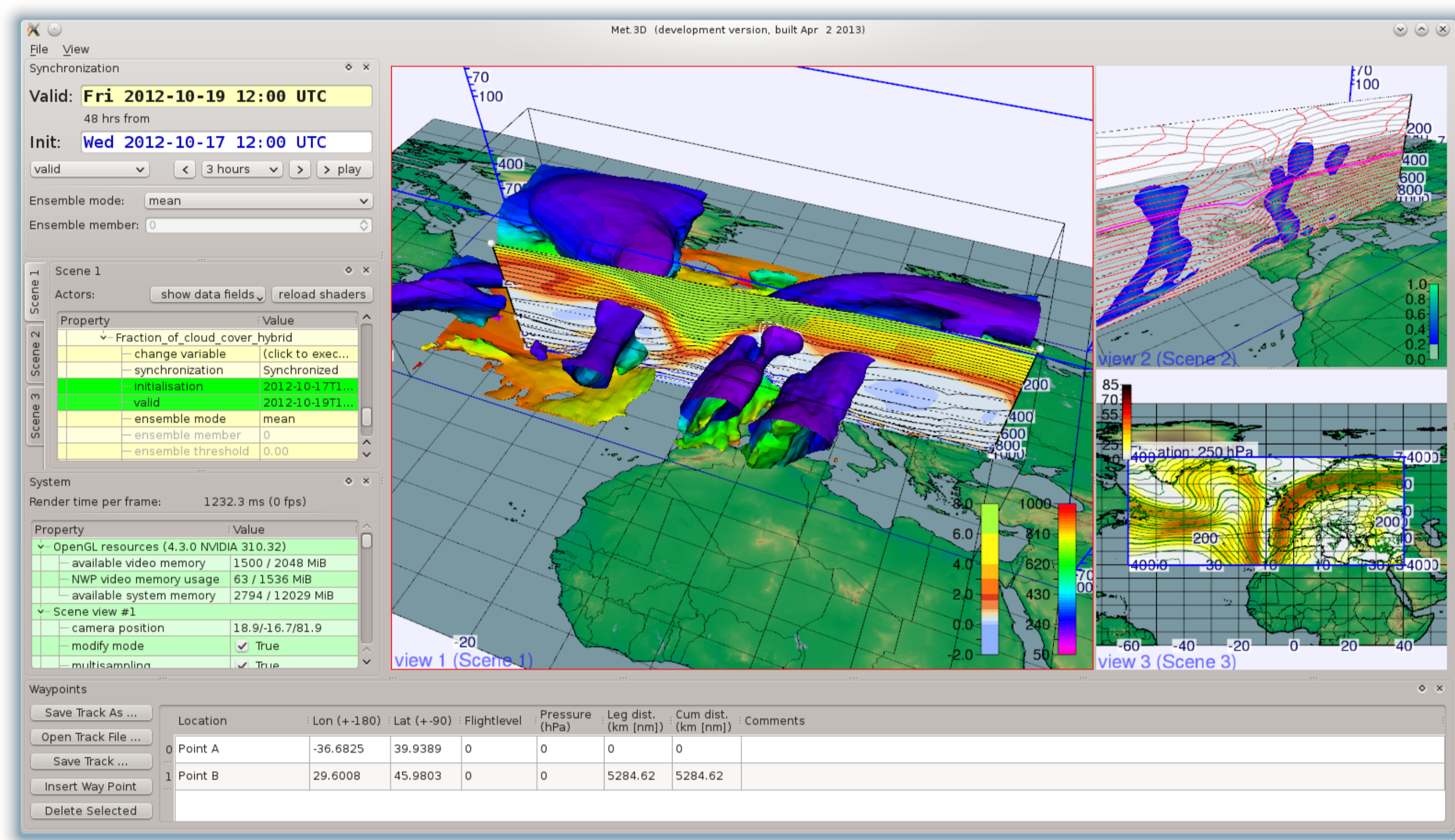
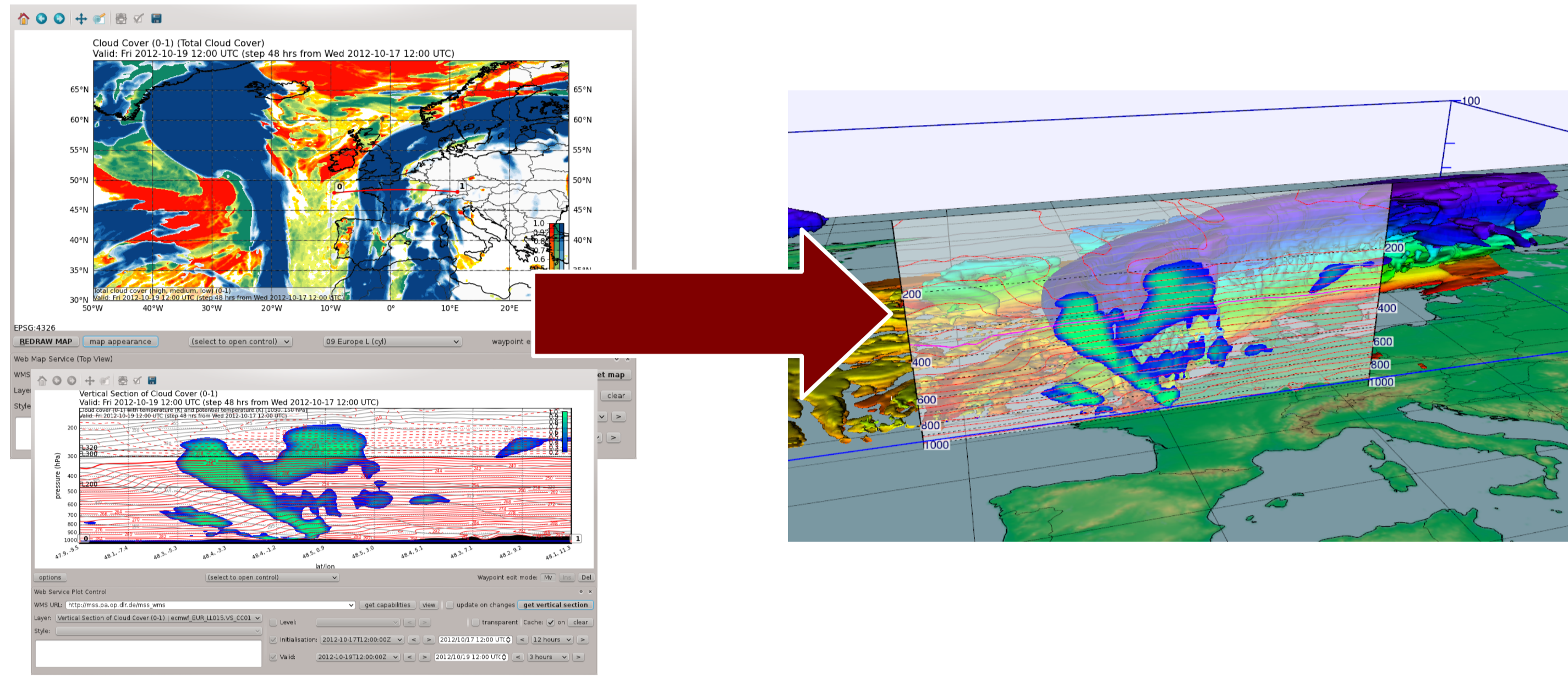


Interactive 3D visualization of ECMWF ensemble forecasts for research flight planning

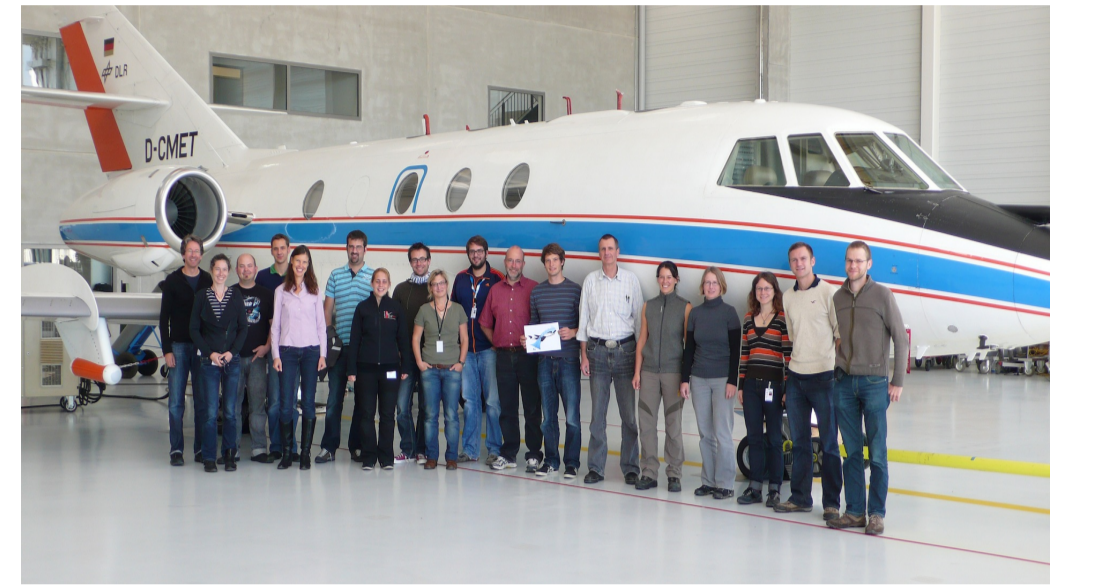
Marc Rautenhaus⁽¹⁾, Christian Grams⁽²⁾, Andreas Schäfler⁽³⁾ and Rüdiger Westermann⁽¹⁾

(1) Computer Graphics and Visualization Group, TU München; (2) Institute for Atmospheric and Climate Science, ETH Zürich; (3) Institut für Physik der Atmosphäre, DLR Oberpfaffenhofen

1 Objective: Investigate the “next step” from the current 2D system and visualize **ensemble forecast** data in **3D** to quickly identify atmospheric features of interest for a flight and to assess their **uncertainty** in the forecast.



2



T-NAWDEX-Falcon campaign:

DLR Oberpfaffenhofen, October 2012, in-situ measurements in **Warm Conveyor Belts** (Schäfler et al., 2013, submitted to *Weather*). Here we show the case of **19 October 2012**. Tasks were to compute ensemble trajectories to detect WCBs and to visualize a derived **probability of WCB occurrence** in the context of the ensemble forecast.

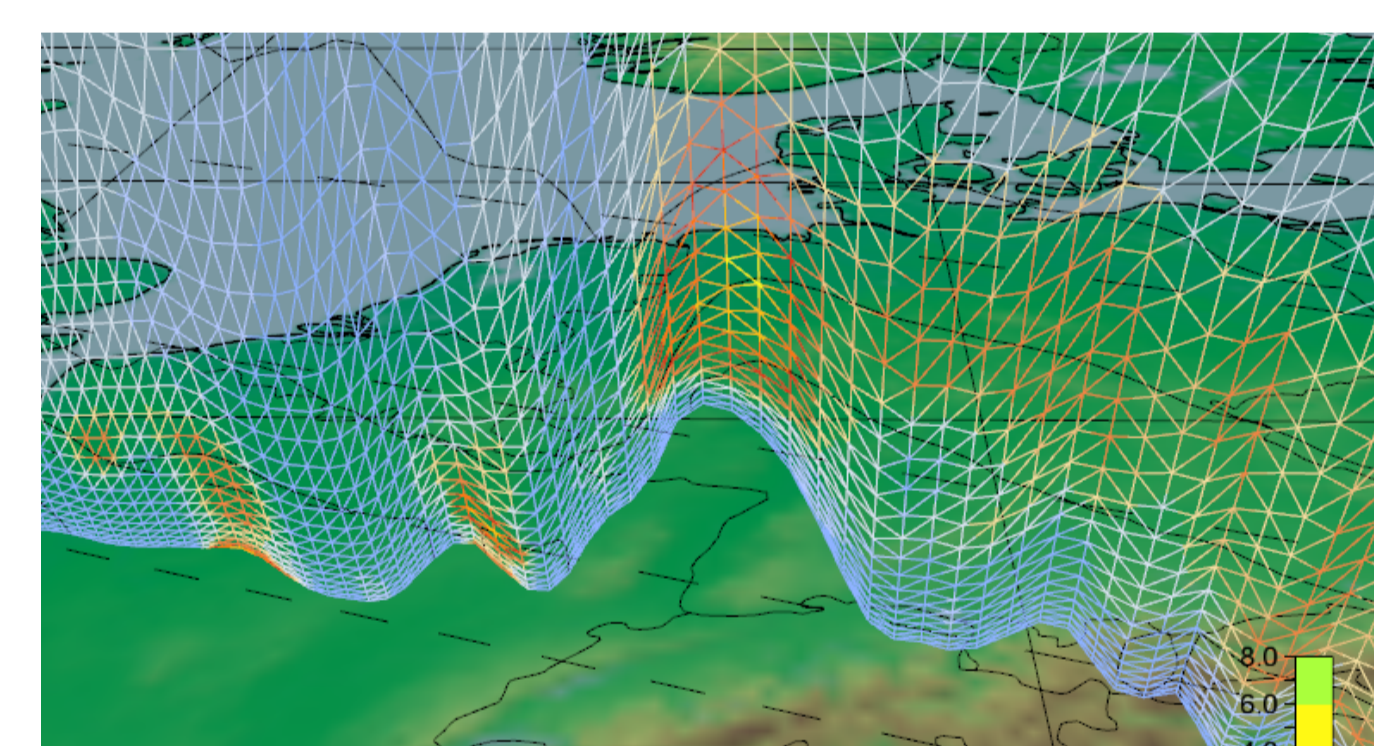
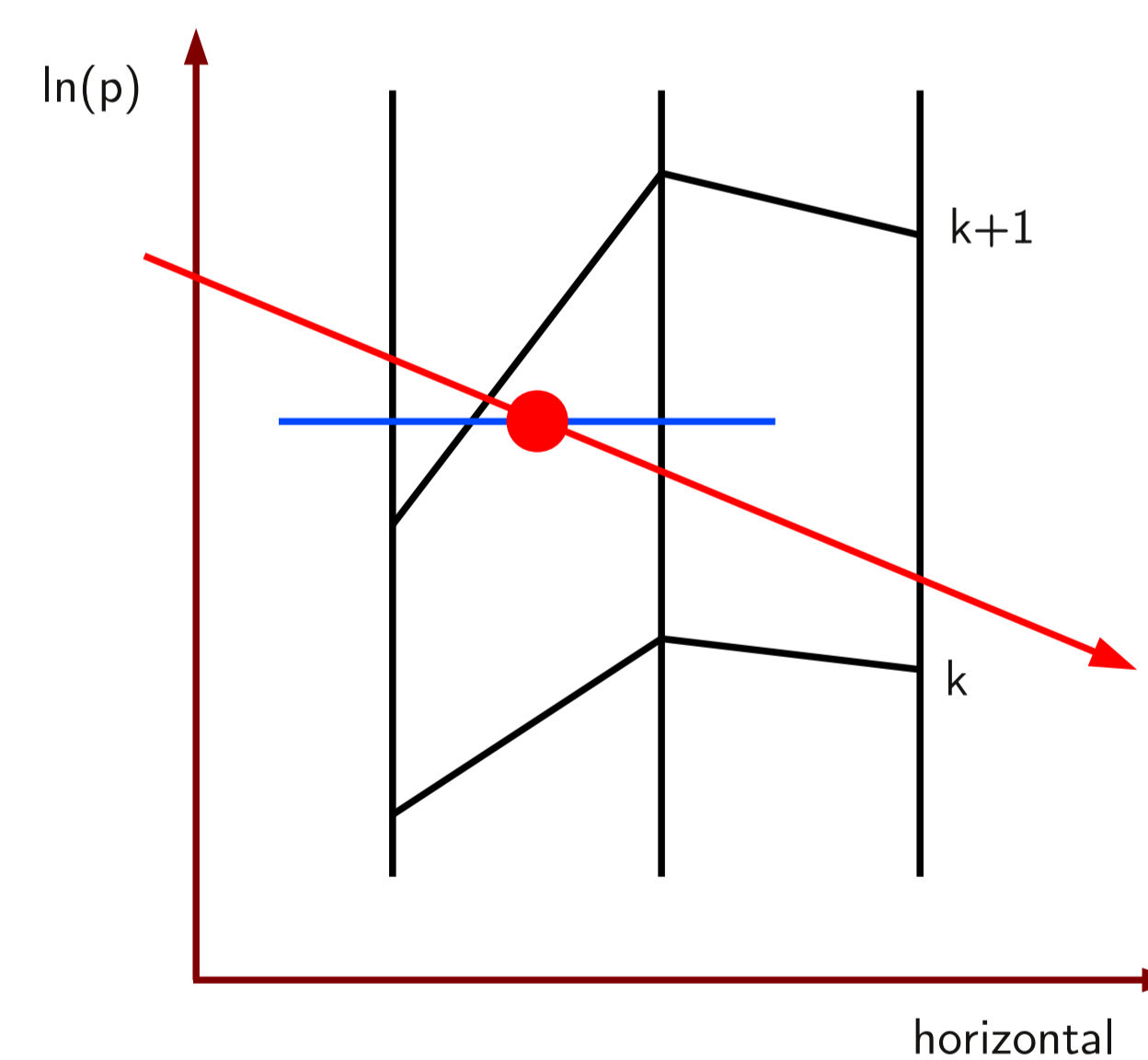
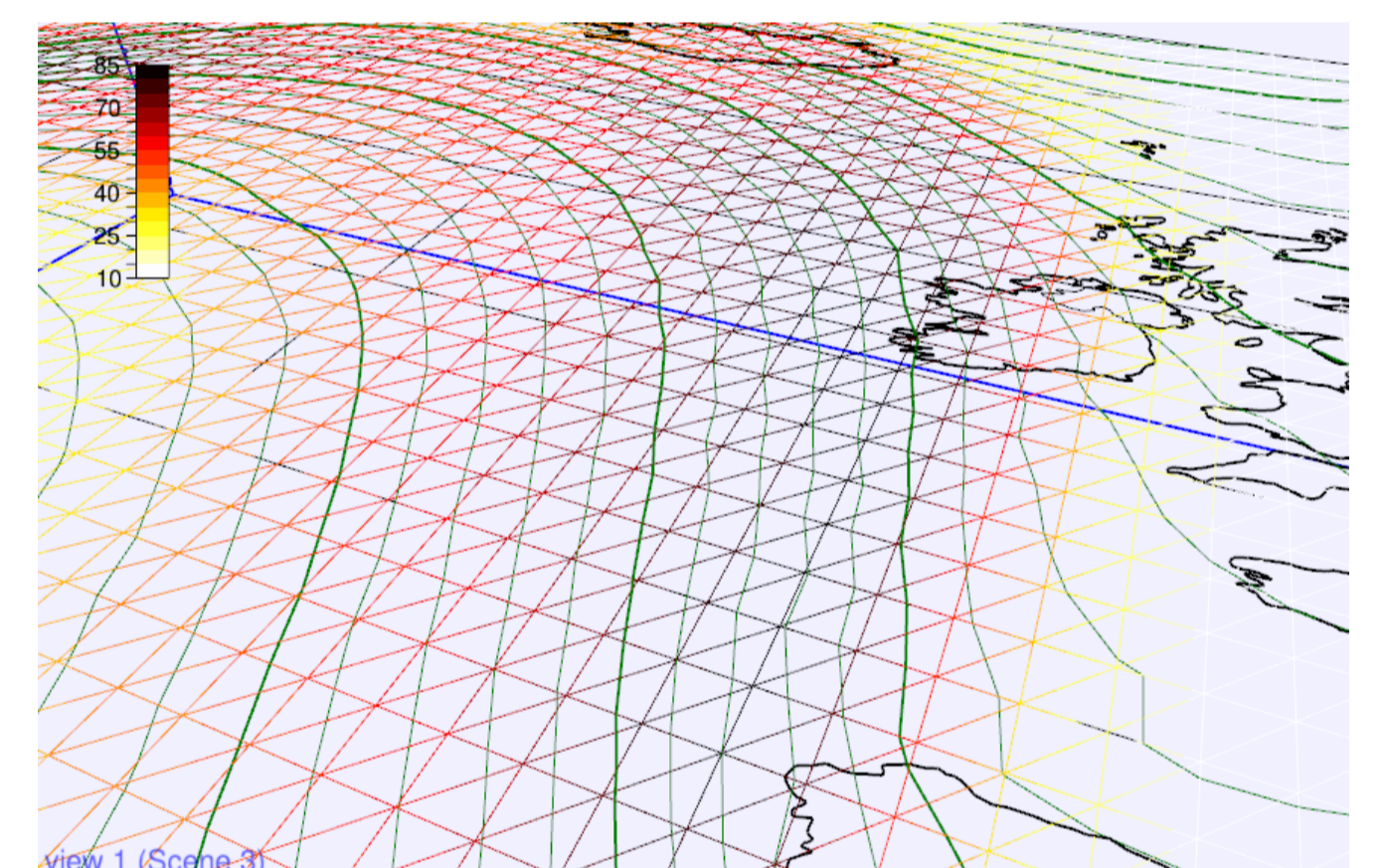
3

How to use ensemble in 3D: Animate members? Explore statistical metrics? Explore detected features? Explore probabilities of features? **Met.3D:** Prototype of a 3D forecasting tool – navigation through 5D data (space + time + ensemble); bridge from 2D to 3D.

5

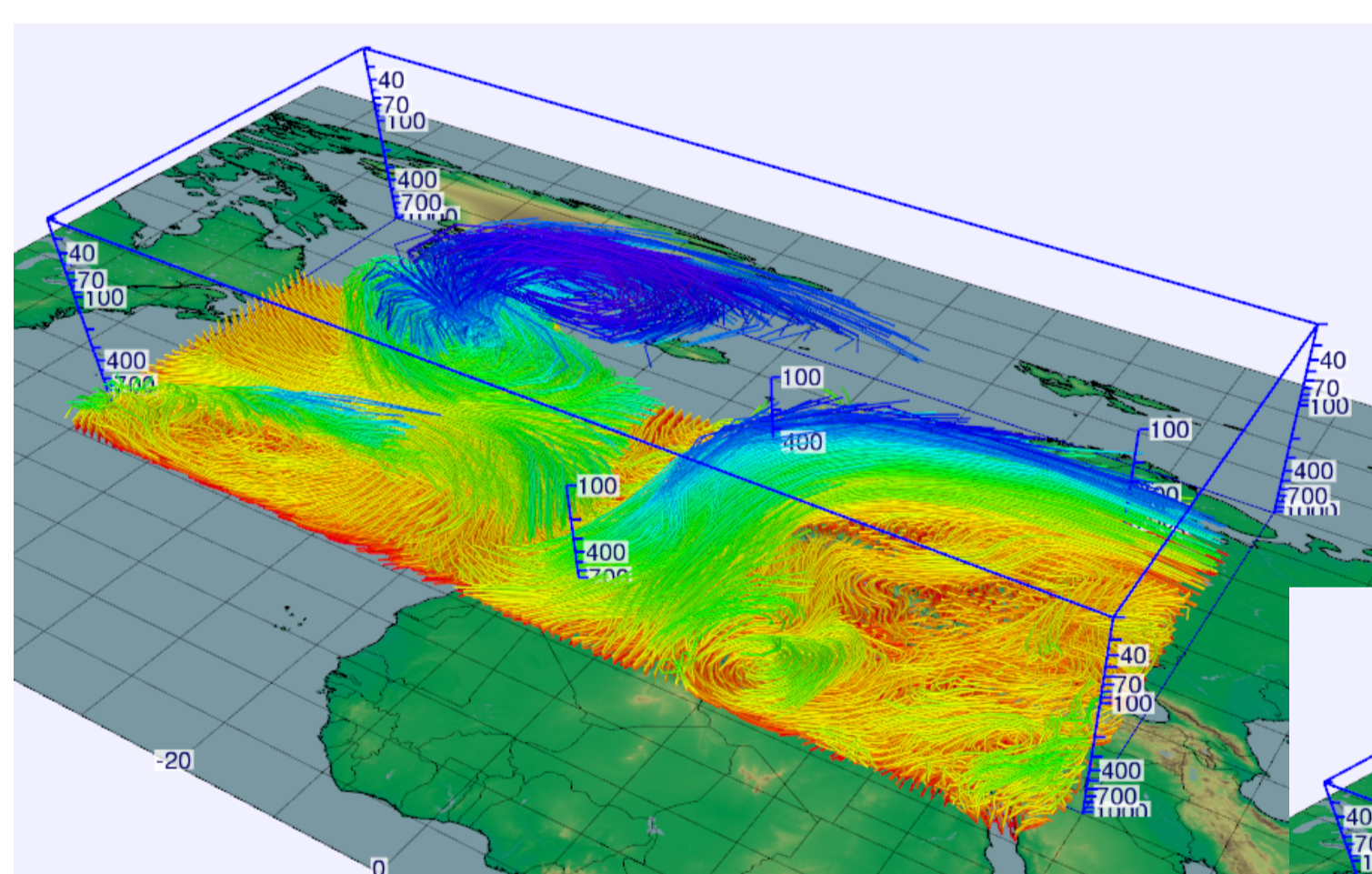
GPU based visualization:

2D sections: Map model grid to vertices, perform model level searches & interpolation on GPU.



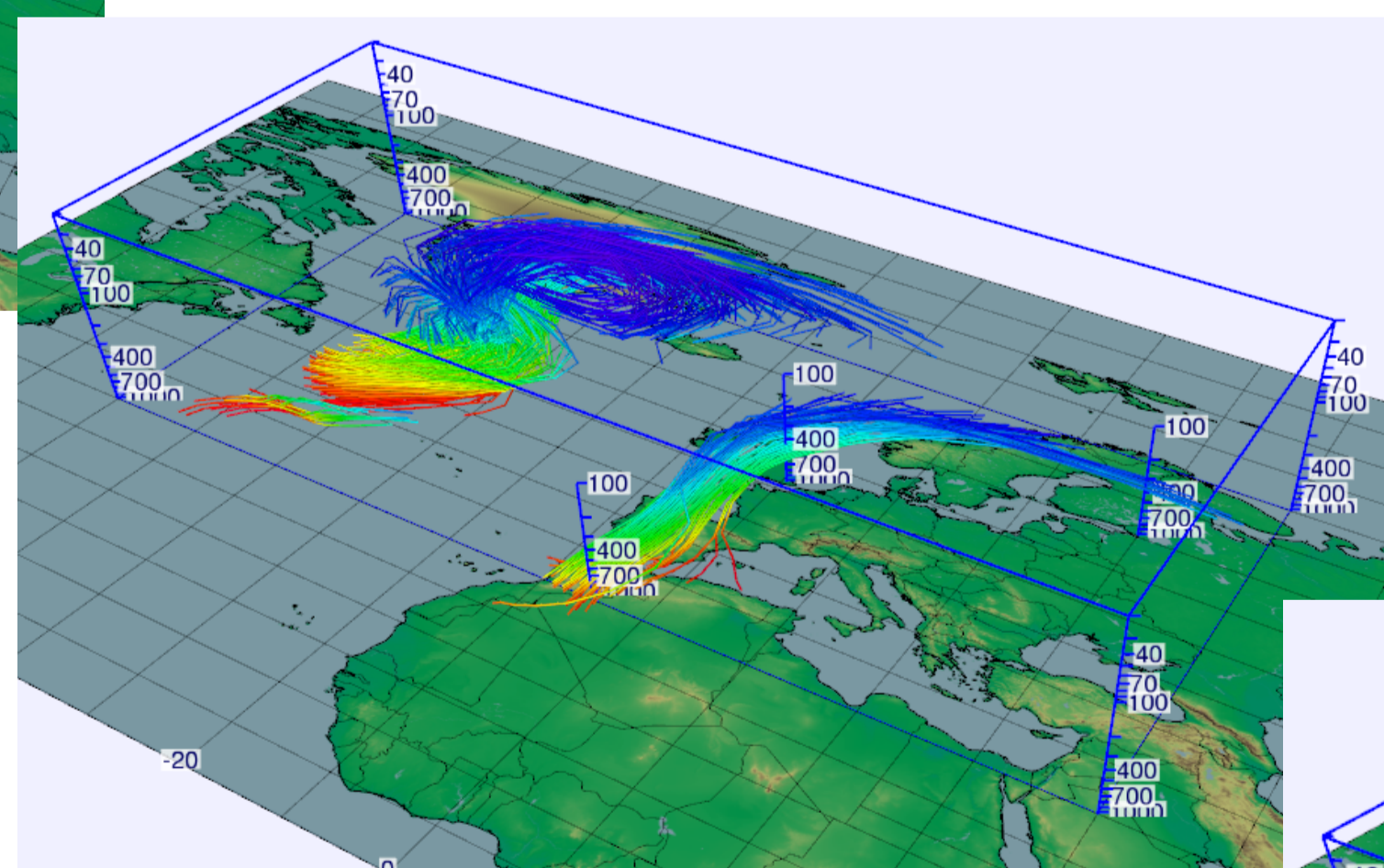
Raycaster: Level searches and trilinear interpolation all along the viewing ray is expensive.

4 WCB probability via trajectories:



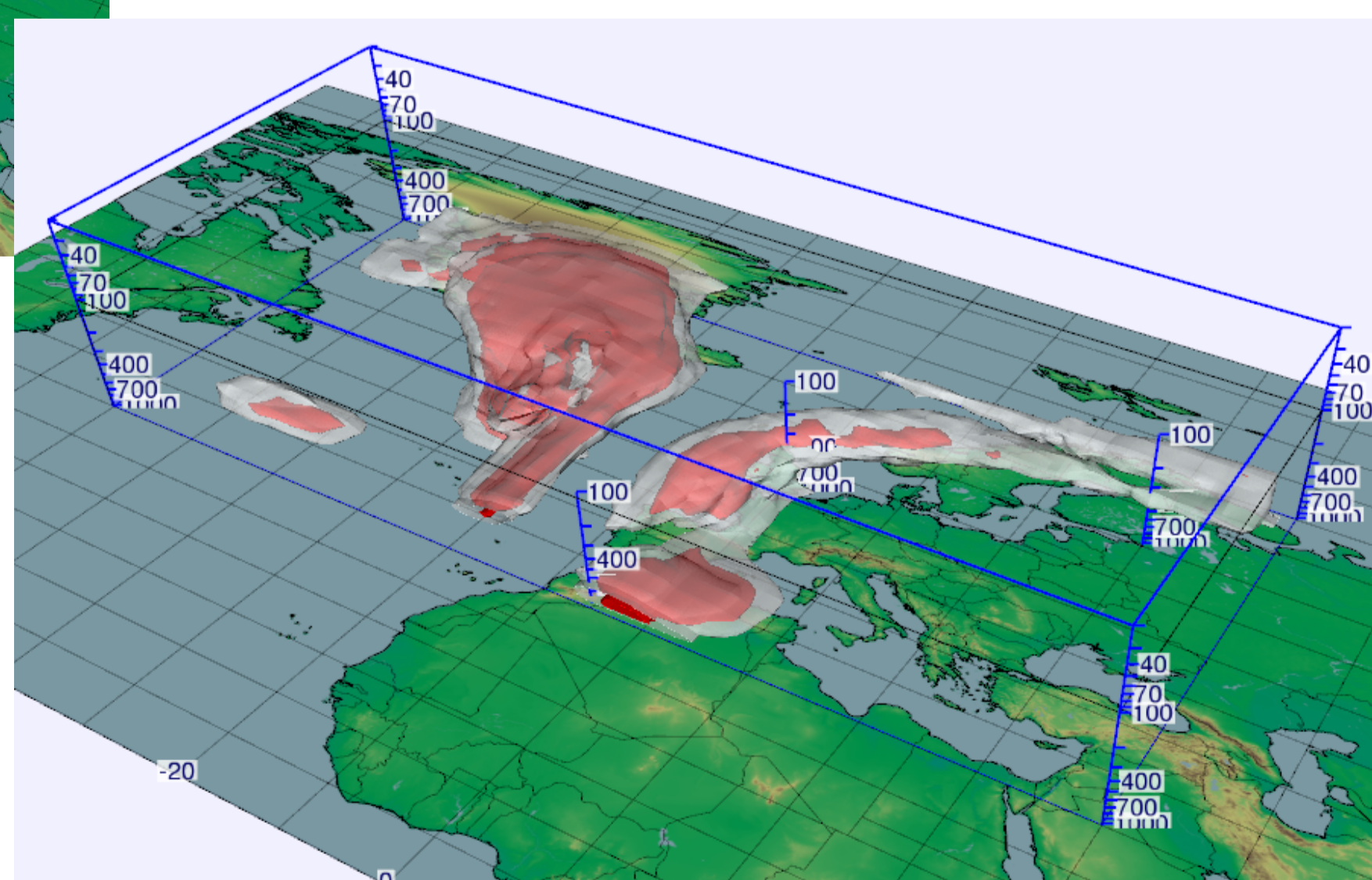
IACETH

Compute 48h trajectories from low-level grid points for every member, starting every six hours (C. Grams, ETH Zürich, using the LAGRANTO model, Wernli & Davis, 1997, Q.J.R. Meteorol. Soc.).



Interactively filter according to ascent: e.g. 500 hPa/48h.

Extract trajectory positions at specific valid time and grid these positions: Probability of WCB occurrence = how many members have a trajectory in a given grid box?



6

Ongoing work:

Uncertainty visualization. Label placement. Efficient visualization algorithms for model grid datasets. Efficient selection algorithms for large trajectory datasets.

Using ECMWF's forecasts 2013. Reading, UK, 5th to 7th June 2013
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Technische Universität München
Department of Computer Science

