

Advanced Topics in 3D Computer Vision

KickOff SS 2022
(IN2106, IN4023)



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Prof. Dr. Nassir Navab

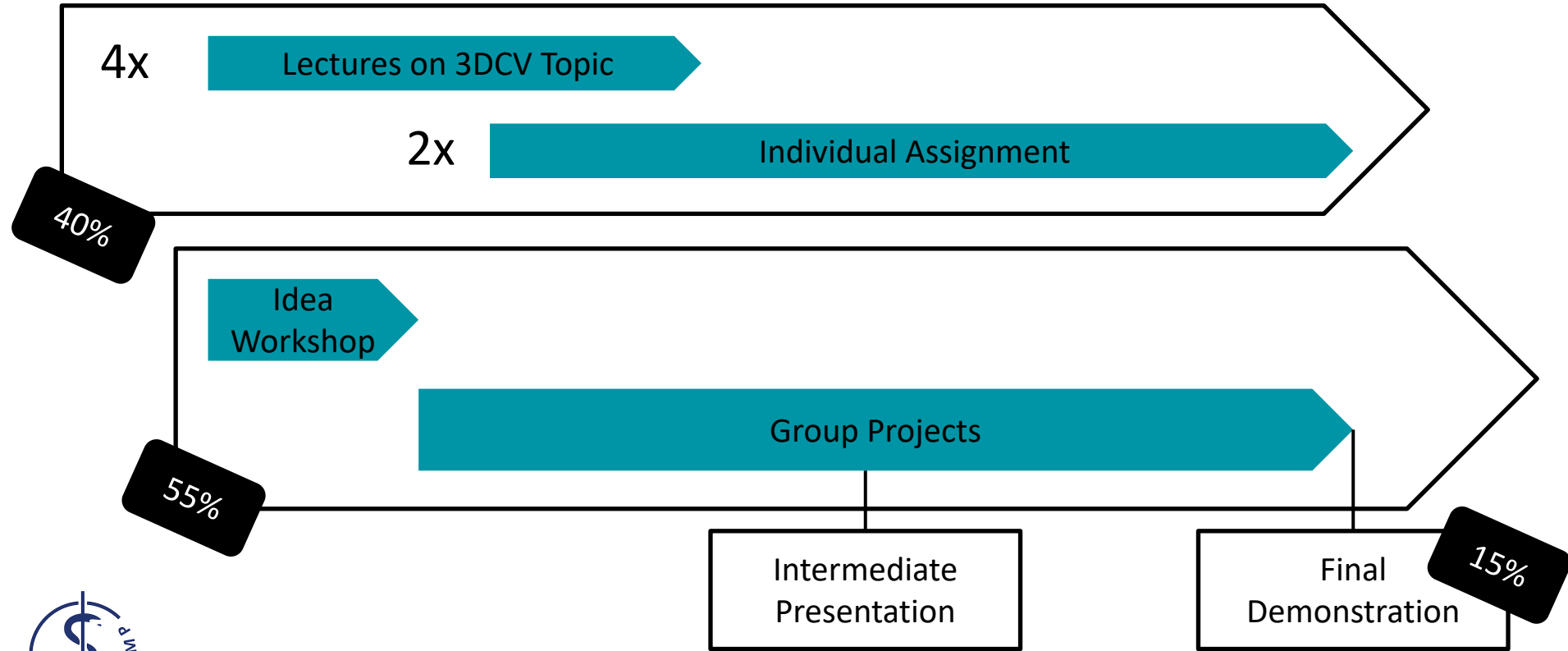
Feedback from previous Students

"AT3DCV is the best course I have ever taken at TUM. I really love this concept because we Master Students can get very detailed, fruitful, and patient supervision from researchers specialized in that field. As a master student who is about to graduate, I really recommend AT3DCV if you are a young fellow and want to do research someday in the future because in this course, you will get a LOT of support from the organizers and this really helps you enjoy research. I believe that is how and why we start doing research. We are being motivated instead of being pushed!"

Hanzhi Chen, MSc Robotics, Cognition, Intelligence
AT3DCV student in WS 2020/21



Lecture Structure



AT3DCV – Concept

1. Theoretical Foundation

- “Flipped Class-room”
 - Pre-recorded lectures: to study in your own pace
 - Interactive Tutor sessions: your chance for discussion and questions (on lectures and assignments)
 - Pass 2 (out of 4) assignments (mostly practical and some theoretical parts)

2. Group projects:

- Apply your 3DV and DL knowledge
- Very close tutoring
- “researchy” projects
 - Projects are purposely not strictly defined
 - Be innovative and creative
 - Final workshop: combination of scientific poster-session and start-up pitch
 - Present your working demo/code/application/results



Application

- 2 stage process:
 - Register in TUM Online
<http://docmatching.in.tum.de/index.php/schedule>
 - Submit questionnaire and upload CV + Transcript
https://docs.google.com/forms/d/e/1FAIpQLScoykzsr9NKdc1B3lnwrL3FoFuLOF_LBaA1ZlPjGWA6_FvwWg/vi ewform
- Deadline: 15th of February 2022
- 16 Students will be selected (usually 100+ applications)



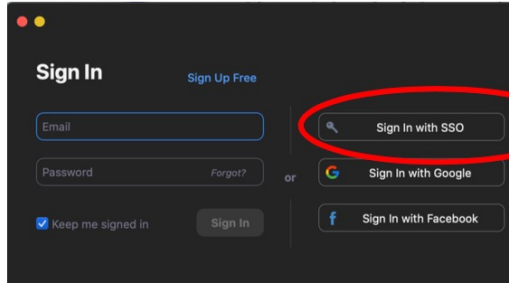
Virtual/Hybrid/On-sight

- Depending on government/TUM regulations
- Communication via Zoom (for virtual lectures and Chat)
- See website for updates (<https://www.in.tum.de/campar/teaching/practical-courses/advanced-topics-in-3d-computer-vision/>)

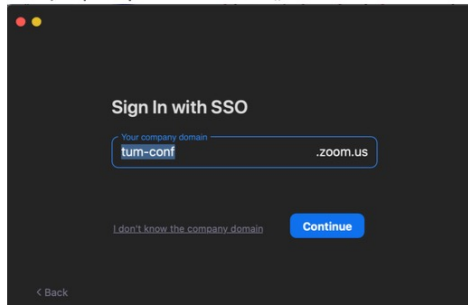


How-To: TUM-Zoom Chat

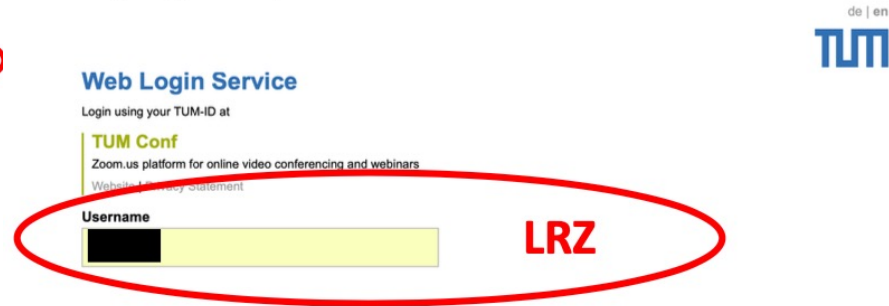
- 1) Download the Zoom App and install.
- 2) Sign in with the SSO



- 3) Specify the domain as „tum-conf“



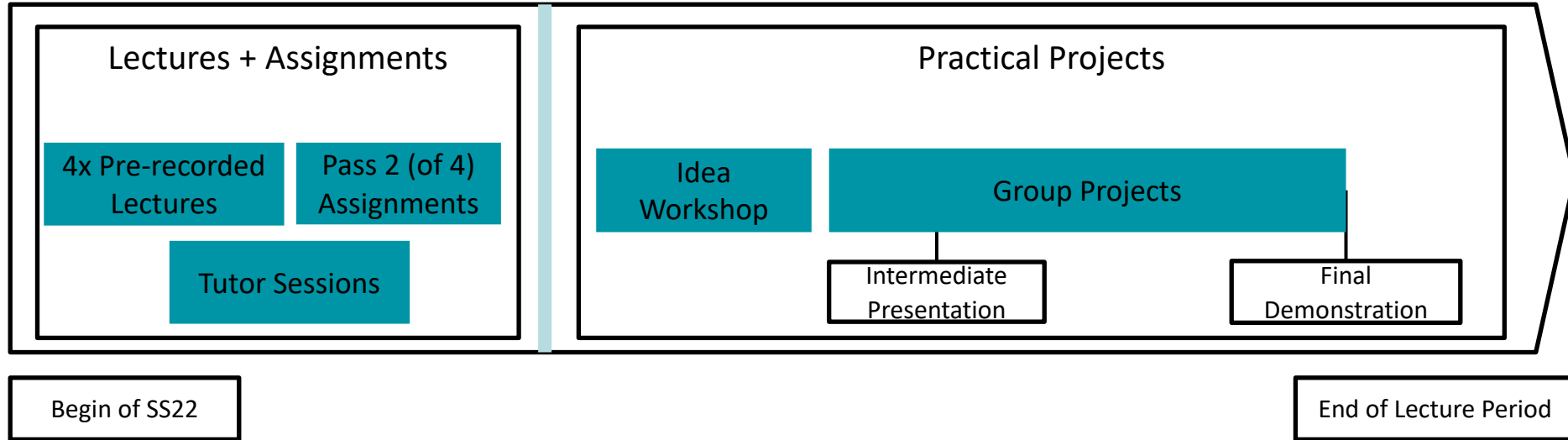
- 4) Log in with your LRZ credential on the web interface



- 5) Go back to Zoom app
- 6) Go to "Chat" -> Top right "Search" for "Patrick Ruhkamp" and text "AT3DCV"
- 7) You will be manually added to the group

Comment: If you have problems logging in for the first time, try to sign in first by directly opening <https://tum-conf.zoom.us> in your browser. Then follow the instructions from 2) again

Timeline



Lectures

- Pre-recorded lectures on 3D Computer Vision and Deep Learning topics (tbd):
 - Basic Tips and Knowledge for Deep 3D Vision
 - Sensing Depth with 3D Computer Vision
 - Visual Self-Localization - Classical Methods and Learning-based Approaches
 - 3D Deep Learning



Group Projects

- Students will be matched by taking their preferences into account
- Potential project ideas will be suggested during lectures
- Final project proposals of the group will be discussed in workshop session
- We are open to suggestions and ideas!!!
- Projects can either be applied in real world problems OR try to solve open research questions



What to expect

- Gain detailed knowledge in modern computer vision problems
- Study relevant Deep Learning methods
- Understand to see the world in 3D
- Lectures provide starting point for your projects
- Solve 3D Computer Vision tasks
- Apply your acquired knowledge in real scenarios and/or push the boundaries of research in Computer Vision



What we expect

- Interest in Computer Vision
- Independent and pro-active participation
- Actively asking for help (team members and tutors)
- Coding knowledge
- Working dedicated in your team towards achieving the goals of your group project



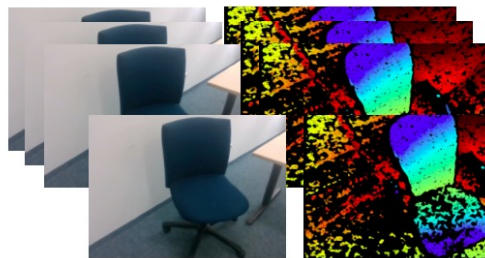
Previous Projects

AT3DCV

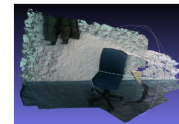


1. Furniture Replacement

RE. CONSTRUCTION
SE. GMENTATION
AU. GMENTATION



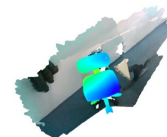
RE.



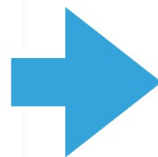
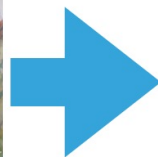
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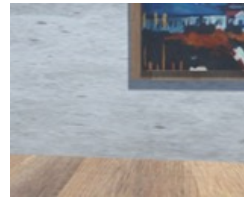
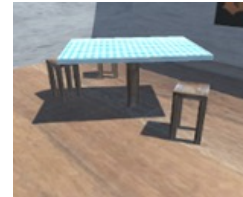
AU.



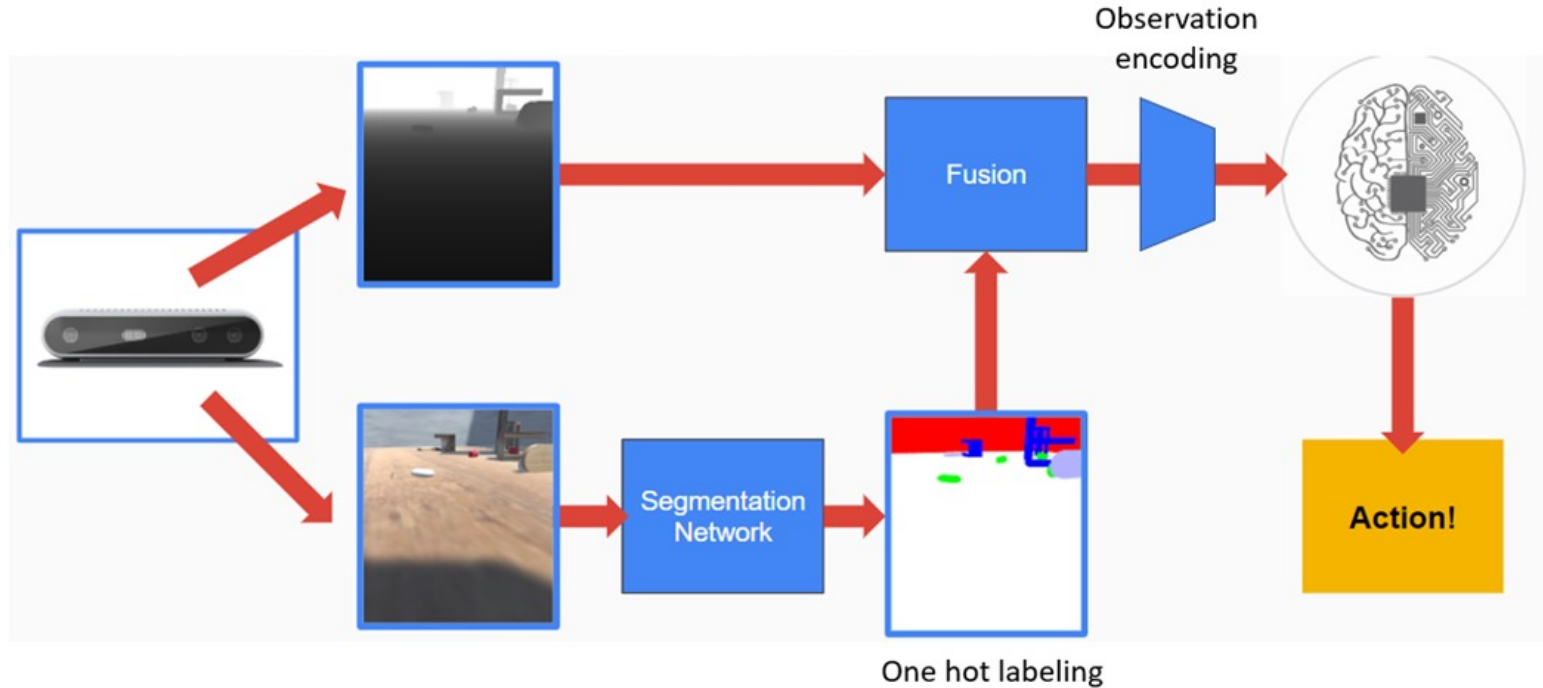
Point cloud from Scan-Net



2. Garbage Evaporating Autonomous Robot (a.k.a. Trash Hugger)



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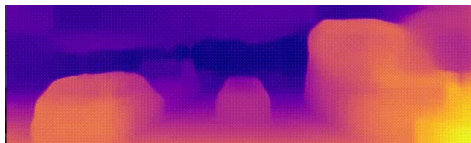


3. Consistent Depth Prediction

- In this work, we would like to take both **single-frame accuracy** and **multi-frame consistency** into account, without blurring edges, or huge computational overhead.



Inputs



Manydepth [1]



Ours

- With consistent predictions, we can achieve better results in augmented reality applications, 3D reconstruction, etc.



Inputs



Manydepth [1]



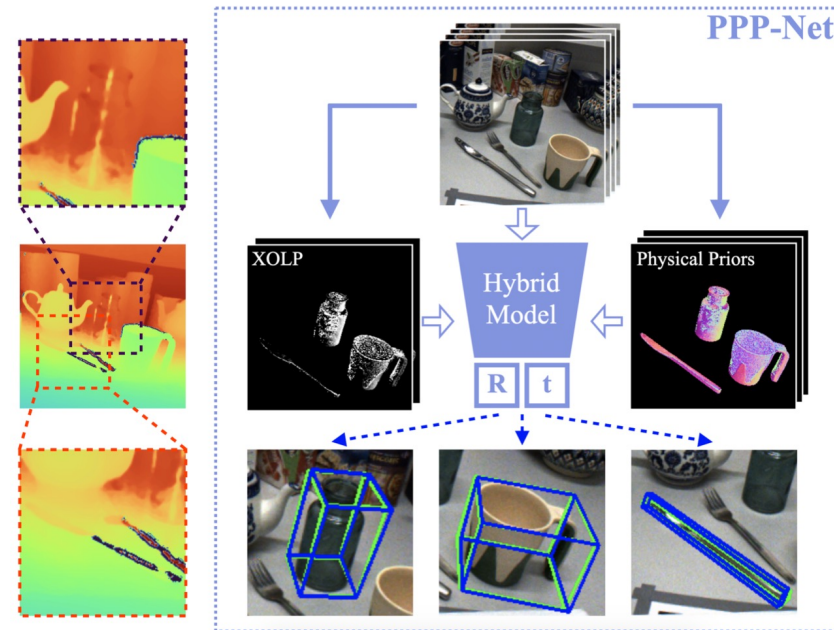
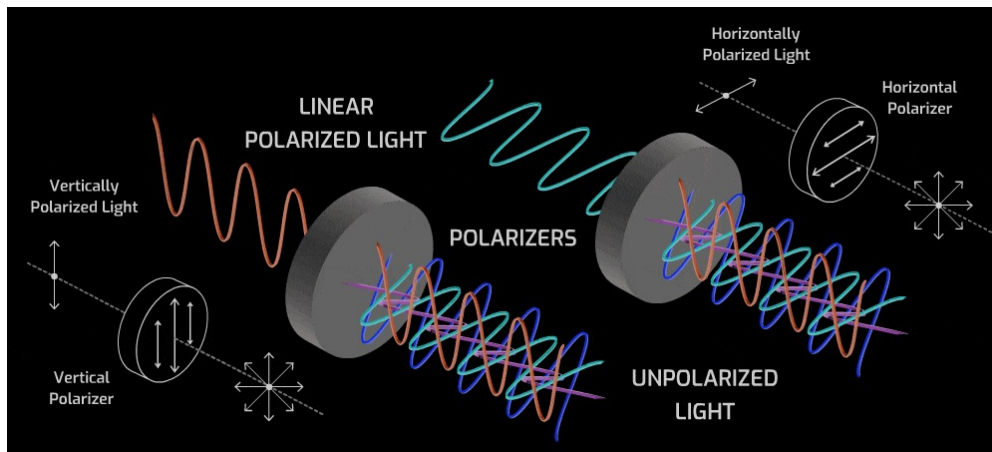
Ours



Ruhkamp, Gao, Chen, Navab, Busam "Attention meets Geometry", 3DV 2021, ICCV-W 2021

[1] Watson, J., Mac Aodha, O., Prisacariu, V., Brostow, G., & Firman, M. "The Temporal Opportunist: Self-Supervised Multi-Frame Monocular Depth". CVPR, 2021

4. Polarimetric Pose Prediction



Questions

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- Web:
<https://www.in.tum.de/campar/teaching/practical-courses/advanced-topics-in-3d-computer-vision/>

