Foundations in 3D Computer Vision [IN0012]

Advanced Topics in 3D Computer Vision [IN2106, IN4023]

February 7, 2024







Dr. Benjamin Busam, Lennart Bastian, Niko Brasch, Boody Elskhawy, Junwen Huang, HyunJun Jung, Mert Karaoglu, Mert Kiray, Mengze Li, Ege Özsoy, Klara Reichard, Felix Tristram, Pengyuan Wang, Guangyao Zhai

Feedback from previous Students

"AT3DCV is the best course I have ever taken at TUM. I really love this concept because we Master Students can get very detailed, fruitful, and patient supervision from researchers specialized in that field. As a master student who is about to graduate, I really recommend AT3DCV if you are a young fellow and want to do research someday in the future because in this course, you will get a LOT of support from the organizers and this really helps you enjoy research. I believe that is how and why we start doing research. We are being motivated instead of being pushed!"

Hanzhi Chen, MSc Robotics, Cognition, Intelligence AT3DCV student in WS 2020/21



Core Organizers



Felix Tristram



Nikolas Brasch



Mengze Li



Boody Elskhawy



Junwen Huang





Benjamin Busam



Guangyao Zhai



Pengyuan Wang



Lennart Bastian



HyunJun Jung



Mert Kiray



Karaoglu

Reichard

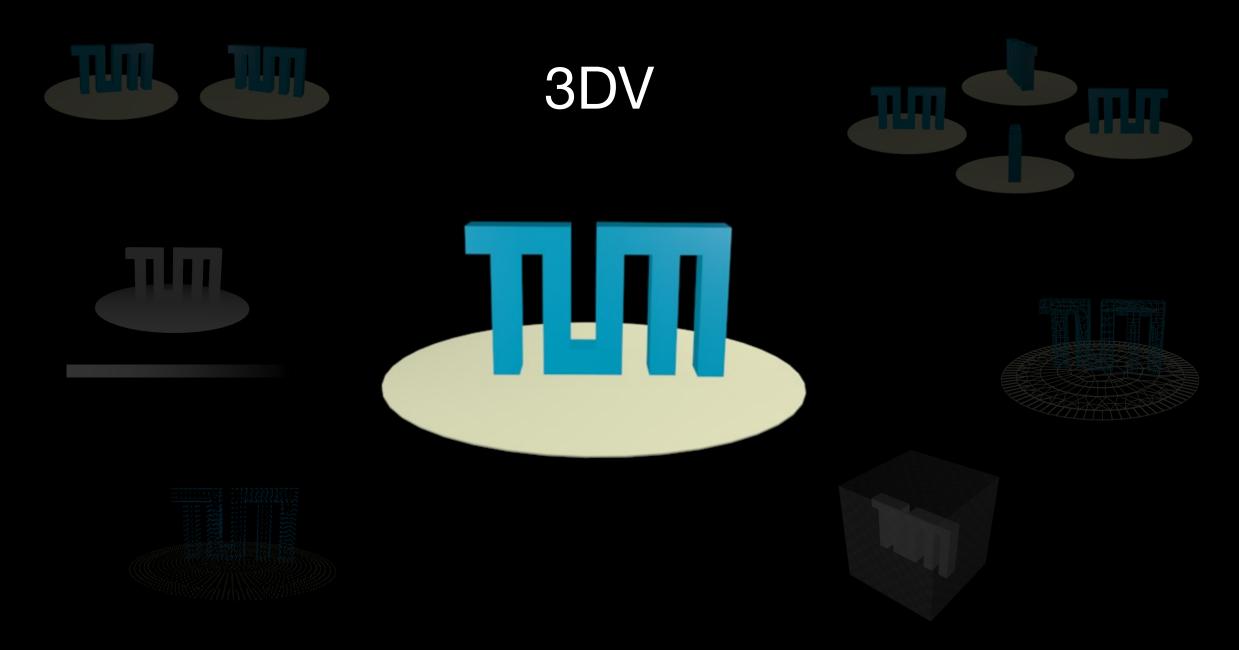


Ege Özsoy





memegenerator.net



Previous Projects

Garbage Evaporating Robot





Garbage Evaporating Robot













Garbage Evaporating Robot

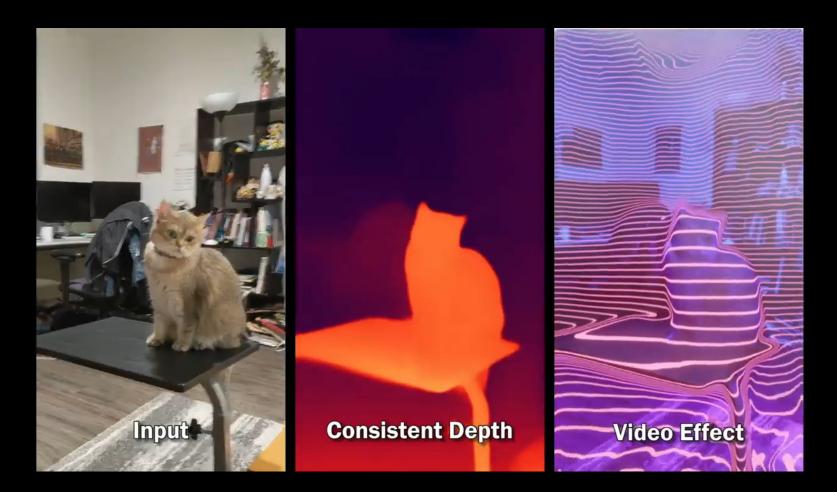


Birds-Eye View :: 1hour of training

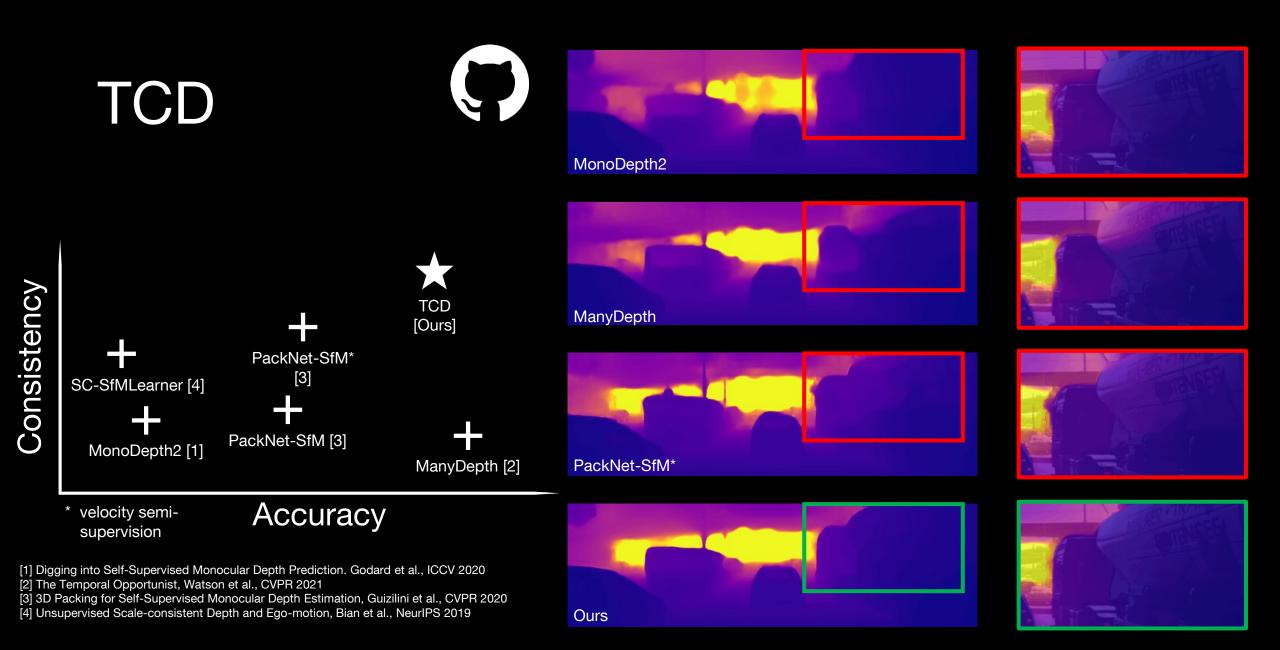




Temporally Consistent Depth [TCD]

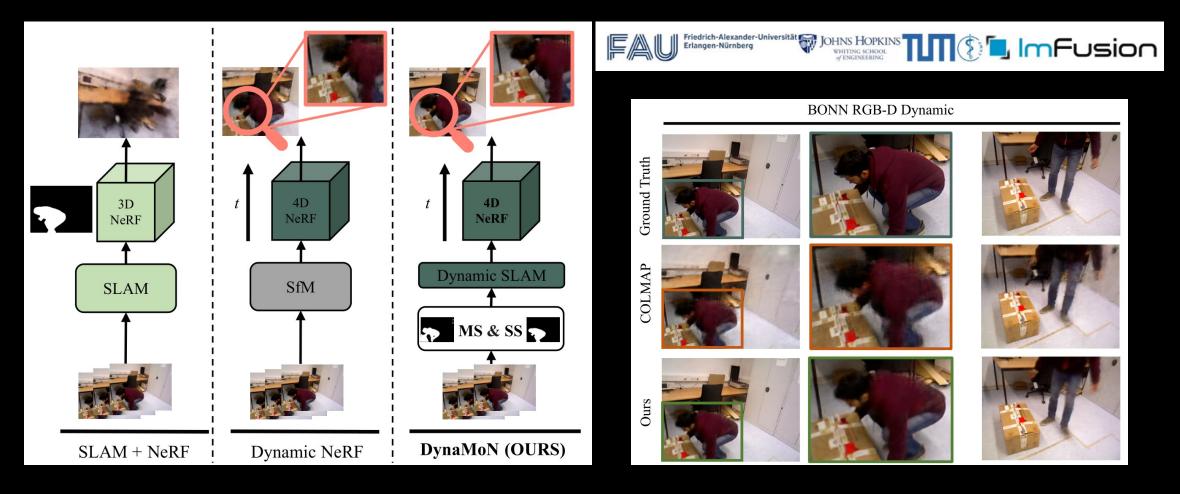


Luo, Huang, Szeliski, Matzen, Kopf. Consistent video depth estimation. SIGGRAPH 2020 Kopf, Rong, Huang. Robust Consistent Video Depth Estimation. CVPR 2021



Ruhkamp, Gao, Chen, Navab, Busam. Attention meets Geometry: Geometry Guided Spatial-Temporal Attention for Consistent Self-Supervised Monocular Depth Estimation ICCVW 2021. 3DV 2021.

DynaMoN: Motion-Aware Cam. Poses & Reconstruction



Karaoglu, Schieber, Schischka, Görgülü, Grötzner, Ladikos, Roth, Navab, Busam. DynaMoN: Motion-Aware Fast And Robust Camera Localization for Dynamic NeRF. arXiv 2023.

DynaMoN: Motion-Aware Cam. Poses & Reconstruction

DynaMoN

Motion-Aware Fast And Robust Camera Localization for Dynamic NeRF

Mert Asim Karaoglu*, Hannah Schieber*, Nicolas Schischka*, Melih Gorgulu*, Florian Grötzner, Alexander Ladikos, Daniel Roth, Nassir Navab, and Benjamin Busam





Karaoglu, Schieber, Schischka, Görgülü, Grötzner, Ladikos, Roth, Navab, Busam. DynaMoN: Motion-Aware Fast And Robust Camera Localization for Dynamic NeRF. arXiv 2023.

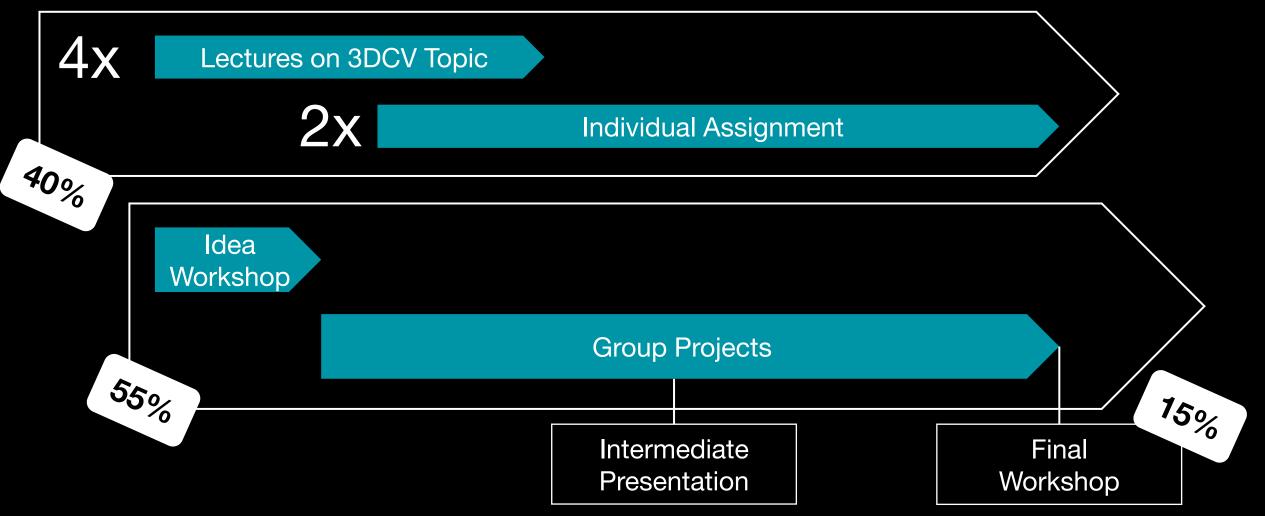
F3DCV / AT3DCV

Summer 2024



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Course Structure



F3DCV / AT3DCV – Concept

- 1. Theoretical + Practical Foundation
 - "Flipped Class-room"
 - Pre-recorded lectures: to study n your own pace
 - Interactive Tutor sessions: your chance for discussion and questions (on lectures and assignments)
 - Pass 2 (out of 4) assignments (mostly practical and some theoretical parts)
 - There will be different parts for F3DCV and AT3DCV

2. Group projects

Apply your 3DV and DL knowledge

- Very close tutoring
- "Researchy" projects
 - Projects are purposely not strictly defined
 - Be innovative and creative!
 - Final workshop: combination of scientific poster-session and start-up pitch
 - Present your working demo/code/application/results

Application

- 2 stage process:
 - Register in TUM Online https://matching.in.tum.de/
 - Submit questionnaire and upload CV + Transcript https://forms.gle/8ZJb2Dc1z22CjwVv5
- Deadline: 14th of February 2024

- Ca. 20 students will be selected (usually 100+ applications)
- Info on Course Websites

F3DCV:https://www.cs.cit.tum.de/camp/teaching/practical-courses/foundations-in-3d-computer-vision-ss-2024/AT3DCV:https://www.cs.cit.tum.de/camp/teaching/practical-courses/advanced-topics-in-3d-computer-vision-ss-2024/



Course Dates

Individual Phase

18.04. Introduction Session
Lecture Material
+ 4 Challenges are provided
25.04. Tutor Session

15.05. 23:59 CEST Hand in 2 of 4 Challenges

Group Phase

02.05. Group Project Introductions16.05. Project Planning Session (Idea Workshop)

23.05. Group Meeting Slot
06.06. Group Meeting Slot
13.06. Group Meeting Slot
20.06. Group Meeting Slot
27.06. Mid-Term Presentations
04.07. Group Meeting Slot
11.07. Group Meeting Slot
18.07. Additional (Group Meeting) Slot

XX.07. Final (external) Workshop, TranslaTUM

In Person / Virtual – Hybrid

- Mostly onsite in person
- Option to attend virtually via zoom (if necessary)
- Thursdays at 16:00 in <u>MI 03.13.010</u>





Group Projects



- Hybrid Groups of 3-4 students
 Paired F3DCV + AT3DCV teams
- Students will be matched taking their preferences into account
- Project direction can be steered by the ideas of the group
- Project proposals will be discussed in workshop session
- Projects either on real world problems OR open research questions

What we expect

- Interest in Computer Vision
- Independent and pro-active participation
- Actively asking for help [team members and tutors]
- Coding knowledge
- Team work towards achieving the group / project goals

Expectation:	►B
Reality:	∕►B

Questions

E-Mail us on

f3dcv@mailnavab.informatik.tu-muenchen.de at3dcv@mailnavab.informatik.tu-muenchen.de

Your F3DCV / AT3DCV Team:

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Web:

https://www.cs.cit.tum.de/camp/teaching/practical-courses/foundations-in-3d-computer-vision-ss-2024/ https://www.cs.cit.tum.de/camp/teaching/practical-courses/advanced-topics-in-3d-computer-vision-ss-2024/



